



# Intel® oneAPI Programming Guide

Intel Corporation

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# Introduction

# 1

Obtaining high compute performance on today's modern computer architectures requires code that is optimized, power efficient, and scalable. The demand for high performance continues to increase due to needs in AI, video analytics, data analytics, as well as in traditional high performance computing (HPC).

Modern workload diversity has resulted in a need for architectural diversity; no single architecture is best for every workload. A mix of scalar, vector, matrix, and spatial (SVMS) architectures deployed in CPU, GPU, AI, and FPGA [accelerators](#) is required to extract the needed performance.

Today, coding for CPUs and accelerators requires different languages, libraries, and tools. That means each hardware platform requires completely separate software investments and provides limited application code reusability across different target architectures.

The oneAPI programming model simplifies the programming of CPUs and accelerators using modern C++ features to express parallelism with an open source programming language called Data Parallel C++ (DPC++). The DPC++ language enables code reuse for the host (such as a CPU) and accelerators (such as a GPU) using a single source language, with execution and memory dependencies clearly communicated. Mapping within the DPC++ code can be used to transition the application to run on the hardware, or set of hardware, that best accelerates the workload. A host is available to simplify development and debugging of device code, even on platforms that do not have an accelerator available.

oneAPI also supports programming on CPUs and accelerators using the OpenMP\* offload feature with existing C/C++ or Fortran code.

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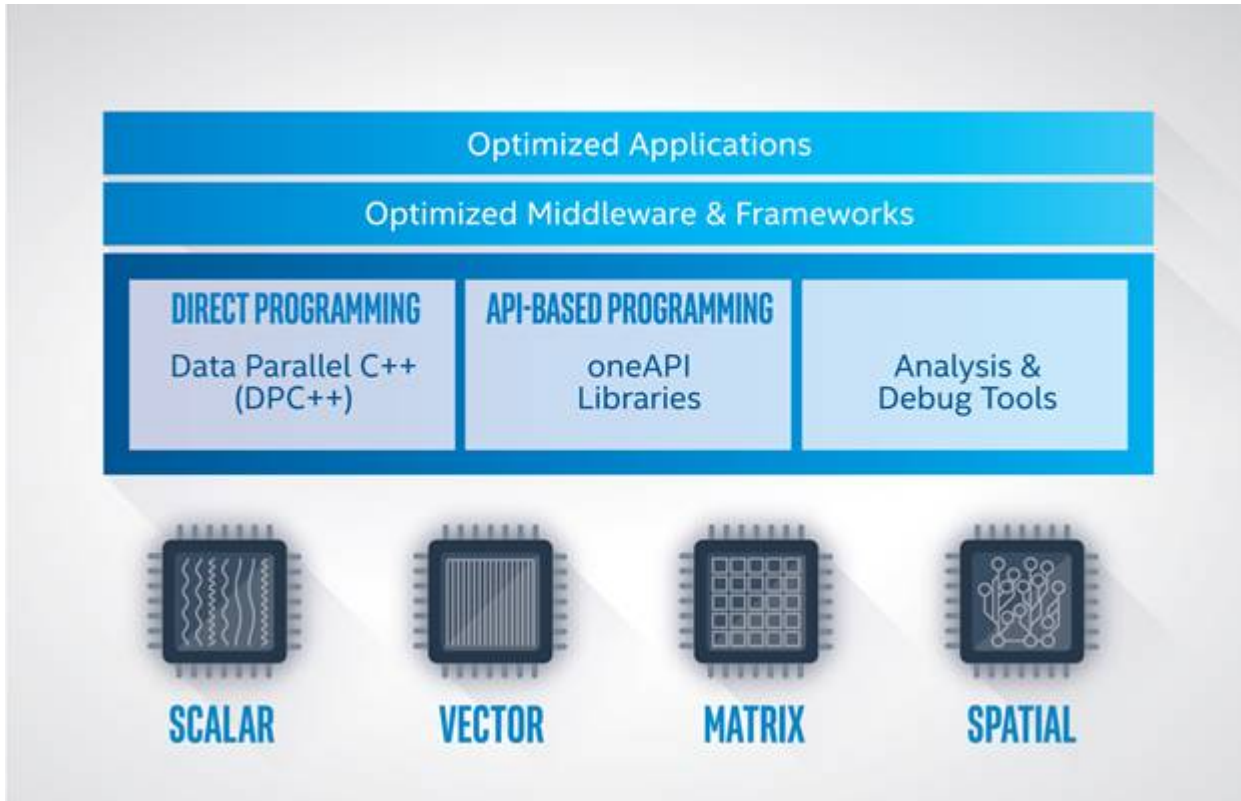
**NOTE** Not all programs can benefit from the single programming model offered by oneAPI. It is important to understand if your program can benefit and how to design, implement, and use the oneAPI programming model for your program.

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Learn more about the oneAPI initiative and programming model at [oneapi.com](https://oneapi.com). The site includes the oneAPI Specification, DPC++ Language Guide and API Reference, open source library documentation, and other resources.

## Intel oneAPI Programming Overview

The oneAPI programming model provides a comprehensive and unified portfolio of developer tools that can be used across hardware targets, including a range of performance libraries spanning several workload domains. The libraries include functions custom-coded for each target architecture, so the same function call delivers optimized performance across supported architectures. DPC++ is based on industry standards and open specifications to encourage ecosystem collaboration and innovation.



As shown in the figure above, applications that take advantage of the oneAPI programming model can execute on multiple target hardware platforms ranging from CPU to FPGA. Intel offers oneAPI products as part of a set of toolkits. The Intel® oneAPI Base Toolkit, Intel® oneAPI HPC Toolkit, Intel® oneAPI IoT Toolkit, and several other toolkits feature complementary tools based on specific developer workload needs. For example, the Intel oneAPI Base Toolkit includes the Intel® oneAPI DPC++/C++ Compiler, the Intel® DPC++ Compatibility Tool, select libraries, and analysis tools.

- Developers who want to migrate existing CUDA\* code to DPC++, can use the **Intel DPC++ Compatibility Tool** to help migrate their existing projects to DPC++.
- The **Intel oneAPI DPC++/C++ Compiler** supports direct programming of code targeting accelerators. Direct programming is coding for performance when APIs are not available for the algorithms expressed in user code. It supports online and offline compilation for CPU and GPU targets and offline compilation for FPGA targets.
- API-based programming is supported via sets of optimized libraries. The library functions provided in the oneAPI product are pre-tuned for use with any supported target architecture, eliminating the need for developer intervention. For example, the BLAS routine available from **Intel oneAPI Math Kernel Library** is just as optimized for a GPU target as a CPU target.
- Finally, the compiled DPC++ application can be analyzed and debugged to ensure performance, stability, and energy efficiency goals are achieved using tools such as **Intel® VTune™ Profiler** or **Intel® Advisor**.

The Intel oneAPI Base Toolkit is available as a free download from the [Intel Developer Zone](#).

Users familiar with Intel® Parallel Studio and Intel® System Studio may be interested in the [Intel oneAPI HPC Toolkit](#) and [Intel oneAPI IoT Toolkit](#) respectively.

## oneAPI Toolkit Distribution

oneAPI Toolkits are available via multiple distribution channels:

- Local product installation: install the oneAPI toolkits from the Intel® Developer Zone.
- Install from containers or repositories: install the oneAPI toolkits from one of several supported containers or repositories.

- Pre-installed in the Intel® DevCloud: use a free development sandbox for access to the latest Intel SVMS hardware and select oneAPI tools.

Learn more about each of these distribution channels from the [oneAPI product website](#) on the Intel Developer Zone.

## About This Guide

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This document provides:

- [oneAPI Programming Model](#): An introduction to the oneAPI programming model (platform, execution, memory, and kernel programming)
- [Compile and Run oneAPI Programs](#): Details about how to compile code for various accelerators (CPU, FPGA, etc.)
- [API-based Programming](#): A brief introduction to common APIs and related libraries
- [Software Development Process](#): An overview of the software development process using various oneAPI tools, such as debuggers and performance analyzers, and optimizing code for a specific accelerator (CPU, FPGA, etc.)

## Related Documentation

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The following documents are useful starting points for developers getting started with oneAPI projects.

- Get started guides for select oneAPI toolkits:
  - Get Started with Intel oneAPI Base Toolkit for [Linux\\*](#) | [Windows\\*](#) | [MacOS\\*](#)
  - Get Started with Intel oneAPI HPC Toolkit for [Linux](#) | [Windows](#) | [MacOS](#)
  - Get Started with Intel oneAPI IoT Toolkit for [Linux](#) | [Windows](#)
- Release notes for select oneAPI toolkits:
  - [Intel oneAPI Base Toolkit](#)
  - [Intel oneAPI HPC Toolkit](#)
  - [Intel oneAPI IoT Toolkit](#)
- Language reference material:
  - [DPC++ Language Guide and API Reference](#)
  - [SYCL\\* Specification](#) (for version 1.2.1)
  - [Data Parallel C++: Mastering DPC++ for Programming of Heterogeneous Systems using C++ and SYCL](#) (book)
  - [LLVM/OpenMP\\* Documentation](#)
  - [OpenMP\\* Specifications](#) (examples documents recommended)

# oneAPI Programming Model

In heterogenous computing, the [host](#) processor takes advantage of accelerator [devices](#) to execute code more efficiently.

The oneAPI programming model supports two methods of heterogenous computing: Data Parallel C++ (DPC++) and OpenMP\* for C, C++, and Fortran.

DPC++ is an open source language based on modern C++ and the SYCL\* language from the Khronos\* Group with some additional Intel extensions. The Intel® oneAPI DPC++/C++ Compiler is available as part of the Intel oneAPI Base Toolkit.

OpenMP has been a standard programming language for over 20 years, and Intel implements version 5.0 of the OpenMP standard. The Intel oneAPI DPC++/C++ Compiler with OpenMP offload support is available as part of the Intel oneAPI Base Toolkit, Intel oneAPI HPC Toolkit, and Intel oneAPI IoT Toolkit. The Intel® Fortran Compiler Classic and Intel® Fortran Compiler (Beta) with OpenMP offload support is available as part of the Intel oneAPI HPC Toolkit.

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**NOTE**

OpenMP is not supported for FPGA devices.

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The next sections briefly describe each language and provide pointers to more information.

## Data Parallel C++ (DPC++)

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Data Parallel C++ (DPC++) is a high-level language designed for data parallel programming productivity.

### Simple DPC++ Sample Code

The best way to introduce DPC++ is through an example. Since DPC++ is based on modern C++, this example uses several features that have been added to C++ in recent years, such as lambda functions and uniform initialization. Even if developers are not familiar with these features, their semantics will become clear from the context of the example. After gaining some experience with DPC++, these newer C++ features will become second nature.

The following application sets each element of an array to the value of its index, so that  $a[0] = 0$ ,  $a[1] = 1$ , etc.

```
#include <CL/sycl.hpp>
#include <iostream>

constexpr int num=16;
using namespace sycl;

int main() {
    auto r = range{num};
    buffer<int> a{r};

    queue{}.submit([&](handler& h) {
        accessor out{a, h};
        h.parallel_for(r, [=](item<1> idx) {
            out[idx] = idx;
        });
    });
};
```



```
host_accessor result{a};
for (int i=0; i<num; ++i)
    std::cout << result[i] << "\n";
}
```

The first thing to notice is that there is just one source file: both the host code and the offloaded accelerator code are combined in a [single source](#) file. The second thing to notice is that the syntax is standard C++: there aren't any new keywords or pragmas used to express the parallelism. Instead, the parallelism is expressed through C++ classes. For example, the `buffer` class on line 8 represents data that will be offloaded to the device, and the `queue` class on line 11 represents a connection from the host to the accelerator.

The logic of the example works as follows. Lines 8 and 9 create a buffer of 16 `int` elements, which have no initial value. This buffer acts like an array. Line 11 constructs a `queue`, which is a connection to an accelerator device. This simple example asks DPC++ to choose a default accelerator device, but a more robust application would probably examine the topology of the system and choose a particular accelerator. Once the queue is created, the example calls the `submit()` member function to submit work to the accelerator. The parameter to this `submit()` function is a lambda function, which executes immediately on the host. The lambda function does two things. First, it creates an `accessor` on line 12, which can writing elements in the buffer. Second, it calls the `parallel_for()` function on line 13 to execute code on the accelerator.

The call to `parallel_for()` takes two parameters. One parameter is a lambda function, and the other is the `range` object "r" that represents the number of elements in the buffer. DPC++ arranges for this lambda to be called on the accelerator once for each index in that range, i.e. once for each element of the buffer. The lambda simply assigns a value to the buffer element by using the `out` accessor that was created on line 12. In this simple example, there are no dependencies between the invocations of the lambda, so DPC++ is free to execute them in parallel in whatever way is most efficient for this accelerator.

After calling `parallel_for()`, the host part of the code continues running without waiting for the work to complete on the accelerator. However, the next thing the host does is to create a `host_accessor` on line 18, which reads the elements of the buffer. DPC++ knows this buffer is written by the accelerator, so the `host_accessor` constructor (line 18) blocks until the work submitted by the `parallel_for()` is complete. Once the accelerator work completes, the host code continues past line 18, and it uses the `out` accessor to read values from the buffer.

## Additional DPC++ Resources

This introduction to DPC++ is not meant to be a complete tutorial. Rather, it just gives you a flavor of the language. There are many more features to learn, including features that allow you to take advantage of common accelerator hardware such as local memory, barriers, and SIMD. There are also features that let you submit work to many accelerator devices at once, allowing a single application to run work in parallel on many devices simultaneously.

The following resources are useful to learning and mastering DPC++:

- [Simplify Coding Across Architectures with DPC++](#) is a 2:45 minute overview video about the benefits of DPC++.
- [Explore DPC++ with Samples from Intel](#) provides an overview and links to simple sample applications available from GitHub\*.
- The [DPC++ Foundations Code Sample Walk-Through](#) is a detailed examination of the Vector Add sample code, the DPC++ equivalent to a basic Hello World application.
- The [oneapi.com](#) site includes a [DPC++ Language Guide and API Reference](#) with descriptions of classes and their interfaces. It also provides details on the four programming models of DPC++ and SYCL - platform model, execution model, memory model, and kernel programming model.
- The [DPC++ Essentials training course](#) is a guided learning path using Jupyter\* Notebooks on Intel® DevCloud.

- [Data Parallel C++: Mastering DPC++ for Programming of Heterogeneous Systems using C++ and SYCL](#) is a comprehensive book that introduces and explains key programming concepts and language details about DPC++.

## C/C++ or Fortran with OpenMP\* Offload Programming Model

The Intel® oneAPI DPC++/C++ Compiler and the Intel® Fortran Compiler (Beta) enable software developers to use OpenMP\* directives to offload work to Intel accelerators to improve the performance of applications.

This section describes the use of OpenMP directives to target computations to the accelerator. Developers unfamiliar with OpenMP directives can find basic usage information documented in the OpenMP Support sections of the [Intel® oneAPI DPC++/C++ Compiler Developer Guide and Reference](#) or [Intel® Fortran Compiler for oneAPI Developer Guide and Reference](#).

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### NOTE

OpenMP is not supported for FPGA devices.

---

### Basic OpenMP Target Construct

The OpenMP target construct is used to transfer control from the host to the target device. Variables are mapped between the host and the target device. The host thread waits until the offloaded computations are complete. Other OpenMP tasks may be used for asynchronous execution on the host; use the `nowait` clause to specify that the encountering thread does not wait for the target region to complete.

#### C/C++

The C++ code snippet below targets a SAXPY computation to the accelerator.

```
#pragma omp target map(tofrom:fa), map(to:fb,a)
#pragma omp parallel for firstprivate(a)
for(k=0; k<FLOPS_ARRAY_SIZE; k++)
    fa[k] = a * fa[k] + fb[k]
```

Array `fa` is mapped both to and from the accelerator since `fa` is both input to and output from the calculation. Array `fb` and the variable `a` are required as input to the calculation and are not modified, so there is no need to copy them out. The variable `FLOPS_ARRAY_SIZE` is implicitly mapped to the accelerator. The loop index `k` is implicitly private according to the OpenMP specification.

#### Fortran

This Fortran code snippet targets a matrix multiply to the accelerator.

```
!$omp target map(to: a, b ) map(tofrom: c )
!$omp parallel do private(j,i,k)
    do j=1,n
        do i=1,n
            do k=1,n
                c(i,j) = c(i,j) + a(i,k) * b(k,j)
            enddo
        enddo
    enddo
!$omp end parallel do
!$omp end target
```

Arrays `a` and `b` are mapped to the accelerator, while array `c` is both input to and output from the accelerator. The variable `n` is implicitly mapped to the accelerator. The private clause is optional since loop indices are automatically private according to the OpenMP specification.

## Map Variables

To optimize data sharing between the host and the accelerator, the target data directive maps variables to the accelerator and the variables remain in the target data region for the extent of that region. This feature is useful when mapping variables across multiple target regions.

### C/C++

```
#pragma omp target data [clause[[],] clause],...
structured-block
```

### Fortran

```
!$omp target data [clause[[],] clause],...
structured-block
!$omp end target data
```

### Clauses

The clauses can be one or more of the following. See [TARGET DATA](#) for more information.

- DEVICE (integer-expression)
- IF ([TARGET DATA:] scalar-logical-expression)
- IS\_DEVICE\_PTR (list)
- MAP ([[map-type-modifier[,]] map-type: ] list)

---

**NOTE** Map type can be one or more of the following:

---

- alloc
- to
- from
- tofrom
- delete
- release
- SUBDEVICE ([integer-constant ,] integer-expression [ : integer-expression [ : integer-expression]])
- USE\_DEVICE\_ADDR (list) // available only in ifx
- USE\_DEVICE\_PTR (ptr-list)

```
DEVICE (integer-expression)
IF ([TARGET DATA:] scalar-logical-expression)
IS_DEVICE_PTR (list)
MAP ([[map-type-modifier[,]] map-type: alloc | to | from | tofrom | delete | release] list)
SUBDEVICE ([integer-constant ,] integer-expression [ : integer-expression [ : integer-
expression]])
USE_DEVICE_ADDR (list) // available only in ifx
USE_DEVICE_PTR (ptr-list)
```

Use the target update directive to synchronize an original variable in the host with the corresponding variable in the device.

## Compile to Use OMP TARGET

The following example commands illustrate how to compile an application using OpenMP target.

### C/C++

- Linux:

```
icx -fopenmp -fopenmp-targets=spir64 code.c
```

- Windows (you can use `icx` or `icpx`):

```
icx /Qopenmp /Qopenmp-targets=spir64 code.c
```

#### Fortran

- Linux:

```
ifx -fopenmp -fopenmp-targets=spir64 code.f90
```

- Windows:

```
ifx /Qopenmp /Qopenmp-targets=spir64 code.f90
```

### Additional OpenMP Offload Resources

- Intel offers code samples that demonstrate using OpenMP directives to target accelerators at <https://github.com/oneapi-src/oneAPI-samples/tree/master/DirectProgramming>. Specific samples include:
  - [Matrix Multiplication](#) is a simple program that multiplies together two large matrices and verifies the results. This program is implemented using two ways: DPC++ or OpenMP.
  - The [ISO3DFD](#) sample refers to Three-Dimensional Finite-Difference Wave Propagation in Isotropic Media. The sample is a three-dimensional stencil used to simulate a wave propagating in a 3D isotropic medium. The sample shows some of the more common challenges and techniques when targeting OMP accelerator devices in more complex applications to achieve good performance.
  - [openmp\\_reduction](#) is a simple program that calculates pi. This program is implemented using C++ and OpenMP for CPUs and accelerators based on Intel® Architecture.
- [Get Started with OpenMP\\* Offload Feature](#) provides details on using Intel's compilers with OpenMP offload, including lists of supported options and example code.
- [LLVM/OpenMP Runtimes](#) describes the distinct types of runtimes available and can be helpful when debugging OpenMP offload.
- openmp.org has an examples document: <https://www.openmp.org/wp-content/uploads/openmp-examples-4.5.0.pdf>. Chapter 4 of the examples document focuses on accelerator devices and the target construct.
- *Using OpenMP - the Next Step* is a good OpenMP reference book. Chapter 6 covers OpenMP support for heterogeneous systems. For additional information on this book, see <https://www.openmp.org/tech/using-openmp-next-step>.

## Device Selection

---

Offloading code to a [device](#) (such as a CPU, GPU, or FPGA) is available for both DPC++ and OpenMP\* applications.

### DPC++ Device Selection in the Host Code

Host code can explicitly select a device type. To do this, select a queue and initialize its device with one of the following:

- `default_selector`
- `cpu_selector`
- `gpu_selector`
- `accelerator_selector`

If `default_selector` is used, the kernel runs based on a heuristic that chooses from available compute devices (all, or a subset based on the value of the `SYCL_DEVICE_FILTER` environment variable).

If a specific device type (such as `cpu_selector` or `gpu_selector`) is used, then it is expected that the specified device type is available in the platform or included in the filter specified by `SYCL_DEVICE_FILTER`. If such a device is not available, then the runtime system throws an exception indicating that the requested device is not available. This error can be thrown in the situation where an ahead-of-time (AOT) compiled binary is run in a platform that does not contain the specified device type.

#### NOTE

While DPC++ applications can run on any supported target hardware, tuning is required to derive the best performance advantage on a given target architecture. For example, code tuned for a CPU likely will not run as fast on a GPU accelerator without modification.

`SYCL_DEVICE_FILTER` is a complex environment variable that allows you to limit the runtimes, compute device types, and compute device IDs that may be used by the DPC++ runtime to a subset of all available combinations. The compute device IDs correspond to those returned by the SYCL API, `clinfo`, or `sycl-ls` (with the numbering starting at 0). They have no relation to whether the device with that ID is of a certain type or supports a specific runtime. Using a programmatic special selector (like `gpu_selector`) to request a filtered out device will cause an exception to be thrown. Refer to the environment variable description in GitHub for details on use and example values: <https://github.com/intel/llvm/blob/sycl/sycl/doc/EnvironmentVariables.md>.

Additional information about device selection is available from the [DPC++ Language Guide and API Reference](#).

### OpenMP\* Device Query and Selection in the Host Code

OpenMP provided a set of APIs for programmers to query and set device for running code on the device. Host code can explicitly select and set a device num. For each offloading region, a programmer can also use a **device** clause to specify the target device that is to be used for executing the offloading region.

- `int omp_get_num_procs (void)` routine returns the number of processors available to the device
- `void omp_set_default_device(int device_num)` routine controls the default target device
- `int omp_get_default_device(void)` routine returns the default target device
- `int omp_get_num_devices(void)` routine returns the number of non-host devices available for offloading code or data.
- `int omp_get_device_num(void)` routine returns the device number of the device on which the calling thread is executing.
- `int omp_is_initial_device(int device_num)` routine returns *true* if the current task is executing on the host device; otherwise, it returns *false*.
- `int omp_get_initial_device(void)` routine returns a device number that represents the host device.

A programmer can use the environment variable `LIBOMPTARGET_DEVICE_TYPE = [ CPU | GPU ]` to perform a device type selection. If a specific device type such as CPU or GPU is specified, then it is expected that the specified device type is available in the platform. If such a device is not available, then the runtime system throws an error that the requested device type is not available if the environment variable `OMP_TARGET_OFFLOAD=mandatory`, otherwise, the execution will have a fallback execution on its initial device. Additional information about device selection is available from the OpenMP 5.1 specification. Details about environment variables are available from GitHub: <https://github.com/intel/llvm/blob/sycl/sycl/doc/EnvironmentVariables.md>.

#### See Also

[Device Selectors for FPGA](#)

# oneAPI Development Environment Setup

# 3

The Intel® oneAPI tools are available in several convenient forms, as detailed in [oneAPI Toolkit Distribution](#) earlier in this guide. Follow the instructions in the [Intel oneAPI Toolkit Installation Guide](#) to obtain and install the tools.

## Install Directories

On a Windows\* system, the Intel oneAPI development tools are typically installed in the `C:\Program Files (x86)\Intel\oneAPI\` directory.

On Linux\* or macOS\* system, the Intel oneAPI development tools are typically installed in the `/opt/intel/oneapi/` directory.

These are the default locations; the precise location can be changed during installation.

Within the oneAPI installation directory are a collection of folders that contain the compilers, libraries, analyzers, and other tools installed on the development system. The precise list depends on the toolkit(s) installed and the options selected during installation. Most of the folders within the oneAPI installation directory have obvious names. For example, the `mk1` folder contains the Intel® oneAPI Math Kernel Library (Intel® oneMKL), the `ipp` folder contains the Intel® Integrated Performance Primitives (Intel® IPP) library, and so on.

## Environment Variables

Some of the tools in the Intel oneAPI toolkits depend on environment variables to:

- Assist the compilation and link process (e.g., `PATH`, `CPATH`, `INCLUDE`, etc.)
- Locate debuggers, analyzers, and local help files (e.g., `PATH`, `MANPATH`)
- Identify tool-specific parameters and dynamic (shared) link libraries (e.g., `LD_LIBRARY_PATH`, `CONDA_*`, etc.)

## setvars and vars Files

Every installation of the Intel oneAPI toolkits includes a single top-level "setvars" script and multiple tool-specific "vars" scripts (`setvars.sh` and `vars.sh` on Linux and macOS; `setvars.bat` and `vars.bat` on Windows). When executed (sourced), these scripts configure the local environment variables to reflect the needs of the installed Intel oneAPI development tools.

The following sections provide detailed instructions on how to use the oneAPI setvars and vars scripts to initialize the oneAPI development environment:

- [Use the setvars Script with Windows\\*](#)
- [Use the setvars Script with Linux\\* or MacOS\\*](#)

## Modulefiles (Linux only)

Users of [Environment Modules](#) might prefer to use the modulefiles included with the oneAPI toolkit installation to initialize the development environment variables. The oneAPI modulefiles are only supported on Linux and are provided as an alternative to using the setvars and vars scripts described above. In general, users should not mix the usage of modulefiles with the setvars environment scripts.

See [Use Modulefiles with Linux\\*](#) for detailed instructions on how to use the oneAPI modulefiles to initialize the oneAPI development environment.

## Use the setvars Script with Windows\*

Most of the component tool folders contain an environment script named `vars.bat` that configures the environment variables needed by that component to support oneAPI development work. For example, in a default installation, the `ipp` vars script on Windows is located at: `C:\Program Files (x86)\Intel\oneAPI\ipp\latest\env\vars.bat`. This pattern is shared by all oneAPI components that include an environment vars script.

These component tool vars scripts can be called directly or collectively. To call them collectively, a script named `setvars.bat` is provided in the oneAPI installation folder. For example, in a default installation on a Windows machine: `C:\Program Files (x86)\Intel\oneAPI\setvars.bat`.

Running the `setvars.bat` script without any arguments causes it to locate and run all of the `<component>\latest\env\vars.bat` scripts installed on the system. Changes made to the environment using the Windows `set` command can be seen after running these scripts.

Visual Studio Code\* developers can install an extension to have `setvars.bat` run automatically. Learn more in [Using Visual Studio Code with Intel oneAPI Toolkits](#).

---

**NOTE**

Changes to your environment made by running the `setvars.bat` script (or the individual `vars.bat` scripts) are not permanent. Those changes only apply to the `cmd.exe` session in which the `setvars.bat` environment script was executed.

---

### Command Line Arguments

The `setvars.bat` script supports several command-line arguments, which is displayed using the `--help` option. For example:

```
"C:\Program Files (x86)\Intel\oneAPI\setvars.bat" --help
```

Important arguments include the `--config=file` argument and the ability to include additional arguments that will be passed to the `vars.bat` scripts that are called by the `setvars.bat` script.

The `--config=file` argument provides the ability to limit environment initialization to a specific set of oneAPI components, as well as providing a way to initialize the environment for a specific component version. For example, to limit environment setup just the Intel® Integrated Performance Primitives (Intel® IPP) library and the Intel® oneAPI Math Kernel Library (oneMKL), create a config file that tells the `setvars.bat` script to only configure the environment variables for those two oneAPI components. More details and examples are provided in [Use a Config file for setvars.bat on Windows](#).

Any extra arguments passed on the `setvars.bat` command line that are not described in the `setvars.bat` help message will be passed to every called `vars.bat` script. That is, if the `setvars.bat` script does not recognize an argument, it assumes the argument is meant for use by one or more component vars scripts and passes those extra arguments to every component `vars.bat` script that it calls. The most common extra arguments are the `ia32` and `intel64` arguments, which are used by the Intel compilers and the Intel IPP and oneMKL libraries to indicate the application target architecture.

If both Microsoft Visual Studio\* 2017 and Visual Studio 2019 are installed on your system, you can specify which of these two Visual Studio environments should be initialized as part of the oneAPI environment initialization by adding either the `vs2017` or the `vs2019` argument to the `setvars.bat` command line. By default, the most recent version of Visual Studio is located and initialized.

Inspect the individual `vars.bat` scripts to determine which, if any, command line arguments they accept.

## How to Run

```
<install-dir>\setvars.bat
```

## How to Verify

After executing `setvars.bat`, verify success by searching for the `SETVARS_COMPLETED` environment variables. If `setvars.bat` was successful, `SETVARS_COMPLETED` will have a value of 1:

```
set | find "SETVARS_COMPLETED"
```

Return value

```
SETVARS_COMPLETED=1
```

If the return value is anything other than `SETVARS_COMPLETED=1`, then the test failed and `setvars.bat` did not complete properly.

## Multiple Runs

Because many of the individual `env\vars.bat` scripts make significant changes to `PATH`, `CPATH`, and other environment variables, the top-level `setvars.bat` script will not allow multiple invocations of itself in the same session. This is done to ensure that your environment variables do not become too long due to redundant path references, especially the `%PATH%` environment variable.

This can be overridden by passing `setvars.bat` a `--force` flag. In this example, the user tries to run `setvars.bat` twice. The second instance is stopped because `setvars.bat` has already been run.

```
> <install-dir>\setvars.bat
:: initializing environment ...
(SNIP: lot of output)
:: oneAPI environment initialized ::

> <install-dir>\setvars.bat
:: WARNING: setvars.bat has already been run. Skipping re-execution.
  To force a re-execution of setvars.bat, use the '--force' option.
  Using '--force' can result in excessive use of your environment variables.
```

In the third instance, the user runs `<install-dir>\setvars.bat --force` and the initialization is successful.

```
> <install-dir>\setvars.bat --force
:: initializing environment ...
(SNIP: lot of output)
:: oneAPI environment initialized ::
```

## ONEAPI\_ROOT Environment Variable

The `ONEAPI_ROOT` variable is set by the top-level `setvars.bat` script when that script is sourced. If there is already a `ONEAPI_ROOT` environment variable defined, `setvars.bat` overwrites it. This variable is primarily used by the `oneapi-cli` sample browser and the Microsoft Visual Studio and Visual Studio Code\* sample browsers to help them locate oneAPI tools and components, especially for locating the `setvars.bat` script if the `SETVARS_CONFIG` feature has been enabled. For more information on the `SETVARS_CONFIG` feature, see [Automate the setvars.bat Script with Microsoft Visual Studio\\*](#).

On Windows systems, the installer adds the `ONEAPI_ROOT` variable to the environment and no additional user action is required.



## Use a Config file for `setvars.bat` on Windows

The `setvars.bat` script sets environment variables for use with the oneAPI toolkits by executing each of the `<install-dir>\latest\env\vars.bat` scripts found in the respective oneAPI folders. Unless you configure your Windows system to run the `setvars.bat` script automatically, it must be executed every time a new terminal window is opened for command line development, or prior to launching Visual Studio Code, Sublime Text, or any other C/C++ editor you use. For more information, see [Configure Your System](#).

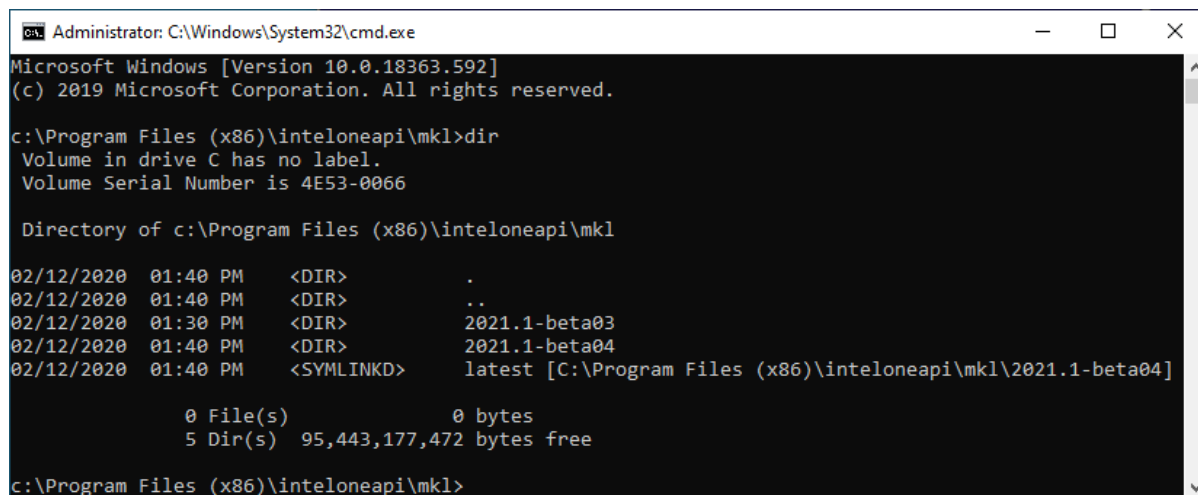
The procedure below describes how to use a configuration file to manage environment variables.

## Versions and Configurations

Some oneAPI tools support installation of multiple versions. For those tools that do support multiple versions, the directory is organized like this:

```
[Component] directory
- [1.0] version directory
- [1.1] version directory
- [1.2] version directory
- [latest -> 1.2] symlink or shortcut
```

For example:



```
Administrator: C:\Windows\System32\cmd.exe
Microsoft Windows [Version 10.0.18363.592]
(c) 2019 Microsoft Corporation. All rights reserved.

c:\Program Files (x86)\inteloneapi\mkl>dir
Volume in drive C has no label.
Volume Serial Number is 4E53-0066

Directory of c:\Program Files (x86)\inteloneapi\mkl

02/12/2020  01:40 PM    <DIR>          .
02/12/2020  01:40 PM    <DIR>          ..
02/12/2020  01:30 PM    <DIR>          2021.1-beta03
02/12/2020  01:40 PM    <DIR>          2021.1-beta04
02/12/2020  01:40 PM    <SYMLINKD>     latest [C:\Program Files (x86)\inteloneapi\mkl\2021.1-beta04]

               0 File(s)                0 bytes
               5 Dir(s)  95,443,177,472 bytes free

c:\Program Files (x86)\inteloneapi\mkl>
```

For all tools, there is a symbolic link named `latest` that points to the latest installed version of that component; and the `vars.bat` script located in the `latest\env\` folder is what the `setvars.bat` executes by default.

If required, `setvars.bat` can be customized to point to a specific directory by using a configuration file.

## --config Parameter

The top level `setvars.bat` script accepts a `--config` parameter that identifies your custom **config.txt** file.

```
<install-dir>\setvars.bat --config="path\to\your\config.txt"
```

The name of your configuration file can have any name you choose. You can create many config files to setup a variety of development or test environments. For example, you might want to test the latest version of a library with an older version of a compiler; use a `setvars` config file to manage such a setup.

## Config File Sample

The examples below show a simple example of the config file:

### Load Latest of Everything but...

```
mkl=1.1  
dldt=exclude
```

### Exclude Everything but...

```
default=exclude  
mkl=1.0  
ipp=latest
```

The configuration text file must follow these requirements:

- a newline delimited text file
- each line consists of a single "key=value" pair
- "key" names a component folder in the top-level set of oneAPI directories (the folders found in the %ONEAPI\_ROOT% directory). If a "key" appears more than once in a config file, the last "key" wins and any prior keys with the same name are ignored.
- "value" names a version directory that is found at the top-level of the component directory. This includes any symbolic links (such as latest) that might be present at that level in the component directory.
  - OR "value" can be "exclude", which means the named key will NOT have its vars.bat script executed by the setvars.bat script.

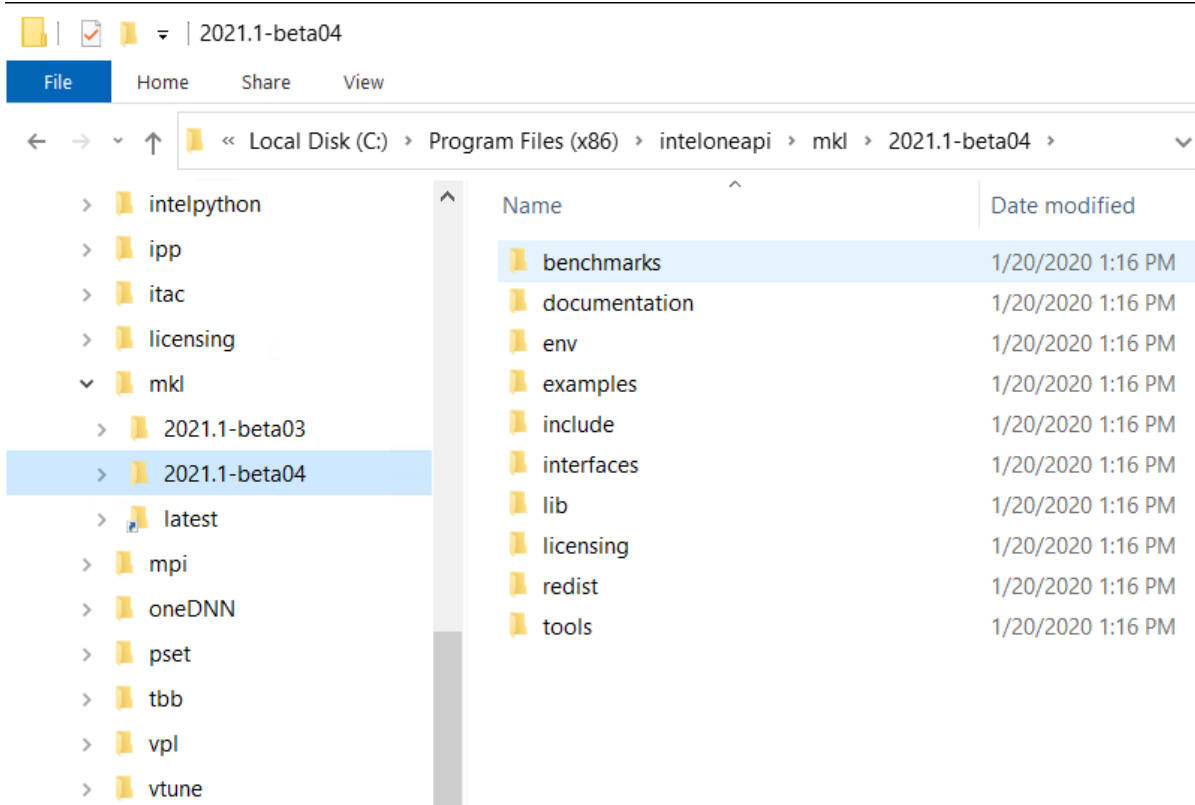
The "key=value" pair "default=exclude" is a special case. When included, it will exclude executing ALL env\vars.bat scripts, except those that are listed in the config file. See the examples below.

### Further Customization of Config Files

The config file can be used to exclude specific components, include specific component versions or only include specific component versions that are named after a "default=exclude" statement.

By default, setvars.bat will process the latest version of each env\vars.bat script.

To explain this further, the sample below shows two versions of oneMKL installed: 2021.1-beta03 and 2021.1-beta04. There is a shortcut to 2021-beta04 indicating that it is the latest version, so by default setvars.bat will execute the 2021.1-beta04 vars.bat script in the mkl folder.



### Specify a Specific Version

To direct `setvars.bat` to execute the `<install-dir>\mkl\2021.1-beta03\env\vars.bat` script, add `mkl=2021.1-beta03` to your config file.

This instructs `setvars.bat` to execute the `env\vars.bat` script located in the `2021.1-beta03` version folder inside the `mkl` directory. For other installed components, `setvars.bat` will execute the `env\vars.bat` script located in the latest version folder.

### Exclude Specific Components

To exclude a component, use the following syntax:

```
<key>=exclude
```

For example, to exclude Intel IPP, but include the 2021.1-beta03 version of oneMKL:

```
mkl=2021.1-beta03
ipp=exclude
```

In this example:

- `setvars.bat` WILL execute the oneMKL 2021.1-beta03 `env\vars.bat` script
- `setvars.bat` WILL NOT execute Intel IPP `env\vars.bat` script files
- `setvars.bat` WILL execute the latest version of the remaining `env\vars.bat` script files

### Include Specific Components

To execute a specific list of component `env\vars.bat` scripts, you must first exclude all `env\vars.bat` scripts. Then add back the list of components to be executed by `setvars.bat`. Use the following syntax to exclude all component `env\vars.bat` scripts from being executed:

```
default=exclude
```

For example, to have `setvars.bat` execute only the oneMKL and Intel IPP component `env\vars.bat` scripts, use this config file:

```
default=exclude
mkl=2021.1-beta03
ipp=latest
```

In this example:

- `setvars.bat` WILL execute the oneMKL 2021.1-beta03 `env\vars.bat` script
- `setvars.bat` WILL execute the latest version of the Intel IPP `env\vars.bat` script
- `setvars.bat` WILL NOT execute the `env\vars.bat` script for any other components

## Automate the `setvars.bat` Script with Microsoft Visual Studio\*

The `setvars.bat` script sets up the environment variables needed to use the oneAPI toolkits. This script must be run every time a new terminal window is opened for command-line development. The `setvars.bat` script can also be run automatically when Microsoft Visual Studio is started. You can configure this feature to instruct the `setvars.bat` script to set up a specific set of oneAPI tools by using the `SETVARS_CONFIG` environment variable.

### SETVARS\_CONFIG Environment Variable States

The `SETVARS_CONFIG` environment variable enables automatic configuration of the oneAPI development environment when you start your instance of Microsoft Visual Studio. The variable has three conditions or states:

- Undefined (the `SETVARS_CONFIG` environment variable does not exist)
- Defined but empty (the value contains nothing or only whitespace)
- Defined and points to a `setvars.bat` configuration file

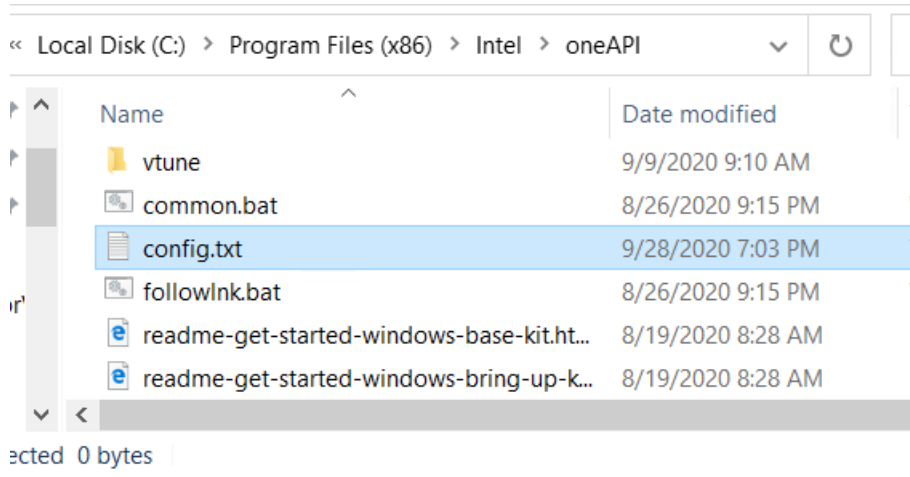
If `SETVARS_CONFIG` is undefined there will be no attempt to automatically run `setvars.bat` when Visual Studio is started. This is the default case, since the `SETVARS_CONFIG` variable is not defined by the oneAPI installer.

If `SETVARS_CONFIG` is defined and has no value (or contains only whitespace), the `setvars.bat` script will be automatically run when Visual Studio is started. In this case, the `setvars.bat` script initializes the environment for *all* oneAPI tools that are installed on your system. For more information about running the `setvars.bat` script, see [Build and Run a Sample Project Using the Visual Studio\\* Command Line](#).

When `SETVARS_CONFIG` is defined with the absolute pathname to a `setvars` configuration file, the `setvars.bat` script will be automatically run when Visual Studio is started. In this case, the `setvars.bat` script initializes the environment for only those oneAPI tools that are defined in the `setvars` configuration file. For more information about how to create a `setvars` config file, see [Using a Config File with `setvars.bat`](#).

### Create a `setvars` Configuration File

Create a new text file that you will use as your `setvars` configuration file. In this example, the file is named `config.txt` and is located in the `C:\Program Files (x86)\Intel\oneAPI` folder.

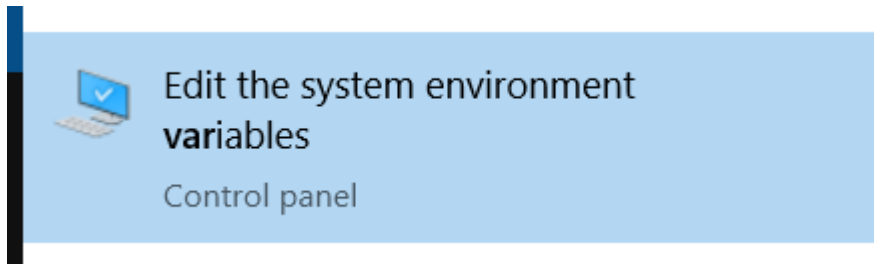


A `setvars` configuration file can have any name and can be saved to any location on your hard disk, as long as that location and the file are accessible and readable by Visual Studio. (A plug-in that was added to Visual Studio when you installed the oneAPI tools on your Windows system performs the `SETVARS_CONFIG` actions; that is why Visual Studio must have access to the location and contents of the `setvars` configuration file.)

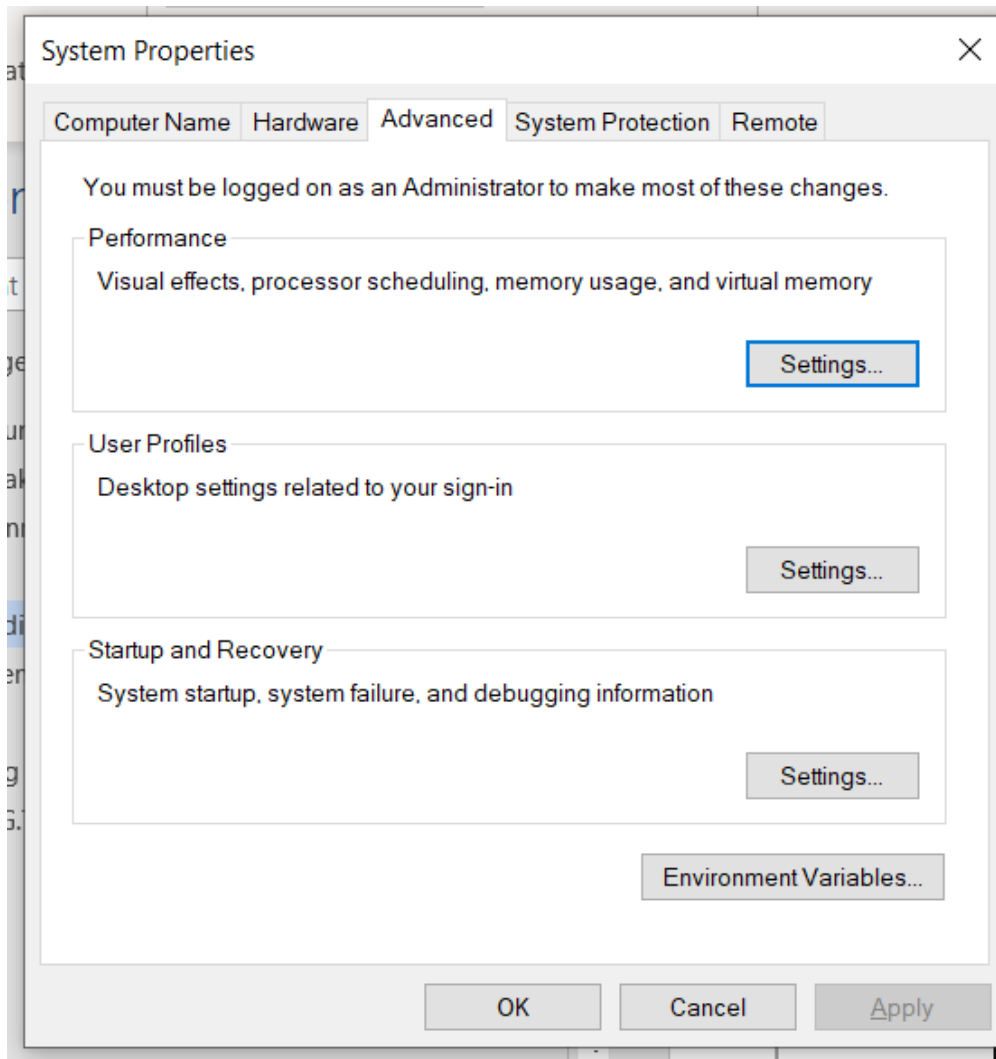
If you leave the `setvars` config file empty, the `setvars.bat` script will initialize your environment for *all* oneAPI tools that are installed on your system. This is equivalent to defining the `SETVARS_CONFIG` variable with an empty string. See [Using a Config File with `setvars.bat`](#) for details regarding what to put inside of your `setvars` config file.

### Define the `SETVARS_CONFIG` Environment Variable

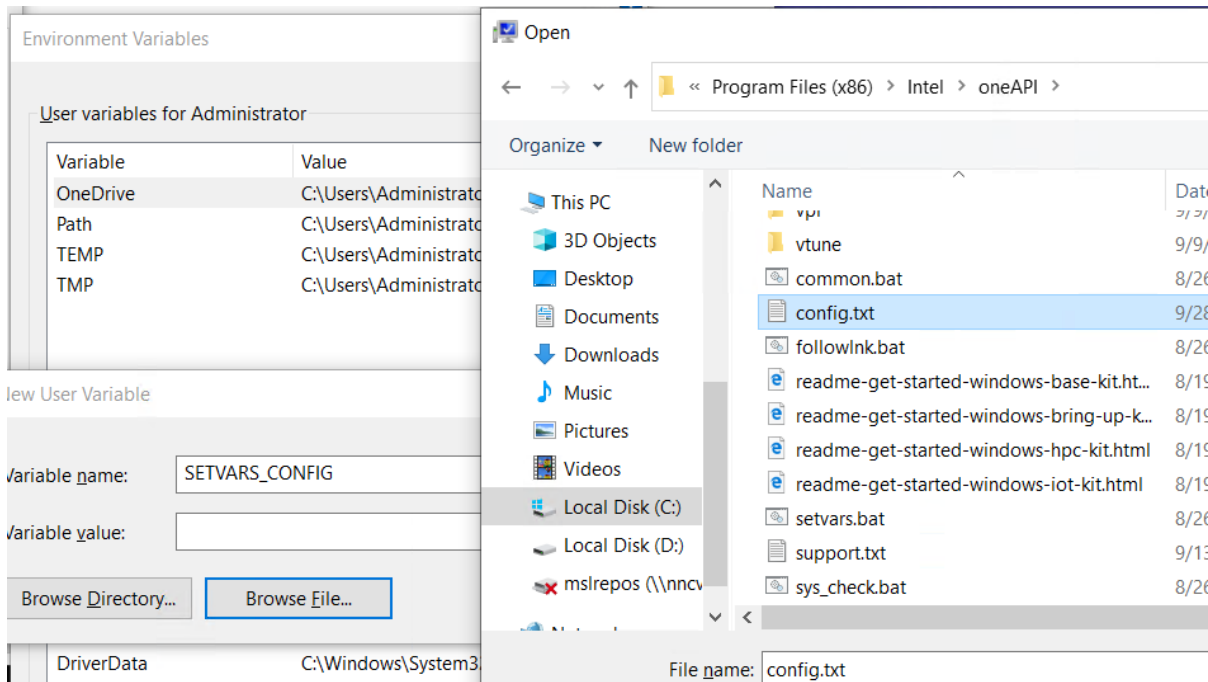
1. Press the Windows key on your keyboard, and then press the letter 's' to open the search window.
2. Enter variable in the search window.
3. Select **Edit the System Environment Variables**.



4. Click the **Environment Variables** button.



5. From the **User Variables** list, select `SETVARS_CONFIG`. Then click **Edit**.  
If `SETVARS_CONFIG` does not appear in your **User Variables** list, click **New**.
6. In the **Variable Name** field, enter `SETVARS_CONFIG`.
7. Click **Browse File**. Locate and click on the text file that you created.



8. Click **Open**.
9. Click **OK** to close the **User Variable** window.
10. Click **OK** to close the **Environment Variables** window.
11. Click **OK** to close the **System Properties** window.

## Use the setvars Script with Linux\* or MacOS\*

Most of the component tool folders contain an environment script named `vars.sh` that configures the environment variables needed by that component to support oneAPI development work. For example, in a default installation, the `ipp` vars script on Linux or macOS is located at: `/opt/intel/ipp/latest/env/vars.sh`. This pattern is shared by all oneAPI components that include an environment `vars` script.

These component tool `vars` scripts can be called directly or collectively. To call them collectively, a script named `setvars.sh` is provided in the oneAPI installation folder. For example, in a default installation on a Linux or macOS machine: `/opt/intel/setvars.sh`.

Sourcing the `setvars.sh` script without any arguments causes it to locate and source all of the `<component>/latest/env/vars.sh` scripts installed on the system. Changes made to the environment using the `env` command can be seen after sourcing these scripts.

### NOTE

Changes to your environment made by sourcing the `setvars.sh` script (or the individual `vars.sh` scripts) are not permanent. Those changes only apply to the terminal session in which the `setvars.sh` environment script was sourced.

## Command Line Arguments

The `setvars.sh` script supports several command-line arguments, which are displayed using the `--help` option. For example:

```
source /opt/intel/oneapi/setvars.sh --help
```

Of particular note are the `--config=file` argument and the ability to include additional arguments that will be passed to the `vars.sh` scripts that are called by the `setvars.sh` script.

The `--config=file` argument provides the ability to limit environment initialization to a specific set of oneAPI components, as well as providing a way to initialize the environment for a specific component version. For example, to limit environment setup to just the Intel® Integrated Performance Primitives (Intel® IPP) library and the Intel® oneAPI Math Kernel Library (oneMKL), create a config file that tells the `setvars.sh` script to only configure the environment variables for those two oneAPI components. More details and examples are provided in [Use a Config file for setvars.sh on Linux or macOS](#).

Any extra arguments passed on the `setvars.sh` command line that are not described in the `setvars.sh` help message will be passed to every called `vars.sh` script. That is, if the `setvars.sh` script does not recognize an argument, it assumes the argument is meant for use by one or more component scripts and passes those extra arguments to every component `vars.sh` script that it calls. The most common extra arguments are the `ia32` and `intel64` arguments, which are used by the Intel compilers and the Intel IPP and oneMKL libraries to indicate the application target architecture.

Inspect the individual `vars.sh` scripts to determine which, if any, command line arguments they accept.

## How to Run

```
source <install-dir>/setvars.sh
```

---

### NOTE

If you are using a non-POSIX shell, such as `csh`, use the following command:

```
% bash -c 'source <install-dir>/setvars.sh ; exec csh'
```

Alternatively, use the [modulefiles scripts](#) to set up your development environment. The modulefiles scripts work with all Linux shells.

---

## How to Verify

After running the `setvars.sh` script, verify success by searching for the `SETVARS_COMPLETED` environment variables. If `setvars.sh` was successful, `SETVARS_COMPLETED` will have a value of 1:

```
env | grep SETVARS_COMPLETED
```

Return value

```
SETVARS_COMPLETED=1
```

## Multiple Runs

Because many of the individual `env/vars.sh` scripts make significant changes to `PATH`, `CPATH`, and other environment variables, the top-level `setvars.sh` script will not allow multiple invocations of itself in the same session. This is done to ensure that your environment variables do not become too long due to redundant path references, especially the `$PATH` environment variable.



This can be overridden by passing `setvars.sh` a `--force` flag. In this example, the user tries to run `setvars.sh` twice. The second instance is stopped because `setvars.sh` has already been run.

```
> source <install-dir>/setvars.sh
:: initializing environment ...
(SNIP: lot of output)
:: oneAPI environment initialized ::

> source <install-dir>/setvars.sh
:: WARNING: setvars.sh has already been run. Skipping re-execution.
  To force a re-execution of setvars.sh, use the '--force' option.
  Using '--force' can result in excessive use of your environment variables
```

In the third instance, the user runs `setvars.sh --force` and the initialization is successful.

```
> source <install-dir>/setvars.sh --force
:: initializing environment ...
(SNIP: lot of output)
:: oneAPI environment initialized ::
```

### ONEAPI\_ROOT Environment Variable

The `ONEAPI_ROOT` variable is set by the top-level `setvars.sh` script when that script is sourced. If there is already a `ONEAPI_ROOT` environment variable defined, `setvars.sh` overwrites it. This variable is primarily used by the `oneapi-cli` sample browser and the Eclipse\* and Visual Studio Code\* sample browsers to help them locate oneAPI tools and components, especially for in locating the `setvars.sh` script if the `SETVARS_CONFIG` feature has been enabled. For more information on the `SETVARS_CONFIG` feature, see [Automate the setvars.sh Script with Eclipse\\*](#).

On Linux and macOS systems, the installer does not add the `ONEAPI_ROOT` variable to the environment. To add it to the default environment, define the variable in your local shell initialization file(s) or in the system's `/etc/environment` file.

### Use a Config file for `setvars.sh` on Linux or macOS

The `setvars.sh` script sets environment variables for use with the oneAPI toolkits by sourcing each of the `<install-dir>/latest/env/vars.sh` scripts found in the respective oneAPI folders. Unless you configure your Linux system to source the `setvars.sh` script automatically, it must be sourced every time a new terminal window is opened for command line development, or prior to launching Eclipse\* or any other C/C++ IDE or editor you use for C/C++ development. For more information, see [Configure Your System](#).

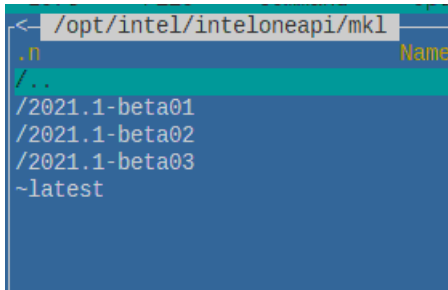
The procedure below describes how to use a configuration file to manage environment variables.

### Versions and Configurations

Some oneAPI tools support installation of multiple versions. For those tools that do support multiple versions, the directory is organized like this:

```
[Component] directory
- [1.0] version directory
- [1.1] version directory
- [1.2] version directory
- [latest -> 1.2] symlink or shortcut
```

For example:



For all tools, there is a symlink named `latest` that points to the latest installed version of that component; and the `vars.sh` script located in the `latest/env/` folder is what the `setvars.sh` sources by default.

If required, `setvars.sh` can be customized to point to a specific directory by using a configuration file.

### --config Parameter

The top level `setvars.sh` script accepts a `--config` parameter that identifies your custom **config.txt** file.

```
> source <install-dir>/setvars.sh --config="full/path/to/your/config.txt"
```

The name of your configuration file can have any name you choose. You can create many config files to setup a variety of development or test environments. For example, you might want to test the latest version of a library with an older version of a compiler; use a `setvars` config file to manage such a setup.

### Config File Sample

The examples below show a simple example of the config file:

#### Load Latest of Everything but...

```
mkl=1.1
dlldt=exclude
```

#### Exclude Everything but...

```
default=exclude
mkl=1.0
ipp=latest
```

The configuration text file must follow these requirements:

- a newline delimited text file
- each line consists of a single "key=value" pair
- "key" names a component folder in the top-level set of oneAPI directories (the folders found in the `$ONEAPI_ROOT` directory). If a "key" appears more than once in a config file, the last "key" wins and any prior keys with the same name are ignored.
- "value" names a version directory that is found at the top-level of the component directory. This includes any symlinks (such as `latest`) that might be present at that level in the component directory.
  - OR "value" can be "exclude", which means the named key will NOT have its `env/vars.sh` script sourced by the `setvars.sh` script.

The "key=value" pair "default=exclude" is a special case. When included, it will exclude sourcing ALL `env/vars.sh` scripts, except those that are listed in the config file. See the examples below.

### Further Customization of Config Files

The config file can be used to exclude specific components, include specific component versions or only include specific component versions that are named after a "default=exclude" statement.

By default, `setvars.sh` will process the latest version of each `env/vars.sh` script.

To explain this further, the sample below shows two versions of oneMKL installed: 2021.1-beta03 and 2021.1-beta04. There is a symlink to 2021-beta04 indicating that it is the latest version, so by default `setvars.sh` will source the 2021.1-beta04 `vars.sh` script in the `mk1` folder.

```
/opt/intel/oneapi/mkl
|
|-- 2021.1-beta03
|   |-- env
|   |-- include
|   |-- interfaces
|   |-- lib
|   |-- tools
|
|-- 2021.1-beta04
|   |-- env
|   |-- include
|   |-- interfaces
|   |-- lib
|   |-- tools
|
|-- latest -> 2021.1-beta04
|   |-- env
|   |-- include
|   |-- interfaces
|   |-- lib
|   |-- tools
```

### Specify a Specific Version

To direct `setvars.sh` to source the `<install-dir>/mk1/2021.1-beta03/env/vars.sh` script, add `mk1=2021.1-beta03` to your config file.

This instructs `setvars.sh` to source on the `env/vars.sh` script located in the 2021.1-beta03 version folder inside the `mk1` directory. For other installed components, `setvars.sh` will source the `env/vars.sh` script located in the latest version folder.

### Exclude Specific Components

To exclude a component, use the following syntax:

```
<key>=exclude
```

For example, to exclude Intel IPP, but include the 2021.1-beta03 version of oneMKL:

```
mk1=2021.1-beta03
ipp=exclude
```

In this example:

- `setvars.sh` WILL source the Intel one MKL 2021.1-beta03 `env/vars.sh` script
- `setvars.sh` WILL NOT source any Intel IPP `env/vars.sh` script files
- `setvars.sh` WILL source the latest version of the remaining `env/vars.sh` script files

### Include Specific Components

To source a specific list of component `env/vars.sh` scripts, you must first exclude all `env/vars.sh` scripts. Then add back the list of components to be sourced by `setvars.sh`. Use the following syntax to exclude all component `env/vars.sh` scripts from being sourced:

```
default=exclude
```

For example, to have `setvars.sh` source only the oneMKL and Intel IPP component `env/vars.sh` scripts, use this config file:

```
default=exclude
mkl=2021.1-beta03
ipp=latest
```

In this example:

- `setvars.sh` WILL source the oneMKL 2021.1-beta03 `env/vars.sh` script
- `setvars.sh` WILL source the latest version of the Intel IPP `env/vars.sh` script
- `setvars.sh` WILL NOT source the `env/vars.sh` script for any other components

## Automate the `setvars.sh` Script with Eclipse\*

The `setvars.sh` script sets up the environment variables needed to use the oneAPI toolkits. This script must be run every time a new terminal window is opened for command-line development. The `setvars.sh` script can also be run automatically when Eclipse\* is started. You can configure this feature to instruct the `setvars.sh` script to set up a specific set of oneAPI tools by using the `SETVARS_CONFIG` environment variable.

### SETVARS\_CONFIG Environment Variable States

The `SETVARS_CONFIG` environment variable enables automatic configuration of the oneAPI development environment when you start your instance of Eclipse IDE for C/C++ Developers. The variable has three conditions or states:

- Undefined (the `SETVARS_CONFIG` environment variable does not exist)
- Defined but empty (the value contains nothing or only whitespace)
- Defined and points to a `setvars.sh` configuration file

If `SETVARS_CONFIG` is undefined or if it exists but has no value (or contains only whitespace), the `setvars.sh` script will be automatically run when Eclipse is started. In this case, the `setvars.sh` script initializes the environment for *all* oneAPI tools that are installed on your system. For more information about running the `setvars.sh` script, see [Build and Run a Sample Project Using Eclipse](#).

When `SETVARS_CONFIG` is defined with the absolute pathname to a `setvars` configuration file, the `setvars.sh` script will be automatically run when Eclipse is started. In this case, the `setvars.sh` script initializes the environment for only those oneAPI tools that are defined in the `setvars` configuration file. For more information about how to create a `setvars` config file, see [Use a Config file for `setvars.sh` on Linux or macOS](#).

---

**NOTE** The default `SETVARS_CONFIG` behavior in Eclipse is different than the behavior described for Visual Studio on Windows. When starting Eclipse, automatic execution of the `setvars.sh` script is always attempted. When starting Visual Studio automatic execution of the `setvars.bat` script it is only attempted if the `SETVARS_CONFIG` environment variable has been defined.

---

## Create a `setvars` Configuration File

Create a new text file that you will use as your `setvars` configuration file. In this example, the file is named `config.txt` and is located in the users home folder. For example `"${HOME}"/config/.txt` or `~/config/.txt`.

A `setvars` configuration file can have any name and can be saved to any location on your hard disk, as long as that location and the file are accessible and readable by Eclipse. (A plug-in that was added to Eclipse when you installed the oneAPI tools on your Linux system performs the `SETVARS_CONFIG` actions; that is why Eclipse must have access to the location and contents of the `setvars` configuration file.)

If you leave the `setvars` config file empty, the `setvars.sh` script will initialize your environment for *all* oneAPI tools that are installed on your system. This is equivalent to defining the `SETVARS_CONFIG` variable with an empty string. See [Use a Config file for setvars.sh on Linux or macOS](#) for details regarding what to put inside of your `setvars` config file.

## Define the SETVARS\_CONFIG Environment Variable

Since the `SETVARS_CONFIG` environment variable is not automatically defined during installation, you must add it to your environment before starting Eclipse (per the rules above). There are a variety of places to define the `SETVARS_CONFIG` environment variable:

- `/etc/environment`
- `/etc/profile`
- `~/.bashrc`
- and so on...

The list above shows common places to define environment variables on a Linux system. Ultimately, where you choose to define the `SETVARS_CONFIG` environment variable depends on your system and your needs.

## Use Modulefiles with Linux\*

Most of the component tool folders contain one or more modulefile scripts that configure the environment variables needed by that component to support development work. Modulefiles are an alternative to using the `setvars.sh` script to set up the development environment. Because modulefiles do not support arguments, multiple modulefiles are available for oneAPI tools and libraries that support multiple configurations (such as a 32-bit configuration and a 64-bit configuration).

### NOTE

The modulefiles provided with the Intel oneAPI toolkits are compatible with the Tcl Environment Modules (Tmod) and Lua Environment Modules (Lmod). The following minimum versions are supported:

- Tmod 4.1
- Tcl version 8.4
- Lmod version 8.2.10

Test which version is installed on your system using the following command:

```
module --version
```

Each of the modulefiles will automatically verify that the Tcl version on your system is adequate when it runs.

The oneAPI modulefile scripts are found in a `modulefiles` folder located inside each component folder (similar to how the individual vars scripts are located). For example, in a default installation, the `ipp` modulefiles script(s) are located in the `/opt/intel/ipp/latest/modulefiles/` directory.

Due to how oneAPI component folders are organized on the disk, it can be difficult to use the oneAPI modulefiles directly where they are installed. A special `modulefiles-setup.sh` script is provided in the oneAPI installation folder to make it easier to work with the oneAPI modulefiles. In a default installation, that setup script is located here: `/opt/intel/oneapi/modulefiles-setup.sh`

The `modulefiles-setup.sh` script locates all modulefile scripts that are part of the oneAPI installation and organizes them into a single directory of folders. Those folders are named for each installed oneAPI component that includes one or more modulefiles.

Each of these component-named folders contains symlinks pointing to all of the modulefiles that are provided by that oneAPI component. These symlinks are organized as versioned modulefiles. Each component folder includes (at minimum) a "latest" version modulefile that will be selected, by default, when loading a component modulefile without specifying a version label.

The default name for the top-level directory of oneAPI modulefiles is `modulefiles` and is located in the oneAPI installation folder. For example: `/opt/intel/oneapi/modulefiles`

### Creating the `modulefiles` Directory

Run the `modulefiles-setup.sh` script.

#### NOTE

By default, the `modulefiles-setup.sh` script creates a folder named `modulefiles` in the oneAPI toolkit installation folder. If your oneAPI installation folder is not writeable, use the `--output-dir=<path-to-folder>` option to create the `modulefiles` folder in a writeable location. Enter `modulefiles-setup.sh --help` for more information about this and other `modulefiles-setup.sh` script options.

After the `modulefiles-setup.sh` script has been run, an organization like the following is created in the top-level `modulefiles` folder:

```
[oneapi_root]
- [modulefiles]
- - [compiler]
- - - [1.0] -> [oneapi_root/compiler/1.0/modulefiles/compiler] # symlink named 1.0 points
to compiler modulefile
- - [compiler32]
- - - [1.0] -> [oneapi_root/compiler/1.0/modulefiles/compiler32] # symlink named 1.0
points to compiler32 modulefile
- - [ipp]
- - - [1.1] -> [oneapi_root/ipp/1.1/modulefiles/ipp]
- - - [1.2] -> [oneapi_root/ipp/1.2/modulefiles/ipp]
- - [ipp32]
- - - [1.1] -> [oneapi_root/ipp/1.1/modulefiles/ipp32]
- - - [1.2] -> [oneapi_root/ipp/1.2/modulefiles/ipp32]
etc...
```

Now, update the `MODULEFILESPATH` to point to this new `modulefiles` folder.

### Installing the `module` Utility onto Your System

The instructions below will help quickly get started with the Environment Modules utility on Ubuntu\*. For full details regarding installation and configuration of the `module` utility, see <http://modules.sourceforge.net/>.

```
$ sudo apt update
$ sudo apt install tcl
$ sudo apt install environment-modules
```

Confirm that the local copy of `tclsh` is new enough (as of this writing, version 8.4 or later is required):

```
$ tclsh
% puts $tcl_version
8.6
% exit
```

To test the `module` installation, initialize the `module` alias.

```
$ source /usr/share/modules/init/sh
$ module
```

---

**NOTE** Initialization for Bourne-compatible shells should work with the `source` command shown above. Additional shell-specific init scripts are provided in the `/usr/share/modules/init/` folder. See that folder and the initialization section in `man module` for more details.

---

Include sourcing the `module` alias init script ( `.../modules/init/sh`) in one of the startup scripts to ensure the `module` command is always available. At this point, the system should be ready to use the `module` command as shown in the following section.

### Getting Started with the `modulefiles-setup.sh` Script

The following example assumes you have:

- installed `tclsh` on to the Linux development system
- installed the Environment Modules utility (i.e., `module`) on to the system
- sourced the `.../modules/init/sh` (or equivalent) `module` init command
- installed the oneAPI toolkits required for your oneAPI development

```
$ cd <oneapi-root-folder>           # cd to the oneapi_root install directory
$ ./modulefiles-setup.sh           # run the modulefiles setup script
$ module use modulefiles           # use the modulefiles folder created above
$ module avail                     # will show tbb/X.Y, etc.
$ module load tbb                  # loads tbb/X.Y module
$ module list                      # should list the tbb/X.Y module you just loaded
$ module unload tbb               # removes tbb/X.Y changes from the environment
$ module list                      # should no longer list the tbb/X.Y env var module
```

Before the unload step, use the `env` command to inspect the environment and look for the changes that were made by the modulefile you loaded. For example, if you loaded the `tbb` modulefile, the command will show you some of the `env` changes made by that modulefile (inspect the modulefile to see all of the changes it will make):

```
$ env | grep -i "intel"
```

---

#### NOTE

A modulefile is a script, but it does not need to have the 'x' (executable) permission set, because it is loaded and interpreted by the "module" interpreter that is installed and maintained by the end-user. Installation of a oneAPI product does not include the modulefile interpreter. It must be installed separately. Likewise, modulefiles do not require that the 'w' permission be set, but they must be readable (ideally, the 'r' permission is set for all users).

---

### Versioning

The installer for oneAPI toolkits applies version folders to individual oneAPI tools and libraries in the form of versioned subdirectories inside the top-level directory for each tool or library. These versioned component folders are used to create the versioned modulefiles. This is essentially what the `modulefiles-setup.sh`

script does; it organizes the symbolic links it creates in the top-level `$(ONEAPI_ROOT)/modulefiles` folder as `<modulefile-name>/version`, so the respective `modulefiles` can be referenced by version when using the `module` command.

```
$ module avail
----- modulefiles -----
ipp/1.1  ipp/1.2  compiler/1.0  compiler32/1.0
```

## Multiple modulefiles

A tool or library may provide multiple `modulefiles` within its `modulefiles` folder. Each becomes a loadable module. They will be assigned a version per the component folder from which they were extracted.

## Understanding How the `modulefiles` are Written when using oneAPI

Symbolic links are used by the `modulefiles-setup.sh` script to gather all of the available tool and library `modulefiles` into a single top-level `modulefiles` folder for oneAPI. This means that the `modulefiles` for oneAPI are not moved or touched. As a consequence of this approach, the `${ModulesCurrentModulefile}` variable points to a *symlink* to each `modulefile`, not to the actual `modulefile` located in the respective installation folders. Because of this, these `modulefiles` are *not* able to reference other folders or files within the `modulefile`'s component folder, because of the symlinks.

Thus, each `modulefile` for oneAPI uses a statement such as:

```
[ file readlink ${ModulesCurrentModulefile} ]
```

to get a reference to the original `modulefile` located in the respective install directory.

For a better understanding, review the `modulefiles` included with the installation. Most include comments explaining how they resolve *symlink* references to a real file, as well as parsing the version number (and version directory). They also include checks to insure that the installed TCL is an appropriate version level and include checks to prevent you from inadvertently loading two versions of the same `modulefile`.

## Use of the `module load` Command by `modulefiles`

Several of the `modulefiles` use the `module load` command to ensure that any required dependent modules are also loaded. There is no attempt to specify the version of those dependent `modulefiles`. This means that a specific dependent module can be manually preloaded prior to loading the module that requires that dependent module. If you do not preload a dependent module, the latest available version is loaded.

This is by design, because it gives the flexibility to control the environment. For example, you may have installed an updated version of a library that you want to test against a previous version of the compiler. Perhaps the updated library has a bug fix and you are not interested in changing the version of any other libraries in your build. If the dependent `modulefiles` were hard-coded to require a specific dependent version of this library, you could not perform such a test.

---

### NOTE

If a dependent `module load` cannot be satisfied, the currently loading module file will be terminated and no changes will be made to your environment.

---

## Additional Resources

For more information about `modulefiles`, see:

- <http://www.admin-magazine.com/HPC/Articles/Environment-Modules>
- <https://support.pawsey.org.au/documentation/display/US/Sample+modulefile+for+Environment+Modules>
- <https://www.chpc.utah.edu/documentation/software/modules-advanced.php>



- <https://modules.readthedocs.io/en/latest/>
- <https://lmod.readthedocs.io/en/latest/>

## Use CMake with oneAPI Applications

---

The CMake packages provided with Intel oneAPI products allow a CMake project to make easy use of oneAPI libraries on Windows\* or Linux\*. Using the provided packages, the experience should be similar to how other system libraries integrate with a CMake project. There are dependency and other build variables provided to CMake project targets as desired.

Not all oneAPI component products support CMake. Those libraries that provide a CMake configuration can be identified by looking in the following locations:

- On Linux:
  - System: `/usr/local/lib/cmake`
  - User: `~/lib/cmake`
- On Windows: `HKEY_LOCAL_MACHINE\Software\Kitware\CMake\Packages\`

To use the CMake packages, use the oneAPI libraries as you would other system libraries. For example, using `find_package(tbb)` ensures that your application's CMake package is using the oneTBB package.

# Compile and Run oneAPI Programs

# 4

This chapter details the oneAPI compilation process across direct programming and API-based programming covering CPU, GPUs, and FPGAs. Some details about the tools employed at each stage of compilation are explained.

## Single Source Compilation

The oneAPI programming model supports single source compilation. Single source compilation has several benefits compared to separate host and device code compilation. It should be noted that the oneAPI programming model also supports separate host and device code compilation as some users may prefer it. Advantages of the single source compilation model include:

- Usability – programmers need to create fewer files and can define device code right next to the call site in the host code.
- Extra safety – single source means one compiler can see the boundary code between host and device and the actual parameters generated by host compiler will match formal parameters of the kernel generated by the device compiler.
- Optimization – the device compiler can perform additional optimizations by knowing the context from which a kernel is invoked. For instance, the compiler may propagate some constants or infer pointer aliasing information across the function call.

## Invoke the Compiler

The Intel® oneAPI C++ Compiler is invoked using `icpx` (Linux\*) or `icx` (Windows\*). The Intel® oneAPI DPC++ Compiler is invoked using `dpcpp`.

For more information, see [Invoking the Compiler](#) in the *Intel® oneAPI DPC++/C++ Compiler Developer Guide and Reference*.

To enable OpenMP\* offloading for C++ applications, invoke the compiler with:

- `icpx -fopenmp -fopenmp-targets=<arch>` (Linux)
- `icx /Qopenmp /Qopenmp-targets:<arch>` (Windows).

To enable OpenMP offloading for DPC++ applications, invoke the compiler with:

- `dpcpp -fopenmp -fopenmp-targets=<arch>` (Linux)
- `dpcpp /Qopenmp /Qopenmp-targets:<arch>` (Windows)

For more information about options, you can go to the option descriptions found in the [Compiler Options](#) section of the *Intel® oneAPI DPC++/C++ Compiler Developer Guide and Reference*.

The `dpcpp` driver has different compatibilities on different OS hosts. Linux provides GCC\*-style command line options and Windows provides Microsoft Visual C++\* compatibility with Microsoft Visual Studio\*.

- It recognizes GCC-style command line options (starting with "-") and can be useful for projects that share a build system across multiple operating systems.
- It recognizes Windows command line options (starting with "/") and can be useful for Microsoft Visual Studio-based projects.

## Standard Intel oneAPI DPC++/C++ Compiler Options

A full list of Intel oneAPI DPC++/C++ Compiler options are available from the *Intel oneAPI DPC++/C++ Compiler Developer Guide and Reference*.

- The [Offload Compilation Options](#), [OpenMP\\* Options](#), and [Parallel Processing Options](#) section includes options specific to DPC++ and OpenMP\* offload.

- A full list of available options and a brief description of each is available in the [Alphabetical List of Compiler Options](#).

## Example Compilation

oneAPI applications can be directly programmed, API-based, which makes use of available oneAPI libraries, or a combination of directly programmed and API-based. API-based programming takes advantage of device offload using library functionality, which can save developers time when writing an application. In general it is easiest to start with API-based programming and use DPC++ or OpenMP\* offload features where API-based programming is insufficient for your needs.

The following sections give examples of API-based code and direct programming using DPC++.

### API-based Code

The following code shows usage of an API call ( $a * x + y$ ) employing the Intel oneAPI Math Kernel Library function `oneapi::mkl::blas::axpy` to multiply  $a$  times  $x$  and add  $y$  across vectors of floating point numbers. It takes advantage of the oneAPI programming model to perform the addition on an accelerator.

```
#include <vector> // std::vector()
#include <cstdlib> // std::rand()
#include <CL/sycl.hpp>
#include "oneapi/mkl/blas.hpp"

int main(int argc, char* argv[]) {

    double alpha = 2.0;
    int n_elements = 1024;

    int incx = 1;
    std::vector<double> x;
    x.resize(incx * n_elements);
    for (int i=0; i<n_elements; i++)
        x[i*incx] = 4.0 * double(std::rand()) / RAND_MAX - 2.0;
    // rand value between -2.0 and 2.0

    int incy = 3;
    std::vector<double> y;
    y.resize(incy * n_elements);
    for (int i=0; i<n_elements; i++)
        y[i*incy] = 4.0 * double(std::rand()) / RAND_MAX - 2.0;
    // rand value between -2.0 and 2.0

    cl::sycl::device my_dev;
    try {
        my_dev = cl::sycl::device(cl::sycl::gpu_selector());
    } catch (...) {
        std::cout << "Warning, failed at selecting gpu device. Continuing on default(host)
device.\n";
    }

    // Catch asynchronous exceptions
    auto exception_handler = [] (cl::sycl::exception_list
        exceptions) {
        for (std::exception_ptr const& e : exceptions) {
            try {
                std::rethrow_exception(e);
            } catch (cl::sycl::exception const& e) {
                std::cout << "Caught asynchronous SYCL exception:\n";
            }
        }
    };
}
```

```

        std::cout << e.what() << std::endl;
    }
}

};

cl::sycl::queue my_queue(my_dev, exception_handler);

cl::sycl::buffer<double, 1> x_buffer(x.data(), x.size());
cl::sycl::buffer<double, 1> y_buffer(y.data(), y.size());

// perform y = alpha*x + y
try {
    oneapi::mkl::blas::axpy(my_queue, n_elements, alpha, x_buffer,
        incx, y_buffer, incy);
}

catch(cl::sycl::exception const& e) {
    std::cout << "\t\tCaught synchronous SYCL exception:\n"
        << e.what() << std::endl;
}

std::cout << "The axpy (y = alpha * x + y) computation is complete!" << std::endl;

// print y_buffer
auto y_accessor = y_buffer.template
    get_access<cl::sycl::access::mode::read>();
std::cout << std::endl;
std::cout << "y" << " = [ " << y_accessor[0] << " ]\n";
std::cout << "    [ " << y_accessor[1*incy] << " ]\n";
std::cout << "    [ " << "... ]\n";
std::cout << std::endl;

return 0;
}

```

To compile and build the application (saved as `axpy.cpp`):

1. Ensure that the `MKLROOT` environment variable is set appropriately (`echo ${MKLROOT}`). If it is not set appropriately, source the `setvars.sh` script or run the `setvars.bat` script or set the variable to the folder that contains the `lib` and `include` folders.

For more information about the `setvars` scripts, see [oneAPI Development Environment Setup](#).

2. Build the application using the following command:

On Linux:

```
dpcpp -I${MKLROOT}/include -c axpy.cpp -o axpy.o
```

On Windows:

```
dpcpp -I${MKLROOT}/include /EHsc -c axpy.cpp /Foaxpy.obj
```

3. Link the application using the following command:

On Linux:

```
dpcpp axpy.o -fsycl-device-code-split=per_kernel \
"${MKLROOT}/lib/intel64"/libmkl_sycl.a -Wl,-export-dynamic -Wl,--start-group \
"${MKLROOT}/lib/intel64"/libmkl_intel_ilp64.a \
"${MKLROOT}/lib/intel64"/libmkl_sequential.a \
"${MKLROOT}/lib/intel64"/libmkl_core.a -Wl,--end-group -lsycl -lOpenCL \
-lpthread -lm -ldl -o axpy.out
```

On Windows:

```
dpcpp axpy.obj -fsycl-device-code-split=per_kernel ^
"${MKLRROOT}/lib/intel64"/libmkl_sycl.lib ^
"${MKLRROOT}/lib/intel64"/libmkl_intel_ilp64.lib ^
"${MKLRROOT}/lib/intel64"/libmkl_sequential.lib ^
"${MKLRROOT}/lib/intel64"/libmkl_core.lib ^
sycl.lib OpenCL.lib -o axpy.exe
```

4. Run the application using the following command:

On Linux:

```
./axpy.out
```

On Windows:

```
axpy.exe
```

## Direct Programming

The [vector addition sample code](#) is employed in this example. It takes advantage of the oneAPI programming model to perform the addition on an accelerator.

The following command compiles and links the executable.

```
dpcpp vector_add.cpp
```

The components and function of the command and options are similar to those discussed in the API-Based Code section above.

Execution of this command results in the creation of an executable file, which performs the vector addition when run.

## Compilation Flow Overview

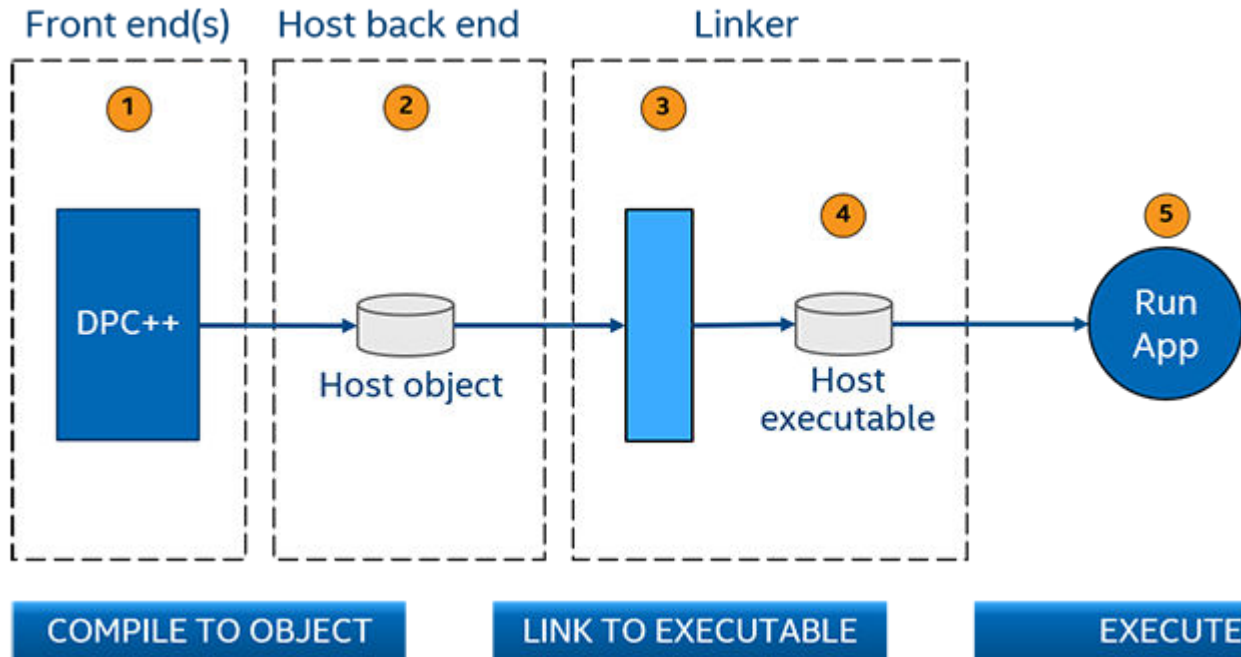
When you create a program with offload, the compiler must generate code for both the host and the device. oneAPI tries to hide this complexity from the developer. The developer simply compiles a Data Parallel C++ (DPC++) application with `dpcpp`, and the same compile command generates both host and device code.

For device code, two options are available: Just-in-Time (JIT) compilation and Ahead-of-Time (AOT) compilation, with JIT being the default. This section describes how host code is compiled, and the two options for generating device code. Additional details are available in Chapter 13 of the [Data Parallel C++ book](#).

### Traditional Compilation Flow (Host-only Application)

The traditional compilation flow is a standard compilation like the one used for C, C++, or other languages, used when there is no offload to a device.

The traditional compilation phases are shown in the following diagram:

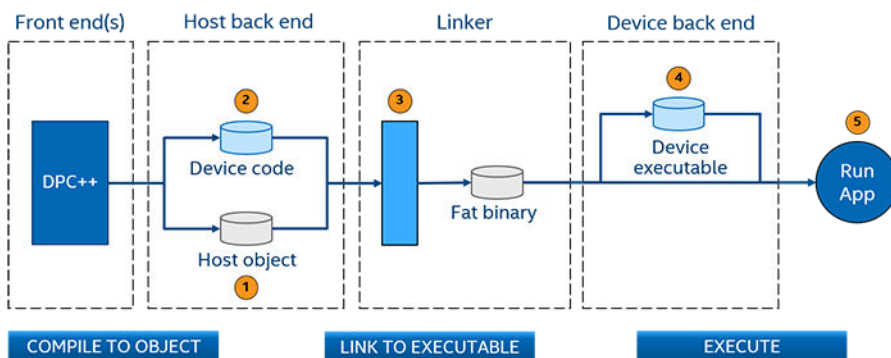


1. The front end translates the source into an intermediate representation and then passes that representation to the back end.
2. The back end translates the intermediate representation to object code and emits an object file (`host.obj` on Windows\*, `host.o` on Linux\*).
3. One or more object files are passed to the linker.
4. The linker creates an executable.
5. The application runs.

### Compilation Flow for DPC++ Offload Code

The compilation flow for DPC++ offload code adds steps for device code to the traditional compilation flow, with JIT and AOT options for device code. In this flow, the developer compiles a DPC++ application with `dpcpp`, and the output is an executable containing both host and device code.

The basic compilation phases for DPC++ offload code are shown in the following diagram:



1. The host code is translated to object code by the back end.
2. The device code is translated to either a SPIR-V or device binary.
3. The linker combines the host object code and the device code (SPIR-V or device binary) into an executable containing the host binary with the device code embedded in it. This process is known as a fat binary.

4. At runtime, the operating system starts the host application. If it has offload, the DPC++ runtime loads the device code (converting the SPIR-V to device binary if needed).
5. The application runs on the host and a specified device.

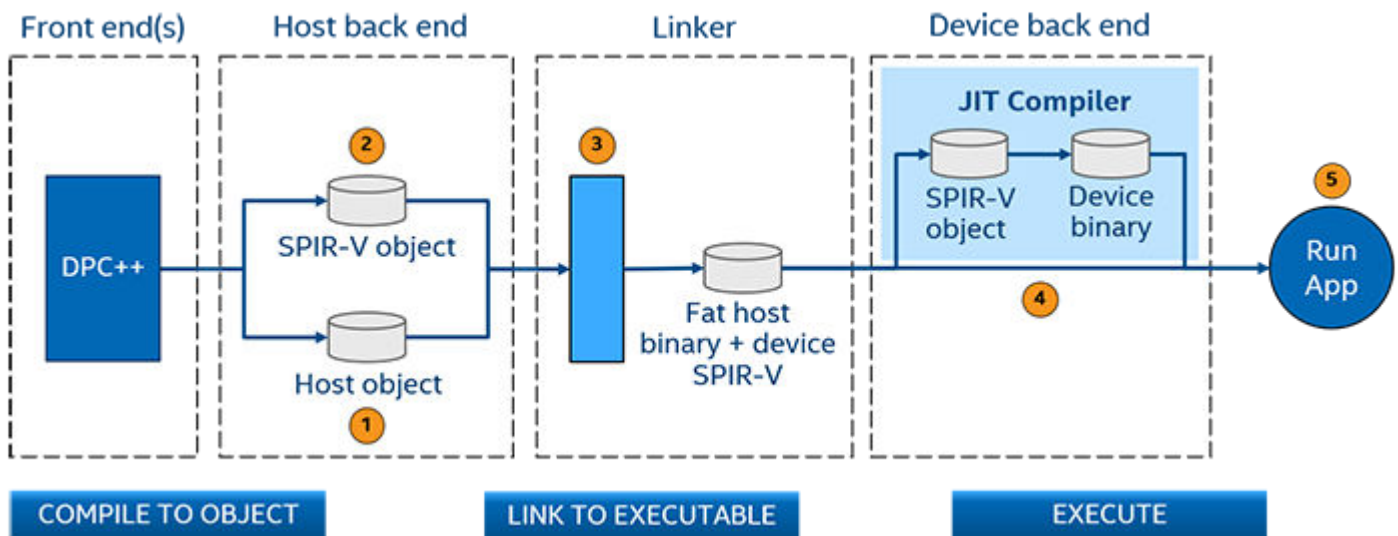
### JIT Compilation Flow

In the JIT compilation flow, the code for the device is translated to SPIR-V intermediate code by the back-end, embedded in the fat binary as SPIR-V, and translated from SPIR-V to device code by the runtime. When the application is run, the runtime determines the available devices and generates the code specific to that device. This allows for more flexibility in where the application runs and how it performs than the AOT flow, which must specify a device at compile time. However, performance may be worse because compilation occurs when the application runs. Larger applications with significant amounts of device code may notice performance impacts.

**Tip** The JIT compilation flow is useful when you do not know what the target device will be.

**NOTE** JIT compilation is not supported for FPGA devices.

The compilation phases are shown in the following diagram:



1. The host code is translated to object code by the back end.
2. The device code is translated to SPIR-V.
3. The linker combines the host object code and the device SPIR-V into a fat binary containing host executable code with SPIR-V device code embedded in it.
4. At runtime:
  - a. The device runtime on the host translates the SPIR-V for the device into device binary code.
  - b. The device code is loaded onto the device.
5. The application runs on the host and device available at runtime.

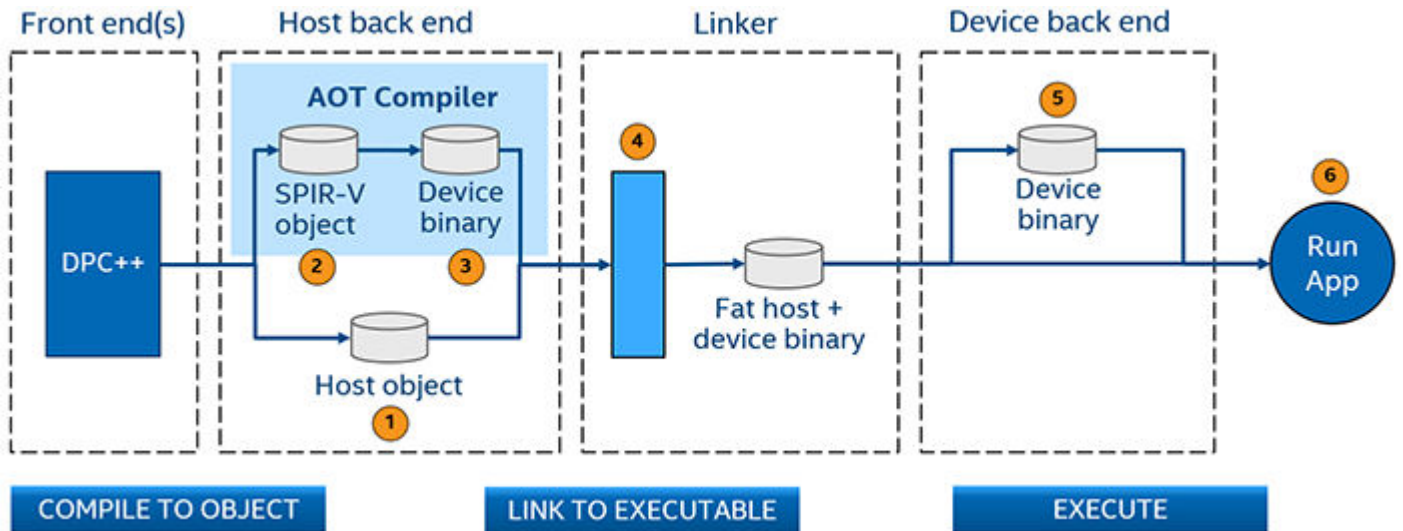
### AOT Compilation Flow

In the AOT compilation flow, the code for the device is translated to SPIR-V and then device code in the host back-end and the resulting device code is embedded in the generated fat binary. The AOT flow provides less flexibility than the JIT flow because the target device must be specified at compilation time. However, executable start-up time is faster than the JIT flow.

**Tip**

- The AOT compilation flow is good when you know exactly which device you are targeting.
- The AOT flow is recommended when debugging your application as it speeds up the debugging cycle.

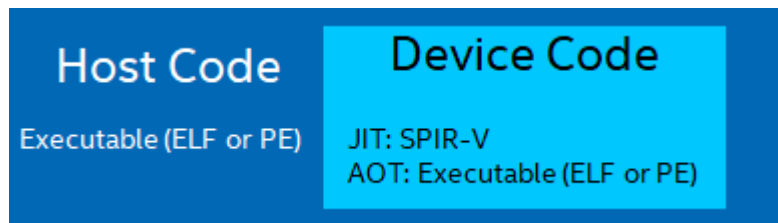
The compilation phases are shown in the following diagram:



1. The host code is translated to object code by the back end.
2. The device code is translated to SPIR-V.
3. The SPIR-V for the device is translated to a device code object using the device specified by the user on the command line.
4. The linker combines the host object code and the device object code into a fat binary containing host executable code with device executable code embedded in it.
5. At runtime, the device executable code is loaded onto the device.
6. The application runs on a host and specified device.

**Fat Binary**

A fat binary is generated from the JIT and AOT compilation flows. It is a host binary that includes embedded device code. The contents of the device code vary based on the compilation flow.



- The host code is an executable in either the ELF (Linux) or PE (Windows) format.
- The device code is a SPIR-V for the JIT flow or an executable for the AOT flow. Executables are in one of the following formats:
  - CPU: ELF (Linux), PE (Windows)
  - GPU: ELF (Windows, Linux)
  - FPGA: ELF (Linux), PE (Windows)



## CPU Flow

DPC++ supports online and offline compilation modes for the CPU target. Online compilation is the same as for all other targets.

### Online Compilation for CPU

No specifics for CPU target. The command below produces a fat binary with a SPIR-V image, which can be run with online compilation on any compatible device, including a CPU.

```
dpcpp a.cpp b.cpp -o app.out
```

### Offline Compilation for CPU

---

**NOTE** This is an experimental feature with limited functionality.

---

Use this command to produce `app.out`, which only runs on an x86 device.

```
dpcpp -fsycl-targets=spir64_x86_64-unknown-linux-sycldevice a.cpp b.cpp -o app.out
```

### Example CPU Commands

The commands below implement the scenario when part of the device code resides in a static library.

---

**NOTE**  
Linking with a dynamic library is not supported.

---

Produce a fat object with device code:

```
dpcpp -c static_lib.cpp
```

Create a fat static library out of it using the `ar` tool:

```
ar cr libstlib.a static_lib.o
```

Compile application sources:

```
dpcpp -c a.cpp
```

Link the application with the static library:

```
dpcpp -foffload-static-lib=libstlib.a a.o -o a.exe
```

### Optimization Flags for CPU Architectures

In offline compilation mode, optimization flags can be used to produce code aimed to run better on a specific CPU architecture. Those are passed via the `-Xsycl-target-backend dpcpp option`:

On Linux:

```
dpcpp -fsycl-targets=spir64_x86_64-unknown-linux-sycldevice \
-Xsycl-target-backend=spir64_x86_64-unknown-linux-sycldevice "<CPU optimization flags>" \
a.cpp b.cpp -o app.out
```

On Windows:

```
dpcpp -fsycl-targets=spir64_x86_64-unknown-linux-sycldevice ^
-Xsycl-target-backend=spir64_x86_64-unknown-linux-sycldevice "<CPU optimization flags>" ^
a.cpp b.cpp -o app.out
```

Supported CPU optimization flags are:

```
-march=<instruction_set_arch> Set target instruction set architecture:
'sse42' for Intel(R) Streaming SIMD Extensions 4.2
'avx2' for Intel(R) Advanced Vector Extensions 2
'avx512' for Intel(R) Advanced Vector Extensions 512
```

#### NOTE

The set of supported optimization flags may be changed in future releases.

## Host and Kernel Interaction on CPU

Host code interacts with device code through kernel parameters and data buffers represented with `cl::sycl::accessor` objects or `cl_mem` objects for OpenCL data buffers.

## Control Binary Execution on Multiple CPU Cores

### Environment Variables

The following environment variables control the placement of DPC++ threads on multiple CPU cores during program execution.

Environment Variable	Description
DPCPP_CPU_CU_AFFINITY	<p>Set thread affinity to CPU. The value and meaning is the following:</p> <ul style="list-style-type: none"> <li>close - threads are pinned to CPU cores successively through available cores.</li> <li>spread - threads are spread to available cores.</li> <li>master - threads are put in the same cores as master. If DPCPP_CPU_CU_AFFINITY is set, master thread is pinned as well, otherwise master thread is not pinned</li> </ul> <p>This environment variable is similar to the OMP_PROC_BIND variable used by OpenMP.</p> <p><b>Default:</b> Not set</p>
DPCPP_CPU_SCHEDULE	<p>Specify the algorithm for scheduling work-groups by the scheduler. Currently, DPC++ uses TBB for scheduling. The value selects the partitioner used by the TBB scheduler. The value and meaning is the following:</p> <ul style="list-style-type: none"> <li>dynamic - TBB auto_partitioner. It performs sufficient splitting to balance load.</li> <li>affinity - TBB affinity_partitioner. It improves auto_partitioner's cache affinity by its choice of mapping subranges to worker threads compared to</li> <li>static - TBB static_partitioner. It distributes range iterations among worker threads as uniformly as possible. TBB partitioner relies grain-size to control chunking. Grain-size is 1 by default, indicating every work-group can be executed independently.</li> </ul> <p><b>Default:</b> dynamic</p>
DPCPP_CPU_NUM_CUS	Set the numbers threads used for kernel execution.

Environment Variable	Description
	<p>To avoid over subscription, maximum value of <code>DPCPP_CPU_NUM_CUS</code> should be the number of hardware threads. If <code>DPCPP_CPU_NUM_CUS</code> is 1, all the workgroups are executed sequentially by a single thread and this is useful for debugging.</p> <p>This environment variable is similar to <code>OMP_NUM_THREADS</code> variable used by OpenMP.</p> <p><b>Default:</b> Not set. Determined by TBB.</p>
<code>DPCPP_CPU_PLACES</code>	<p>Specify the places that affinities are set. The value is { sockets   numa_domains   cores   threads }.</p> <p>This environment variable is similar to the <code>OMP_PLACES</code> variable used by OpenMP.</p> <p>If value is <code>numa_domains</code>, TBB NUMA API will be used. This is analogous to <code>OMP_PLACES=numa_domains</code> in the OpenMP 5.1 Specification. TBB task arena is bound to numa node and SYCL nd range is uniformly distributed to task arenas.</p> <p><code>DPCPP_CPU_PLACES</code> is suggested to be used together with <code>DPCPP_CPU_CU_AFFINITY</code>.</p> <p><b>Default:</b> cores</p>

See the [Intel oneAPI DPC++/C++ Compiler Developer Guide and Reference](#) for more information about all supported environment variables.

### Example 1: Hyper-threading Enabled

Assume a machine with 2 sockets, 4 physical cores per socket, and each physical core has 2 hyper threads.

- `S<num>` denotes the socket number that has 8 cores specified in a list
- `T<num>` denotes the TBB thread number
- `"-"` means unused core

```

DPCPP_CPU_NUM_CUS=16
export DPCPP_CPU_PLACES=sockets
DPCPP_CPU_CU_AFFINITY=close:  S0:[T0 T1 T2 T3 T4 T5 T6 T7]          S1:[T8 T9 T10 T11 T12 T13
T14 T15]
DPCPP_CPU_CU_AFFINITY=spread: S0:[T0 T2 T4 T6 T8 T10 T12 T14]      S1:[T1 T3 T5 T7 T9 T11
T13 T15]
DPCPP_CPU_CU_AFFINITY=master: S0:[T0 T1 T2 T3 T4 T5 T6 T7]        S1:[T8 T9 T10 T11 T12 T13
T14 T15]

export DPCPP_CPU_PLACES=cores
DPCPP_CPU_CU_AFFINITY=close :  S0:[T0 T8 T1 T9 T2 T10 T3 T11]      S1:[T4 T12 T5 T13 T6 T14
T7 T15]
DPCPP_CPU_CU_AFFINITY=spread:  S0:[T0 T8 T2 T10 T4 T12 T6 T14]    S1:[T1 T9 T3 T11 T5 T13 T7
T15]
DPCPP_CPU_CU_AFFINITY=master:  S0:[T0 T1 T2 T3 T4 T5 T6 T7]        S1:[T8 T9 T10 T11 T12 T13
T14 T15]

export DPCPP_CPU_PLACES=threads
DPCPP_CPU_CU_AFFINITY=close:   S0:[T0 T1 T2 T3 T4 T5 T6 T7]        S1:[T8 T9 T10 T11 T12 T13
T14 T15]
DPCPP_CPU_CU_AFFINITY=spread:  S0:[T0 T2 T4 T6 T8 T10 T12 T14]    S1:[T1 T3 T5 T7 T9 T11 T13

```

```
T15]
DPCPP_CPU_CU_AFFINITY=master:  S0:[T0 T1 T2 T3 T4 T5 T6 T7]      S1:[T8 T9 T10 T11 T12 T13
T14 T15]

export DPCPP_CPU_NUM_CUS=8
DPCPP_CPU_PLACES=sockets, cores and threads have the same bindings:
DPCPP_CPU_CU_AFFINITY=close close:  S0:[T0 - T1 - T2 - T3 -]      S1:[T4 - T5 - T6 - T7 -]
DPCPP_CPU_CU_AFFINITY=close spread:  S0:[T0 - T2 - T4 - T6 -]      S1:[T1 - T3 - T5 - T7 -]
DPCPP_CPU_CU_AFFINITY=close master:  S0:[T0 T1 T2 T3 T4 T5 T6 T7] S1:[]
```

## Example 2: Hyper-threading Disabled

Assume a machine with 2 sockets, 4 physical cores per socket, and each physical core has 2 hyper threads.

- S<num> denotes the socket number that has 8 cores specified in a list
- T<num> denotes the TBB thread number
- "-" means unused core

```
export DPCPP_CPU_NUM_CUS=8
DPCPP_CPU_PLACES=sockets, cores and threads have the same bindings:
DPCPP_CPU_CU_AFFINITY=close:  S0:[T0 T1 T2 T3]      S1:[T4 T5 T6 T7]
DPCPP_CPU_CU_AFFINITY=spread: S0:[T0 T2 T4 T6]      S1:[T1 T3 T5 T7]
DPCPP_CPU_CU_AFFINITY=master: S0:[T0 T1 T2 T3]      S1:[T4 T5 T6 T7]

export DPCPP_CPU_NUM_CUS=4
DPCPP_CPU_PLACES=sockets, cores and threads have the same bindings:
DPCPP_CPU_CU_AFFINITY=close:  S0:[T0 - T1 - ]      S1:[T2 - T3 - ]
DPCPP_CPU_CU_AFFINITY=spread: S0:[T0 - T2 - ]      S1:[T1 - T3 - ]
DPCPP_CPU_CU_AFFINITY=master: S0:[T0 T1 T2 T3]      S1:[ - - - - ]
```

## GPU Flow

The GPU Flow is like the CPU flow except that different back ends and target triples are used.

Target triple for GPU offline compiler is spir64\_gen-unknown-linux-sycldevice.

---

**NOTE** GPU offline compilation currently requires an additional option, which specifies the desired GPU architecture.

---

### See Also

[Intel® oneAPI GPU Optimization Guide](#)

## Example GPU Commands

The examples below illustrate how to create and use static libraries with device code on Linux.

---

**NOTE**  
Linking with a dynamic library is not supported.

---

Produce a fat object with device code:

```
dpcpp -c static_lib.cpp
```

Create a fat static library out of it using the ar tool:

```
ar cr libstlib.a static_lib.o
```

Compile application sources:

```
dpcpp -c a.cpp
```

Link the application with the static library:

```
dpcpp -foffload-static-lib=libstlib.a a.o -o a.exe
```

## Offline Compilation for GPU

The following example command produces `app.out` for a specific GPU target:

On Linux:

```
dpcpp -fsycl-targets=spir64_gen-unknown-linux-sycldevice \
-Xsycl-target-backend=spir64_gen-unknown-linux-sycldevice "-device skl" a.cpp b.cpp -o app.out
```

On Windows:

```
dpcpp -fsycl-targets=spir64_gen-unknown-linux-sycldevice ^
-Xsycl-target-backend=spir64_gen-unknown-linux-sycldevice "-device skl" a.cpp b.cpp -o app.out
```

## FPGA Flow

Field-programmable gate arrays (FPGAs) are configurable integrated circuits that you can program to implement arbitrary circuit topologies. Classified as spatial compute architectures, FPGAs differ significantly from fixed Instruction Set Architecture (ISA) devices such as CPUs and GPUs. FPGAs offer a different set of optimization trade-offs from these traditional accelerator devices.

While you can compile DPC++ code for CPU, GPU or FPGA, the compiling process for FPGA development is somewhat different than that for CPU or GPU development.

The following table summarizes terminologies used in describing the FPGA flow:

### FPGA Flow-specific Terminology

Term	Definition
<b>Device code</b>	SYCL source code that executes on a SYCL device rather than the host. Device code is specified via lambda expression, functor, or kernel class. For example, kernel code.
<b>Host code</b>	SYCL source code that is compiled by the host compiler and executes on the host rather than the device.
<b>Device image</b>	The result of compiling the device code to a binary (or intermediate) representation. The device image is combined with the host binary, within a (fat) object or executable file. See <a href="#">Compilation Flow Overview</a> .
<b>FPGA emulator image</b>	The device image resulting from compiling for the FPGA emulator. See <a href="#">FPGA Emulator</a>
<b>FPGA early image</b>	The device image resulting from the early image compilation stage. See <a href="#">FPGA Optimization Report</a>
<b>FPGA hardware image</b>	The device image resulting from the hardware image compilation stage. See <a href="#">FPGA Optimization Report</a> and <a href="#">FPGA Hardware</a> .

**Notice** You can also learn about programming for FPGAs in detail from the *Data Parallel C++* book available at [https://link.springer.com/chapter/10.1007/978-1-4842-5574-2\\_17](https://link.springer.com/chapter/10.1007/978-1-4842-5574-2_17).

## Why is FPGA Compilation Different?

FPGAs differ from CPUs and GPUs in some ways. One important difference when compared to CPU or GPU is generating a device binary for FPGA hardware that is a computationally intensive and time-consuming process. It is normal for an FPGA compile to take several hours to complete. For this reason, only ahead-of-time (or *offline*) kernel compilation mode is supported for FPGA. The long compile time for FPGA hardware makes just-in-time (or *online*) compilation impractical.

Longer compile times are detrimental to developer productivity. The Intel® oneAPI DPC++/C++ Compiler provides several mechanisms that enable you to target FPGA and iterate quickly on your designs. By circumventing the time-consuming process of full FPGA compilation wherever possible, you can benefit from the faster compile times that you are familiar with for CPU and GPU development.

## Types of DPC++ FPGA Compilation

The following table summarizes the types of FPGA compilation:

### Types of DPC++ FPGA Compilation

Device Image Type	Time to Compile	Description
<b>FPGA Emulator</b>	Seconds	The FPGA device code is compiled to the CPU. Use FPGA emulator to verify your SYCL code's functional correctness.
<b>Optimization Report</b>	Minutes	The FPGA device code is partially compiled for hardware. The compiler generates an optimization report that describes the structures generated on the FPGA, identifies performance bottlenecks, and estimates resource utilization.
<b>FPGA Hardware Image</b>	Hours	Generates the real FPGA bitstream to execute on the target FPGA platform.

A typical FPGA DPC++ development workflow is to iterate in each of these stages, refining the code using the feedback provided by each stage. Intel® recommends relying on emulation and the FPGA optimization report whenever possible.

#### Tip

To compile for FPGA emulation or to generate the FPGA optimization report, you need only the Intel® oneAPI DPC++/C++ Compiler, which is part of the Intel® oneAPI Base Toolkit. However, an FPGA hardware compile requires the [Intel® FPGA Add-on for oneAPI Base Toolkit](#). Refer to the [Intel® oneAPI Toolkits Installation Guide](#) for more information about installing this add-on.

## FPGA Emulator

The FPGA emulator is the fastest method to verify the correctness of your code. It executes the DPC++ device code on the CPU. The emulator is similar to the SYCL host device, but unlike the host device, the FPGA emulator device supports FPGA extensions such as FPGA pipes and `fpga_reg`. For more information, refer to [Pipes Extension](#) and [Kernel Variables](#) topics in the *Intel® oneAPI DPC++ FPGA Optimization Guide*.

The following are some important caveats to remember when using the FPGA emulator:

- **Performance is not representative**

Never draw inferences about FPGA performance from the FPGA emulator. The FPGA emulator's timing behavior is not correlated to that of the physical FPGA hardware. For example, an optimization that yields a 100x performance improvement on the FPGA may show no impact on the emulator performance. The emulator might show an unrelated increase or decrease.

- **Undefined behavior may differ**

If your code produces different results when compiled for the FPGA emulator versus FPGA hardware, your code most likely exercises undefined behavior. By definition, undefined behavior is not specified by the language specification, and might manifest differently on different targets.

#### Tip

When targeting the FPGA emulator device, use the `-O2` compiler flag to turn on optimizations and speed up the emulation. To turn off optimizations (for example, to facilitate debugging), pass `-O0`.

## FPGA Optimization Report

A full FPGA compilation occurs in the following stages and optimization reports are generated after both stages:

Stages	Description	Optimization Report Information
<b>FPGA early image</b> (Compilation takes minutes to complete)	The SYCL device code is optimized and converted into an FPGA design specified in the <a href="#">Verilog Register-Transfer Level (RTL)</a> (a low-level, native entry language for FPGAs). The intermediate compilation result is the FPGA early device image that is not an executable.  The optimization report generated at this stage is sometimes referred to as the <i>static report</i> .	Contains significant information about how the compiler has transformed your SYCL device code into an FPGA design. The report contains the following information: <ul style="list-style-type: none"> <li>• Visualizations of structures generated on the FPGA</li> <li>• Performance and expected performance bottleneck</li> <li>• Estimated resource utilization</li> </ul> For information about the FPGA optimization report, refer to the <a href="#">Intel® oneAPI DPC++ FPGA Optimization Guide</a> .
<b>FPGA hardware image</b> (Compilation takes hours to complete)	The Verilog RTL specifying the design's circuit topology is mapped onto the FPGA's primitive hardware resources by the <a href="#">Intel® Quartus® Prime Software</a> . The Intel® Quartus® Prime Software is included in the <a href="#">Intel® FPGA Add-On for oneAPI Base Toolkit</a> , which is required for this compilation stage. The result is an FPGA hardware binary (also referred to as a bitstream).	Contains precise information about resource utilization and $f_{\max}$ numbers. For detailed information about how to analyze reports, refer to <a href="#">Analyze your Design</a> section in the <i>Intel® oneAPI DPC++ FPGA Optimization Guide</i> .  For information about the FPGA hardware image, refer to the <a href="#">Intel® oneAPI DPC++ FPGA Optimization Guide</a> .

## FPGA Hardware

This is a full compile through to the FPGA hardware image. You can target the [Intel® Programmable Acceleration Card \(PAC\) with Intel® Arria® 10 GX FPGA](#), the [Intel® FPGA PAC D5005](#) (previously known as *Intel® PAC with Intel® Stratix® 10 SX FPGA*), or a custom board.

For more information about using Intel® PAC or custom boards, refer to the [FPGA BSPs and Boards](#) section.

## FPGA Compilation Flags

FPGA compilation flags control the [FPGA image type](#) the Intel® oneAPI DPC++/C++ Compiler targets.

The following are examples of Intel® oneAPI DPC++/C++ Compiler commands that target the three FPGA image types:

```
# FPGA emulator image
dpcpp -fintel_fpga -DFPGA_EMULATOR fpga_compile.cpp -o fpga_compile.fpga_emu

# FPGA early image (with optimization report): default board
dpcpp -fintel_fpga -Xhardware -fsycl-link=early fpga_compile.cpp -o fpga_compile_report.a

# FPGA early image (with optimization report): explicit board
dpcpp -fintel_fpga -Xhardware -fsycl-link=early -Xsboard=intel_sl0sx_pac:pac_sl0
fpga_compile.cpp -o fpga_compile_report.a

# FPGA hardware image: default board
dpcpp -fintel_fpga -Xhardware fpga_compile.cpp -o fpga_compile.fpga

# FPGA hardware image: explicit board
dpcpp -fintel_fpga -Xhardware -Xsboard=intel_sl0sx_pac:pac_sl0 fpga_compile.cpp -o
fpga_compile.fpga
```

The following table explains the compiler flags used in the above example commands:

#### FPGA Compilation Flags

Flag	Explanation
-fintel_fpga	Performs ahead-of-time (offline) compilation for FPGA.
-DFPGA_EMULATOR	Adds a preprocessor define (see code snippet above).
-Xhardware	Instructs the compiler to target FPGA hardware. If you omit this flag, the compiler targets the default FPGA target, which is FPGA emulator.  <b>NOTE</b> Using the prefix -Xs causes an argument to be passed to the FPGA backend.
-fsycl-link=early	Instructs the compiler to stop after creating the FPGA early image (and associated optimization report).
-Xsboard=<bsp:variant>	[Optional argument] Specifies the FPGA board variant and BSP. If omitted, the compiler chooses the default FPGA board variant <code>pac_a10</code> from the <code>intel_a10gx_pac</code> BSP. Refer to the <a href="#">FPGA BSPs and Boards</a> section for additional details.

#### Warning

The output of a `dpcpp` compile command overwrites the output of previous compiles that used the same output name. Therefore, Intel® recommends using unique output names (specified with `-o`). This is especially important for FPGA compilation since a lost hardware image may take hours to regenerate.

In addition to the compiler flags demonstrated by the commands above, there are flags to control the verbosity of the `dpcpp` command's output, the number of parallel threads to use during compilation, and so on. The following section briefly describes those flags.

#### Other SYCL FPGA Flags Supported by the Compiler

The Intel® oneAPI DPC++/C++ Compiler offers a list of options that allow you to customize the kernel compilation process. The following table summarizes other options supported by the compiler:



### Other Supported FPGA Flags

Option name	Description
<code>-fsycl-help=fpga</code>	Prints out FPGA-specific options for the <code>dpcpp</code> command.
<code>-fsycl-link=early</code> <code>-fsycl-link=image</code>	<ul style="list-style-type: none"> <li><code>-fsycl-link=early</code> is synonymous with <code>-fsycl-link</code>. Both instruct the compiler to stop after creating the FPGA early image (and the associated optimization report).</li> <li><code>-fsycl-link=image</code> is used in the device link compilation flow to instruct the compiler to generate the FPGA hardware image. Refer to the <a href="#">Fast Recompile for FPGA</a> section for additional information.</li> </ul>
<code>-reuse-exe=&lt;exe_file&gt;</code>	Instructs the compiler to extract the compiled FPGA hardware image from the existing executable and package it into the new executable, saving the device compilation time. This option is useful only when compiling for hardware. Refer to the <a href="#">Fast Recompile for FPGA</a> section for additional information.
<code>-Xsv</code>	FPGA backend generates a verbose output describing the progress of the compilation.
<code>-Xsemulator</code>	Generates an emulator device image. This is the default behavior.
<code>-Xsparallel=&lt;num_threads&gt;</code>	<p>Sets the degree of parallelism used in the FPGA bitstream compilation.</p> <p>The <code>&lt;num_threads&gt;</code> value specifies the number of parallel threads you want to use. The maximum recommended value is the number of available cores. Setting this flag is optional. The default behavior is for the Intel® Quartus® Prime software to compile in parallel on all available cores.</p>
<code>-Xsseed=&lt;value&gt;</code>	Sets the seed used by Intel® Quartus® Prime Software when generating the FPGA bitstream. The value must be an unsigned integer, and by default the value is 1.
<code>-Xsfast-compile</code>	Runs FPGA bitstream compilation with reduced effort. This option allows faster compile time but at a cost of reduced performance of the compiled FPGA hardware image. Use this flag only for faster development time. It is not intended for production quality results.

For more information about the FPGA optimization flags, refer to the [Optimization Flags](#) section in the *Intel oneAPI DPC++ FPGA Optimization Guide*.

### Device Selectors for FPGA

You must use the correct SYCL device selector in the host code, depending on whether you are targeting the FPGA emulator or FPGA hardware. The following host code snippet demonstrates how you can use a selector to specify the target device at compile time:

```
// FPGA device selectors are defined in this utility header, along with
// all FPGA extensions such as pipes and fpga_reg
#include <CL/sycl/INTEL/fpga_extensions.hpp>

int main() {
    // Select either:
    // - the FPGA emulator device (CPU emulation of the FPGA)
```

```
// - the FPGA device (a real FPGA)
#ifdef(FPGA_EMULATOR)
    INTEL::fpga_emulator_selector device_selector;
#else
    INTEL::fpga_selector device_selector;
#endif

    queue q(device_selector);
    ...
}
```

---

#### NOTE

- The FPGA emulator and the FPGA are different target devices. Intel® recommends using a preprocessor `define` to choose between the emulator and FPGA selectors. This makes it easy to switch between targets using only command-line flags. For example, the above code snippet can be compiled for the FPGA emulator by passing the flag `-DFPGA_EMULATOR` to the `dpcpp` command.
  - Since FPGAs support only the [ahead-of-time compilation method](#), dynamic selectors (such as the `default_selector`) are less useful than explicit selectors when targeting FPGA.
- 

#### Caution

When targeting the FPGA emulator or FPGA hardware, you must pass correct compiler flags and use the correct device selector in the host code. Otherwise, you might experience runtime failures. Refer to the [fpga\\_compile](#) tutorial in the [Intel® oneAPI Samples Browser](#) to get started with compiling SYCL code for FPGA.

---

## Fast Recompile for FPGA

The Intel® oneAPI DPC++/C++ Compiler supports only the ahead-of-time (AoT) compilation for FPGA hardware, which means that an FPGA device image is generated at compile time. The FPGA device image generation process can take hours to complete. If you make a change that is exclusive to the host code, then recompile only your host code by reusing the existing FPGA device image and circumventing the time-consuming device compilation process.

The Intel® oneAPI DPC++/C++ Compiler provides the following mechanisms to separate device code and host code compilation:

- Passing the `-reuse-exe=<exe_name>` flag to instruct the compiler to attempt to reuse the existing FPGA device image.
- Separating the host and device code into separate files. When a code change applies only to host-only files, the FPGA device image is not regenerated.

The following sections explain these two mechanisms in detail.

### Using the `-reuse-exe` Flag

If the device code and options affecting the device have not changed since the previous compilation, passing the `-reuse-exe=<exe_name>` flag instructs the compiler to extract the compiled FPGA hardware image from the existing executable and package it into the new executable, saving the device compilation time.

Sample use:

```
# Initial compilation
dpcpp -fintel_fpga -Xshardware <files.cpp> -o out.fpga
```

The initial compilation generates an FPGA device image, which takes several hours. Suppose you now make some changes to the host code.

```
# Subsequent recompilation
dpcpp <files.cpp> -o out.fpga -reuse-exe=out.fpga -Xshardware -fintelfpga
```

One of the following actions are taken by the command:

- If the `out.fpga` file does not exist, the `-reuse-exe` flag is ignored and the FPGA device image is regenerated. This is always the case the first time you compile a project.
- If the `out.fpga` file is found, the compiler verifies no change that affect the FPGA device code is made since the last compilation. If no change is detected in the device code, the compiler then reuses the existing FPGA device image and recompiles only the host code. The recompilation process takes a few minutes to complete.
- If the `out.fpga` file is found, but the compiler cannot prove that the FPGA device code will yield a result identical to the last compilation, a warning is printed and the FPGA device code is fully recompiled. Since the compiler checks must be conservative, spurious recompilations can sometimes occur when using the `-reuse-exe` flag.

### Using the Device Link Method

Suppose the program is separated into two files, `main.cpp` and `kernel.cpp`, where only the `kernel.cpp` file contains the device code.

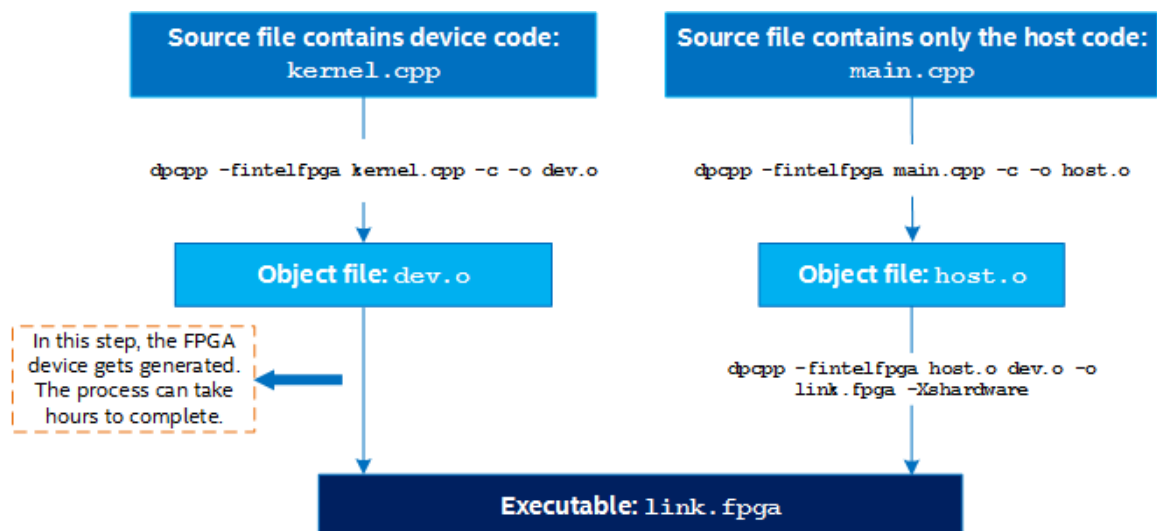
In the normal compilation process, FPGA device image generation happens at link time.

```
# normal compile command
dpcpp -fintelfpga -Xshardware main.cpp kernel.cpp -o link.fpga
```

As a result, any change to either the `main.cpp` or `kernel.cpp` triggers the regeneration of an FPGA hardware image.

The following graph depicts this compilation process:

### Compilation Process



If you want to iterate on the host code and avoid long compile time for your FPGA device, consider using a device link to separate the device and host compilation:

```
# device link command
dpcpp -fintelfpga -fsycl-link=image <input files>[options]
```

The compilation is a three-step process as listed in the following:

1. Compile the device code.

```
dpcpp -fintelfpga -Xshardware -fsycl-link=image kernel.cpp -o dev_image.a
```

Input files must include all files that contain the device code. This step might take several hours to complete.

2. Compile the host code.

```
dpcpp -fintelfpga main.cpp -c -o host.o
```

Input files should include all source files that contain only the host code. These files must not contain any source code that executes on the device but may contain setup and tear-down code, for example, parsing command line options and reporting results. This step takes seconds to complete.

3. Create the device link.

```
dpcpp -fintelfpga host.o dev_image.a -o fast_recompile.fpga
```

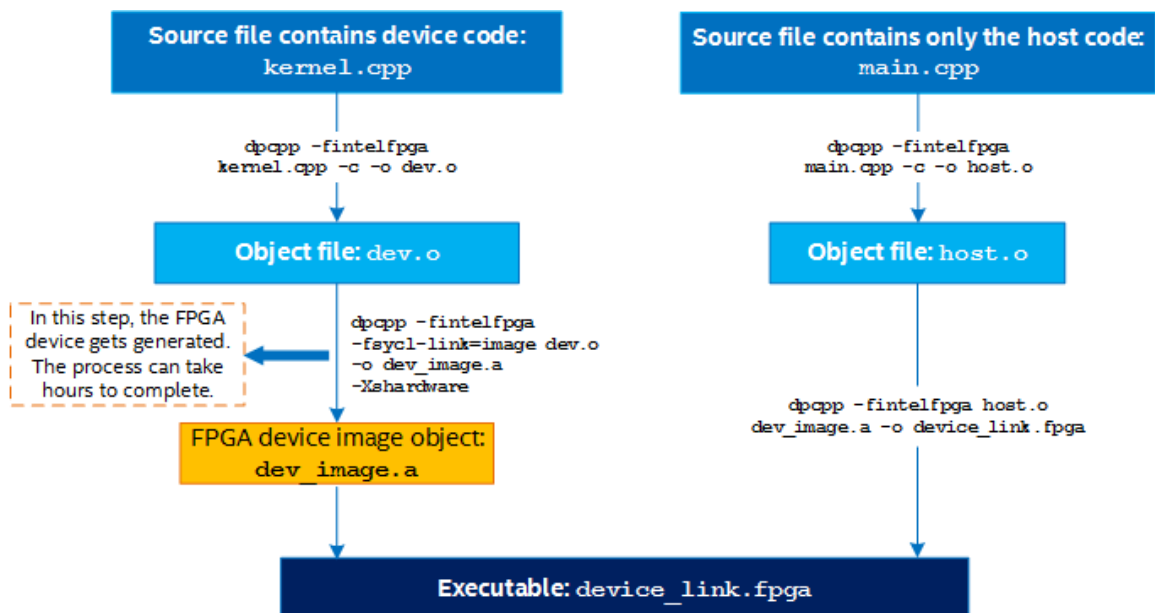
This step takes seconds to complete. The input should include one or more host object files (.o) and exactly one device image file (.a). When linking a static library (.a file), always include the static library after its use. Otherwise, the library's functions are discarded. For additional information about static library linking, refer to [Library order in static linking](#).

#### NOTE

You only need to perform steps 2 and 3 when modifying host-only files.

The following diagram illustrates the device link process:

#### FPGA Device Link Process



Refer to the [fast\\_recompile](#) tutorial in the [Intel® oneAPI Samples Browser](#) for an example using the device link method.

### Which Mechanism to Use?

Of the two mechanisms described above, the `-reuse-exe` flag mechanism is easier to use than the device link mechanism. The flag also allows you to keep your host and device code as a single source, which is preferred for small programs. For larger and more complex projects, the device link method has the advantage of giving you more control over the compiler's behavior.

However, there are some drawbacks of the `-reuse-exe` flag when compared to compiling separate files. Consider the following when using the `-reuse-exe` flag:

- The compiler must spend time partially recompiling and then analyzing the device code to ensure that it is unchanged. This takes several minutes for larger designs. Compiling separate files does not incur this extra time.
- You might occasionally encounter a *false positive* where the compiler incorrectly believes that it must recompile your device code. In a single source file, the device and host code are coupled, so certain changes to the host code can change the compiler's view of the device code. The compiler always behaves conservatively and triggers a full recompilation if it cannot prove that reusing the previous FPGA binary is safe. Compiling separate files eliminates this possibility.

### Generate Multiple FPGA Images (Linux only)

Use this feature of the Intel® oneAPI DPC++/C++ Compiler when you want to split your FPGA compilation into different FPGA images. This feature is particularly useful when your design does not fit on a single FPGA. You can use it to split your very large design into multiple smaller images, which you can use to partially reconfigure your FPGA device.

You can split your design using one of the following approaches, each giving you different benefits:

- Dynamic Linking Flow
- Dynamic Loading Flow

Between the two flows, dynamic linking is easier to implement than dynamic loading. However, dynamic linking can require more memory on the host device as all of the device images must be loaded into memory. Dynamic loading addresses these limitations, but introduces the need for some extra source-level changes. The following comparison table highlights the differences between the flows:

	Dynamic Linking	Dynamic Loading
Can dynamically change FPGA Image at runtime?	Yes	Yes
Defining type and number of FPGA images	At compile time	At runtime
Host-program memory footprint	All FPGA images are stored in memory at runtime.	Only explicitly loaded FPGA images are stored in memory.
Calling host code	Call function in the dynamic library directly.	Explicitly load the dynamic library and functions to call.

### Dynamic Linking Flow

This flow allows you to split your design by different source files and map each of them into a separate FPGA image. Intel® recommends this flow for designs with a small number of FPGA images.

To use this flow, perform the following steps:

1. Split your source code such that for each FPGA image you want, you create a separate `.cpp` file that submits various kernels. Separate the host code into one or more `.cpp` files that can then interface with functions in the kernel files.

Consider that you now have the following three files:

- `main.cpp` containing your host code. For example:

```
// host.cpp
int main() {
    queue queueA;
    add(queueA);
    mul(queueA);
}
```

- `vector_add.cpp` containing a function that submits the `vector_add` kernel. For example:

```
// vector_add.cpp
extern "C"{
    void add(queue queueA) {
        queue.submit(
            // Kernel Code
        );
    }
}
```

- `vector_mul.cpp` containing a function that submits the `vector_mul` kernel. For example:

```
// vector_mul.cpp
extern "C"{
    void mul(queue queueA) {
        queue.submit(
            // Kernel Code
        );
    }
}
```

## 2. Compile the source files using the following commands:

```
dpcpp -fPIC -fintelfpga -c vector_add.cpp -o vector_add.o
dpcpp -fPIC -fintelfpga -c vector_mul.cpp -o vector_mul.o

# FPGA image compiles take a long time to complete
dpcpp -fPIC -shared -fintelfpga vector_add.o -o vector_add.so -Xshardware -Xsboard=pac_a10
dpcpp -fPIC -shared -fintelfpga vector_mul.o -o vector_mul.so -Xshardware -Xsboard=pac_a10

# Final link step
dpcpp -o main.exe main.cpp vector_add.so vector_mul.so
```

With this flow, the long FPGA compile steps are split into separate commands, that you can potentially run on different systems or only when you change the files.

## Dynamic Loading Flow

Use this flow if you want to avoid loading all of the different FPGA images into memory at once. Similar to dynamic linking flow, this flow also requires you to split your code. However, for this flow, you must load the `.so` (shared object) files in the host program. The advantage of this flow is that you can load large FPGA images files dynamically as necessary instead of linking all of the image files at compile time.

To use this flow, perform the following steps:

1. Split your source code in the same manner as done in [step 1 of the dynamic linking flow](#).
2. Modify the `host.cpp` file to appear as follows:

```
// host.cpp
#include <dlfcn.h>

int main() {
```

```

queue queueA;
bool runAdd, runMul;
// Assuming runAdd and runMul are set dynamically at runtime
if (runAdd) {
    auto add_lib = dlopen("./add.so", RTLD_NOW);
    auto add = dlsym(add_lib, "add");
    add(queueA);
}
if (runMul) {
    mul_lib = dlopen("./mul.so", RTLD_NOW);
    mul = dlsym(mul_lib, "mul");
    mul(queueA);
}
}

```

### 3. Compile the source files using the following commands:

#### NOTE

You do not have to link the `.so` files at compile time since they are loaded dynamically at runtime.

```

dpcpp -fPIC -fintelfpga -c vector_add.cpp -o vector_add.o
dpcpp -fPIC -fintelfpga -c vector_mul.cpp -o vector_mul.o

# FPGA Image compiles take a long time to complete
dpcpp -fPIC -shared -fintelfpga vector_add.o -o vector_add.so -Xshardware -Xsboard=pac_a10
dpcpp -fPIC -shared -fintelfpga vector_mul.o -o vector_mul.so -Xshardware -Xsboard=pac_a10

# Final link step. Ensure you add the path containing the .so files to LD_LIBRARY_PATH
LD_LIBRARY_PATH=./:$LD_LIBRARY_PATH dpcpp -o main.exe main.cpp vector_add.so vector_mul.so

```

With this approach, you can arbitrarily load many `.so` files at runtime as required. This is useful when you have a large library of FPGA images and you want to select a subset of files from it.

## FPGA BSPs and Boards

As mentioned earlier in [Types of DPC++ FPGA Compilation](#), generating an FPGA hardware image requires the [Intel® FPGA Add-On for oneAPI Base Toolkit](#), which provides the Intel® Quartus® Prime Software that maps your design from RTL to the FPGA's primitive hardware resources. Additionally, this add-on package provides basic Board Support Packages (BSPs) that can be used to compile to FPGA hardware.

### What is a Board?

Similar to a GPU, an FPGA is an integrated circuit that must be mounted onto a card or a board to interface with a server or a desktop computer. In addition to the FPGA, the board provides memory, power, and thermal management, and physical interfaces to allow the FPGA to communicate with other devices.

### What is a BSP?

A BSP consists of software layers and an FPGA hardware scaffold design that makes it possible to target the FPGA through the Intel® oneAPI DPC++/C++ Compiler. The FPGA design generated by the compiler is stitched into the framework provided by the BSP.

## What is Board Variant?

A BSP can provide multiple board variants, that support different functionality. For example, the `intel_s10sx_pac` BSP contains two variants that differ in their support for Unified Shared Memory (USM). For additional information about USM, refer to the [Unified Shared Memory](#) topic in the *Intel® oneAPI DPC++/C++ Compiler Developer Guide and Reference*.

### NOTE

A board can be supported by more than one BSP and a BSP might support more than one board variant.

The Intel® FPGA Add-On for oneAPI Base Toolkit provides BSPs for two boards and board variants provided by these BSPs can be selected using the following flags in your `dpcpp` command:

Board	BSP	Flag	USM Support
Intel® Programmable Acceleration Card (PAC) with Intel® Arria® 10 GX FPGA	<code>intel_a10gx_pac</code>	<code>-Xsboard=intel_a10gx_pac:pac_a10</code>	Explicit USM
Intel® FPGA Programmable Acceleration Card (PAC) D5005  (previously known as Intel® PAC with Intel® Stratix® 10 SX FPGA)	<code>intel_s10sx_pac</code>	<code>-Xsboard=intel_s10sx_pac:pac_s10</code>	Explicit USM
		<code>-Xsboard=intel_s10sx_pac:pac_s10_usm</code>	Explicit USM Restricted USM

### NOTE

- The Intel® oneAPI DPC++/C++ Compiler (part of the Intel® oneAPI Base Toolkit) provides partial BSPs sufficient for generating the FPGA early image and optimization report. In contrast, the Intel® FPGA Add-On for oneAPI Base Toolkit provides full BSPs, which are necessary for generating the FPGA hardware image.
- When running a DPC++ executable on an FPGA board, you must ensure that you have initialized the FPGA board for the board variant that the executable is targeting. For information about initializing an FPGA board, refer to [FPGA Board Initialization](#).
- For information about FPGA optimizations possible with Restricted USM, refer to [Prepinning](#) and [Zero-Copy Memory Access](#) topics in the *Intel® oneAPI DPC++ FPGA Optimization Guide*.

## Custom BSPs

In addition to the BSPs described above, you can also use custom BSPs provided by a board vendor. Follow these steps to use the Intel® oneAPI DPC++/C++ Compiler with a custom BSP:

1. Install the Intel® FPGA Add-On for Intel® Custom Platform package that contains the version of Intel® Quartus® Prime Software required by the custom BSP. Refer to the detailed instructions in the [Intel oneAPI Toolkits Installation Guide](#).
2. Place the full custom BSP in the `intelfpgadpcpp/latest/board` directory of the add-on installation.
3. Follow all installation instructions provided by the BSP vendor.



## FPGA Board Initialization

Before you run a DPC++ executable containing an FPGA hardware image, you must initialize the FPGA board using the following command:

```
aoclinitialize<board id> <board variant>
```

where:

Parameter	Description
<board_id>	Board ID obtained from the <code>aocl diagnose</code> command. For example, <code>ac10</code> , <code>ac11</code> , and so on.
<board variant>	Name of the board variant as specified by the <code>-Xsboard</code> flag the DPC++ executable was compiled with. For example, <code>pac_s10_usm</code> .

For example, consider that you have a single Intel® Programmable Acceleration Card (PAC) D5005 (previously known as *Intel® Programmable Acceleration Card (PAC) with Intel® Stratix® 10 SX*) on your system and you compile the DPC++ executable using the following command:

```
dpcpp -fintel_fpga -Xhardware -Xsboard=intel_s10sx_pac:pac_s10_usm kernel.cpp
```

In this case, you must initialize the board using the following command:

```
aocl initialize ac10 pac_s10_usm
```

Once this is complete, you can run the DPC++ executable without initializing the board again, unless you are doing one of the following:

- Running a DPC++ workload for the first time after power cycling the host.
- Running a DPC++ workload after running a non-DPC++ workload on the FPGA.
- Running a DPC++ workload compiled with a different board variant in `-Xsboard` flag.

## Targeting Multiple Homogeneous FPGA Devices

The Intel® oneAPI DPC++/C++ Compiler supports targeting multiple homogeneous FPGA devices from a single host CPU. This gives you the opportunity to improve your design's throughput by parallelizing the execution of your program on multiple FPGAs. parallelizing the execution of your program on multiple FPGAs. .

Intel® recommends creating a single context with multiple device queues because with multi-context, buffers at OpenCL layer must be copied between contexts and this introduces overhead and impacts overall performance. However, you can use multi-context if your design is simple and the overhead has no effect on the overall performance.

Follow one of the following methods to target multiple FPGA devices:

### Create a Single Context with Multiple Device Queues

Perform the following steps to target multiple FPGA devices with a single context:

1. Create a single SYCL context to encapsulate a collection of FPGA devices of the same platform.

```
context ctxt(deviceList, &m_exception_handler);
```

2. Create a SYCL queue for each FPGA device.

```
std::vector<queue> queueList;
for (unsigned int i = 0; i < ctxt.get_devices().size(); i++) {
    queue newQueue(ctxt, ctxt.get_devices()[i], &m_exception_handler);
    queueList.push_back(newQueue);
}
```

3. Submit either the same or different device codes to all available FPGA devices. If you want to target a subset of all available devices, then you must first perform device selection to filter out unwanted devices.

```
for (unsigned int i = 0; i < queueList.size(); i++) {
    queueList[i].submit([&](handler& cgh) {...});
}
```

### Create a Context For Each Device Queue (Multi-Context)

Perform the following steps to target multiple FPGA devices with multiple contexts:

1. Obtain a list of all available FPGA devices. Optionally, you can select a device based on the device member or device property. For device properties such as device name, use the member function `get_info()` const with the desired device property.

```
std::vector<device> deviceList = device::get_devices();
```

2. Create a SYCL queue for each FPGA device.

```
std::vector<queue> queueList;
for (unsigned int i = 0; i < deviceList.size(); i++) {
    queue newQueue(deviceList[i], &m_exception_handler);
    queueList.push_back(newQueue);
}
```

3. Submit either the same or different device codes to all available FPGA devices. If you want to target a subset of all available devices, then you must first perform device selection to filter out unwanted devices.

```
for (unsigned int i = 0; i < queueList.size(); i++) {
    queueList[i].submit([&](handler& cgh) {...});
}
```

### Limitations

Consider the following limitations when targeting multiple FPGA devices:

- All FPGA devices use the same FPGA bitstream.
- All FPGA devices used must be of the same FPGA card (same `-Xsboard target`)

### Targeting Multiple Platforms

To compile a design that targets multiple target device types (using different device selectors), you can run the following commands:

### Emulation Compile

For compiling your SYCL code for FPGA emulator target, execute the following commands:

```
dpcpp -fsycl-targets=spir64-unknown-unknown-sycldevice \
jit_kernel.cpp -c -o jit_kernel.o

dpcpp -DFPGA_EMULATOR \
-fsycl-targets=spir64_fpga-unknown-unknown-sycldevice fpga_kernel.cpp \
-c -o fpga_kernel.o

dpcpp -DFPGA_EMULATOR \
-fsycl-targets=spir64_fpga-unknown-unknown-sycldevice,spir64-unknown-unknown-sycldevice main.cpp
jit_kernel.o fpga_kernel.o -o emulator.out
```

The design uses libraries and includes an FPGA kernel (AOT flow) and a CPU kernel (JIT flow).

Specifically, there should be a main function residing in the `main.cpp` file and two kernels for both CPU (`jit_kernel.cpp`) and FPGA (`fpga_kernel.cpp`).

Sample `jit_kernel.cpp` file:

```
sycl::cpu_selector device_selector;
queue deviceQueue(device_selector);

deviceQueue.submit([&](handler &cgh) {
    // CPU Kernel function
});
```

Sample `fpga_kernel.cpp` file:

```
#ifdef FPGA_EMULATOR
INTEL::fpga_emulator_selector device_selector;
#else
INTEL::fpga_selector device_selector;
#endif
queue deviceQueue(device_selector);

deviceQueue.submit([&](handler &cgh) {
    // FPGA Kernel Function
});
```

## FPGA Hardware Compile

To compile for the FPGA hardware target, add the `-Xshardware` flag and remove the `-DFPGA_EMULATOR` flag, as follows:

```
dpcpp -fsycl-targets=spir64-unknown-unknown-sycldevice \
jit_kernel.cpp -c -o jit_kernel.o

dpcpp -fsycl-targets=spir64_fpga-unknown-unknown-sycldevice \
fpga_kernel.cpp -c -o fpga_kernel.o

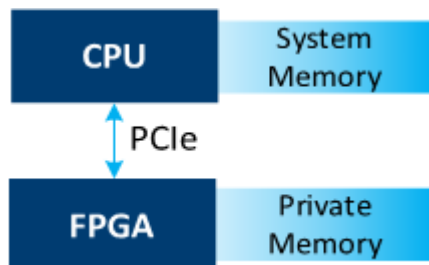
dpcpp -fintel-fpga main.cpp jit_kernel.o fpga_kernel.o -Xshardware
```

## FPGA-CPU Interaction

One of the main influences on the overall performance of an FPGA design is how kernels executing on the FPGA interact with the host on the CPU.

### Host and Kernel Interaction

FPGA devices typically communicate with the host (CPU) via [PCIe](#).



This is an important factor influencing the performance of SYCL programs targeting FPGAs. Furthermore, the first time a particular DPC++ program is run, the FPGA must be configured with its hardware bitstream, and this may require several seconds.

## Data Transfer

Typically, the FPGA board has its own private [DDR](#) memory on which it primarily operates. The CPU must bulk transfer or [dynamic memory access](#) (DMA) all data that the kernel needs to access into the FPGA's local DDR memory. After the kernel completes its operations, results must be transferred over DMA back to the CPU. The transfer speed is bound by the PCIe link itself, as well as the efficiency of the DMA solution. For example, the Intel® PAC with Intel® Arria® 10 GX FPGA has a PCIe Gen 3 x 8 link, and transfers are typically limited to 6-7 GB/s.

The following are the techniques to manage these data transfer times:

- DPC++ allows buffers to be tagged as read-only or write-only, which allows some unnecessary transfers to be eliminated.
- Improve the overall system efficiency by maximizing the number of concurrent operations. Since PCIe supports simultaneous transfers in opposite directions and PCIe transfers do not interfere with kernel execution, techniques such as double buffering can be applied. Refer to the [Double Buffering Host Utilizing Kernel Invocation Queue](#) topic in the *Intel oneAPI DPC++ FPGA Optimization Guide* and the [double\\_buffering](#) tutorial for additional information about these techniques.
- Improve data transfer throughput by prepinning system memory on board variants that support Restricted USM. Refer to the [Prepinning](#) topic in the *Intel oneAPI DPC++ FPGA Optimization Guide* for additional information.

## Configuration Time

You must program the hardware bitstream on the FPGA device in a process called configuration. Configuration is a lengthy operation requiring several seconds of communication with the FPGA device. The SYCL runtime manages configuration for you, automatically. The runtime decides when the configuration occurs. For example, configuration might be triggered when a kernel is first launched, but subsequent launches of the same kernel may not trigger configuration since the bitstream has not changed. Therefore, during development, Intel® recommends to time the execution of the kernel after the FPGA has been configured, for example, by performing a warm-up execution of the kernel before timing kernel execution. You must remove this warm-up execution in the production code.

## Multiple Kernel Invocations

If a SYCL program submits the same kernel to a SYCL queue multiple times (for example, by calling `single_task` within a loop), only one kernel invocation is active at a time. Each subsequent invocation of the kernel waits for the previous run of the kernel to complete.

## See Also

[Intel® oneAPI DPC++ FPGA Optimization Guide](#)

[Intel® Programmable Acceleration Card with Intel® Arria® 10 GX FPGA](#)

[Intel® FPGA Programmable Acceleration Card \(PAC\) D5005](#)

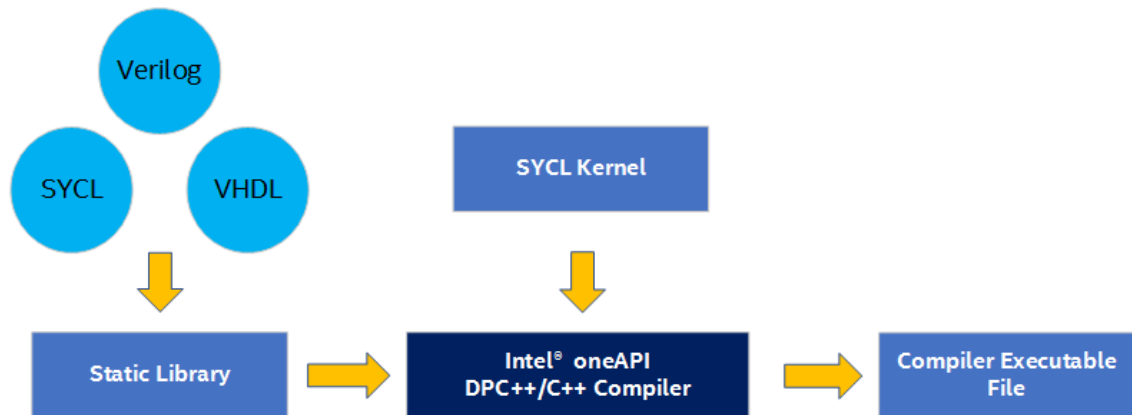
## FPGA Performance Optimization

The preceding FPGA flow covered the basics of compiling DPC++ for FPGA, but there is still much to learn about improving the performance of your designs. The Intel® oneAPI DPC++/C++ Compiler provides tools that you can use to find areas for improvement, and a variety of flags, attributes, and extensions to control design and compiler behavior. You can find all these information in the [Intel® oneAPI DPC++ FPGA Optimization Guide](#), which should be your main reference if you want to understand how to optimize your design.

## Use of Static Library for FPGA

A static library is a single file that contains multiple functions. You can create a static library file using SYCL, OpenCL, High-Level Synthesis (HLS) sources, or register transfer level (RTL). You can then include this library file and use the functions inside your SYCL kernels.

If you develop your library function in HLS, then for more information, refer to [Intel® High Level Synthesis Compiler: Reference Manual](#).



You may use a third-party library or create your own library. To use a static library, you do not require in-depth knowledge in hardware design or in the implementation of library primitives.

To generate libraries that you can use with SYCL, you need to create the following files:

### Generating Libraries for Use with SYCL

File or Component	Description
<b>RTL Modules</b>	
RTL source files	Verilog, System Verilog, or VHDL files that define the RTL component. Additional files such as Intel® Quartus® Prime IP File (.qip), Synopsys Design Constraints File (.sdc), and Tcl Script File (.tcl) are not allowed.
eXtensible Markup Language File (.xml)	Describes the properties of the RTL component. The Intel® oneAPI DPC++/C++ Compiler uses these properties to integrate the RTL component into the SYCL pipeline.
Header file (.hpp)	A header file that contains valid SYCL kernel language and declares the signatures of functions that are implemented by the RTL component.
Emulation model file (OpenCL or HLS-based)	Provides C or C++ model for the RTL component that is used only for emulation. Full hardware compilations use the RTL source files.
<b>SYCL Functions</b>	
SYCL source files (.cpp)	Contains definitions of the SYCL functions. These functions are used during emulation and full hardware compilations.
Header file (.hpp)	A header file describing the functions to be called from SYCL in the SYCL syntax.
<b>OpenCL Functions</b>	

File or Component	Description
OpenCL source files (.cl)	Contains definitions of the OpenCL functions. These functions are used during emulation and full hardware compilations.
Header file (.hpp)	A header file describing the functions to be called from SYCL in the SYCL syntax.
<b>HLS Functions</b>	
HLS source files (.cpp)	Contains definitions of the HLS functions. These functions are used during emulation and full hardware compilations.
Header file (.hpp)	A header file describing the functions to be called from SYCL in the SYCL syntax.

**NOTE**

There is no difference in the header file used for RTL and other library functions. A single library can contain any of the supported sources. You can create a library from mixed sources (SYCL, OpenCL, HLS or RTL) and target these products:

- Intel® oneAPI DPC++/C++ Compiler
- Intel® FPGA SDK for OpenCL Offline Compiler
- Intel® HLS Compiler

The format of the library files is determined by which operating system you compile your source code on, with additional sections that carry additional library information.

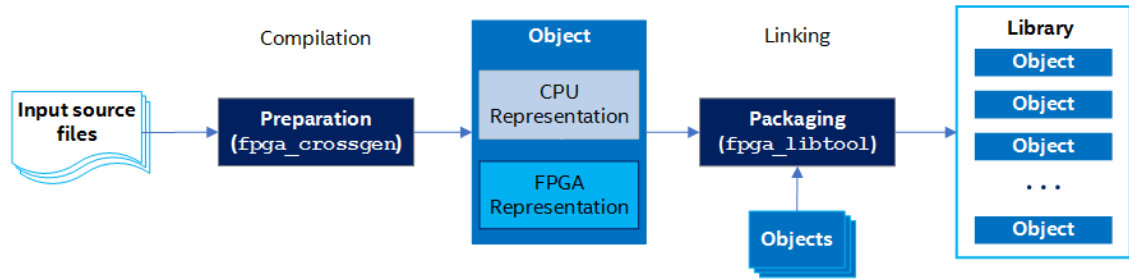
- On Linux\* platforms, a library is a .a archive file that contains .o object files.
- On Windows\* platforms, a library is a .lib archive file that contains .obj object files.

You can call the functions in the library from your kernel without the need to know the hardware design or the implementation details of the underlying functions in the library. Add the library to the `dpcpp` command line when you compile your kernel.

Creating a library is a two-step process:

1. Each object file is created from an input source file using the `fpga_crossgen` command.
  - An object file is effectively an intermediate representation of your source code with both a CPU representation and an FPGA representation of your code.
  - An object can be targeted for use with only one Intel® high-level design product. If you want to target more than one high-level design product, you must generate a separate object for each target product.
2. Object files are combined into a library file using the `fpga_libtool` command. Objects created from different types of source code can be combined into a library, provided all objects target the same high-level design product.

A library is automatically assigned a toolchain version number, and can be used only with the targeted high-level design product with the same version number.



## Create Library Objects From Source Code

You can create a library from object files from your source code. A SYCL-based object file includes code for CPU as well as hardware execution of CPU capturing for use in host and emulation of kernel.

A library can contain multiple object files. You can create object files for use in different high-level design tools from the same source code. Depending on the target high-level design tool, your source code might require adjustments to support tool-specific data types or constructs.

Product	Description
Intel® oneAPI DPC++/C++ Compiler Intel® FPGA SDK for OpenCL Offline Compiler	No additional work is needed in your SYCL and OpenCL source code when you use the code to create objects for the compiler libraries.
Intel® HLS Compiler	<p>SYCL supports language constructs that are not natively supported by C++. Your component might need modifications to support those constructs. It is always preferred to use SYCL data types as library function call parameters.</p> <hr/> <p><b>Restriction</b></p> <p>You cannot use systems of tasks in components intended for use in a SYCL library object.</p> <hr/>

## Create an Object File From Source Code

Use the `fpga_crossgen` command to create library objects from your source code. An object created from your source code contains information required both for emulating the functions in the object and synthesizing the hardware for the object functions.

The `fpga_crossgen` command creates one object file from one input source file. The object created can be used only in libraries that target the same high-level design tool. Also, objects are versioned. That is, each object is assigned a compiler version number and be used only with high-level design tools with the same version number.

Create a library object using the following command:

```
fpga_crossgen <source_file> [--source {sycl|ocl|hls}]
--target {sycl|ocl|hls} [-o <object_file>]
```

The following table describes the parameters:

Parameter	Description
<source_file>	You can use SYCL, OpenCL, HLS, and RTL source code files.

Parameter	Description
<code>--source</code>	Optional flag. It supports <code>sycl</code> , <code>hls</code> , and <code>ocl</code> options. <ul style="list-style-type: none"> <li>When the source file ends in <code>.cpp</code>, the flag defaults to <code>hls</code>.</li> <li>When the source file ends in <code>.cl</code>, the flag defaults to <code>ocl</code>.</li> <li>For RTL source file, the <code>--source</code> flag refers to the emulation model.</li> </ul>
<code>--target</code>	Targets a Intel® high-level design tool ( <code>sycl</code> , <code>ocl</code> , and <code>hls</code> ) for the library. The objects are combined as object files into a SYCL library archive file using the <code>fpga_libtool</code> .
<code>-o</code>	Optional flag. This options helps you specify an object file name. If you do not specify this option, the object file name defaults to be the same name as the source code file name but with an object file suffix ( <code>.o</code> or <code>.obj</code> ).

Example commands:

```
fpga_crossgen lib_sycl.cpp --source sycl --target sycl -o lib_sycl.o
```

```
fpga_crossgen lib_rtl_spec.xml --emulation_model lib_rtl_model.cpp --source sycl --target sycl -o lib_rtl.o
```

```
fpga_crossgen lib_hls.cpp --source hls --target sycl -o lib_hls.o
```

```
fpga_crossgen lib_ocl.cl --source ocl --target sycl -o lib_ocl.o
```

## Packaging Object Files into a Library File

Gather the object files into a library file so that others can incorporate the library into their projects and call the functions that are contained in the objects in the library. To package object files into a library, use the `fpga_libtool` command.

Before you package object files into a library, ensure that you have the path information for all of the object files that you want to include in the library.

All objects that you want to package into a library must have the same version number. The `fpga_libtool` command creates libraries encapsulated in operating system-specific archive files (`.a` on Linux\* and `.lib` on Windows\*). You cannot use libraries created on one operating system with an Intel® high-level design product running on a different operating system.

Create a library file using the following command:

```
fpga_libtool file1 file2 ... fileN --target (sycl|ocl|hls) --create <library_name>
```

The command parameters are defined as follows:

Parameter	Description
<code>file1 file2 ... fileN</code>	You can specify one or more object files to include in the library.
<code>--target (sycl ocl hls)</code>	Target this library for kernels developed. When you mention the <code>sycl</code> option, <code>--target</code> prepares the library for use with the Intel® oneAPI DPC++/C++ Compiler.
<code>--create &lt;library_name&gt;</code>	Allows you to specify the name of the library archive file. Specify the file extension of the library file as <code>.a</code> for Linux-platform libraries.

Example command:

```
fpga_libtool lib_hls.o lib_ocl.o lib_rtl.o lib_sycl.o --target sycl --create lib.a
```



where, the command packages objects created from HLS, OpenCL, RTL, and SYCL source code into a SYCL library called `lib.a`.

---

**Tip**

For additional information, refer to the FPGA tutorial sample "Use Library" listed in the [Intel® oneAPI Samples Browser on Linux\\*](#) or [Intel® oneAPI Samples Browser on Windows\\*](#).

---

## Using Static Libraries

You can include static libraries in your compiler command along with your source files, as shown in the following command:

```
dpcpp -fintelfpga main.cpp lib.a
```

## Restrictions and Limitations in RTL Support

When creating your RTL module for use inside SYCL kernels, ensure that the RTL module operates within the following restrictions:

- An RTL module must use a single input Avalon® streaming interface. That is, a single pair of ready and valid logic must control all the inputs. You have the option to provide the necessary Avalon® streaming interface ports but declare the RTL module as stall-free. In this case, you do not have to implement proper stall behavior because the Intel® oneAPI DPC++/C++ Compiler creates a wrapper for your module. Refer to [Object Manifest File Syntax of an RTL Module](#) for additional information.

---

**NOTE**

You must handle `invalid` signals properly if your RTL module has an internal state. Refer to [Stall-Free RTL](#) for more information.

---

- The RTL module must work correctly regardless of the kernel clock frequency.
- RTL modules cannot connect to external I/O signals. All input and output signals must come from a SYCL kernel.
- An RTL module must have a `clock` port, a `resetsn` port, and Avalon® streaming interface input and output ports (that is, `invalid`, `ovvalid`, `iready`, `oready`). Name the ports as specified here.
- RTL modules that communicate with external memory must have Avalon® memory-mapped interface port parameters that match the corresponding Custom Platform parameters. The Intel® oneAPI DPC++/C++ Compiler does not perform any width or burst adaptation.
- RTL modules that communicate with external memory must behave as follows:
  - They cannot burst across the burst boundary.
  - They cannot make requests every clock cycle and stall the hardware by monopolizing the arbitration logic. An RTL module must pause its requests regularly to allow other load or store units to execute their operations.
- RTL modules cannot act as stand-alone SYCL kernels. RTL modules can only be helper functions and be integrated into a SYCL kernel during kernel compilation.
- Every function call that corresponds to RTL module instantiation is completely independent of other instantiations. There is no hardware sharing.
- Do not incorporate kernel code into a SYCL library file. Incorporating kernel code into the library file causes the offline compiler to issue an error message. You may incorporate helper functions into the library file.
- An RTL component must receive all its inputs at the same time. A single `invalid` input signifies that all inputs contain valid data.
- You can only set RTL module parameters in the `<RTL module description file name>.xml` specification file and not in the SYCL kernel source file. To use the same RTL module with multiple parameters, create a separate `FUNCTION` tag for each parameter combination.
- You can only pass data inputs to an RTL module by value via the SYCL kernel code. Do not pass data inputs to an RTL module via pass-by reference, structs, or channels. In the case of channel data, pass the extracted scalar data.

**NOTE**

Passing data inputs to an RTL module via pass-by reference or structs causes a fatal error to occur in the offline compiler.

- The debugger (for example, GDB for Linux) cannot step into a library function during emulation if the library is built without the debug information. However, irrespective of whether the library is built with or without the debug data, optimization and area reports are not mapped to the individual code line numbers inside a library.
- Names of RTL module source files cannot conflict with the file names of Intel® oneAPI DPC++/C++ Compiler IP. Both the RTL module source files and the compiler IP files are stored in the `<kernel file name>/system/synthesis/submodules` directory. Naming conflicts causes existing compiler IP files in the directory to be overwritten by the RTL module source files.
- The compiler does not support `.qip` files. You must manually parse nested `.qip` files to create a flat list of RTL files.

**Tip**

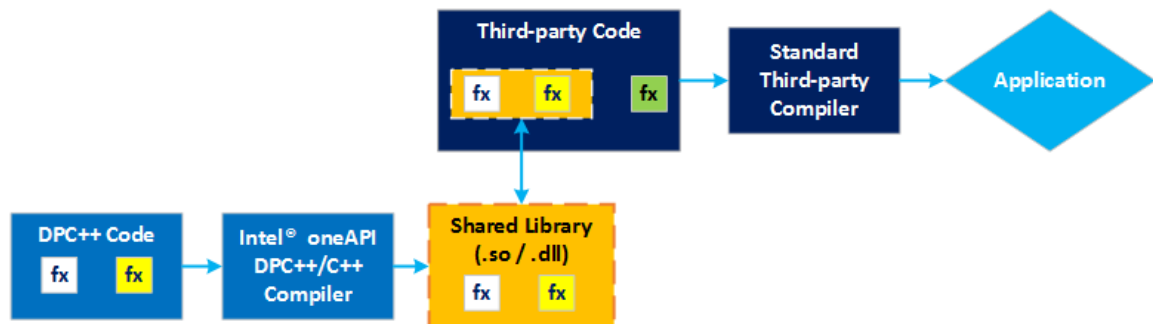
It is very difficult to debug an RTL module that works correctly on its own but works incorrectly as part of a SYCL kernel. Double check all parameters under the `ATTRIBUTES` element in the `<RTL object manifest file name>.xml` file.

- All compiler area estimation tools assume that RTL module area is 0. The compiler does not currently support the capability of specifying an area model for RTL modules.

## Use DPC++ Shared Library With Third-Party Applications

Use the Intel® oneAPI DPC++/C++ Compiler to compile your DPC++ code to a C-standard shared library (`.so` file on Linux and `.dll` file on Windows). You can then call this library from other third-party code to access a broad base of accelerated functions from your preferred programming language.

### DPC++ Functions Packaged into a Shared Library File For Use in Third-party Applications



To use a DPC++ shared library with a third-party application, perform these steps:

1. [Define the Shared Library Interface](#)
2. [Generate the Shared Library File in Linux](#) or [Generate the Shared Library File in Windows](#)
3. [Use the Shared Library](#)

## Define the Shared Library Interface

Intel® recommends defining an interface between the C-standard shared library and your DPC++ code. The interface must include functions you want to export and how those functions interface with your DPC++ code. Prefix the functions that you want to include in the shared library with `extern "C"`.

### NOTE

If you do not prefix with `extern "C"`, then the functions appear with mangled names in the shared library.

Consider the following example code of the `vector_add` function:

```
extern "C" int vector_add(int *a, int *b, int **c, size_t vector_len) {

    // Create device selector for the device of your interest.
    #if FPGA_EMULATOR
        // DPC++ extension: FPGA emulator selector on systems without an FPGA card.
        INTEL::fpga_emulator_selector d_selector;
    #elif FPGA
        // DPC++ extension: FPGA selector on systems with an FPGA card.
        INTEL::fpga_selector d_selector;
    #else
        // The default device selector selects the most performant device.
        default_selector d_selector;
    #endif

    try {
        queue q(d_selector, exception_handler);

        // DPC++ code interface:
        // Vector addition in DPC++
        VectorAddKernel(q, a, b, c, vector_len);
    } catch (exception const &e) {
        std::cout << "An exception is caught for vector add.\n";
        return -1
    }

    return 0;
}
```

## Generate the Shared Library File in Linux

If you are using a Linux system, then perform these steps to generate the shared library file:

1. Compile the DPC++ device code separately.

```
dpcpp -fPIC -fintelfpga -fsycl-link=image [kernel src files] -o <hw image name> -Xshardware
```

Where:

`fPIC` Determines whether the compiler generates position-independent code for the host portion of the device image. Option `-fPIC` specifies full symbol preemption. Global symbol definitions as well as global symbol references get default (that is, preemptable) visibility unless explicitly specified otherwise. You must use this option when building shared objects. You can also specify this option as `-fpic`.

---

**NOTE**

`PIC` is required so that pointers in the shared library reference global addresses and not local addresses.

---

`fintelfpga` Targets FPGA devices.

`fsycl-link=image` Informs the Intel® oneAPI DPC++/C++ Compiler to perform partial linking of device binaries for use with FPGA.

`Xshardware` Compiles for hardware instead of the emulator.

**2. Compile the DPC++ host code separately.**

```
dpccpp -fPIC -fintelfpga <host src files> -o <host image name> -c -DFPGA=1
```

Where:

`DFPGA=1` Sets a compiler macro, `FPGA`, equal to 1. It is used in the device selector to change between target devices (requires corresponding host code to support this). This is optional as you can also set your device selector to `FPGA`.

**3. Link the host and device images and create the binary.**

```
dpccpp -fPIC -fintelfpga -shared <host image name><hw image name> -o lib<library name>.so
```

Where:

`shared` Outputs a shared library (`.so` file).

Output file name Prefix with `lib` for the GCC type of compilers. For additional information, see [Shared libraries with GCC on Linux](#). For example:

```
gcc -Wall -fPIC -L. -o out.a -l<library name>.so
```

---

**NOTE**

Instead of the above multi-step process, you can also perform a single-step compilation to generate the shared library. However, you must perform a full compile if you want to build the executable for testing purposes (for example, `a.out`) or if you make changes in the DPC++ code or C interface.

---

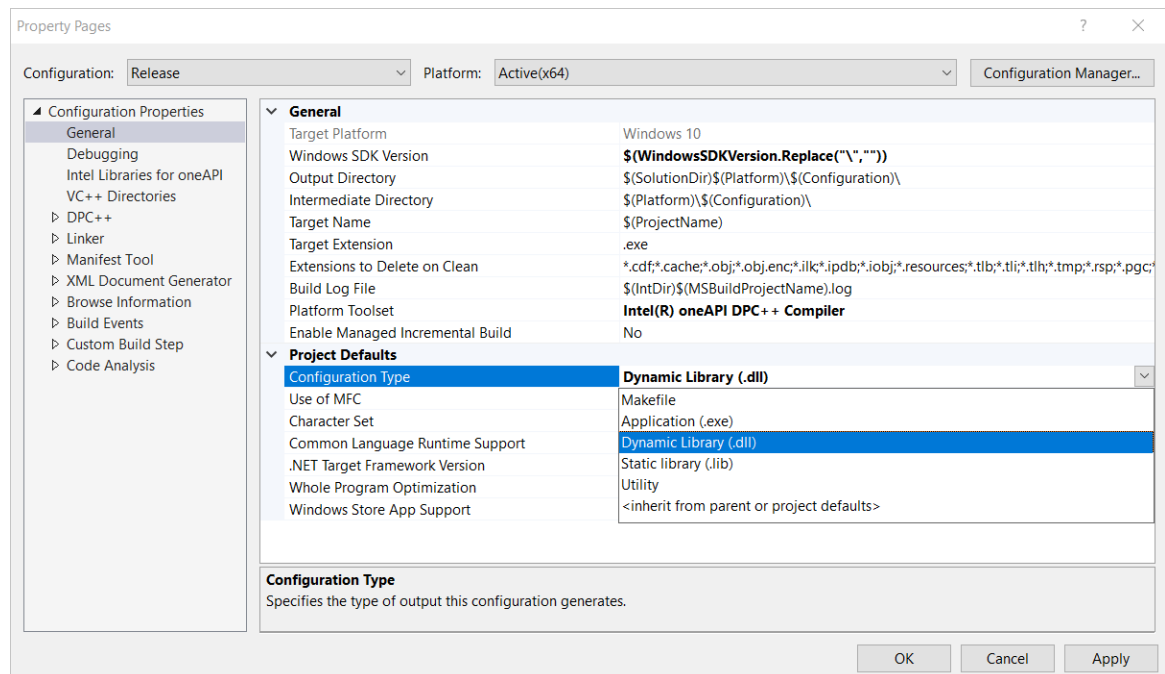
## Generate the Shared Library File in Windows

If you are using a Windows system, then perform these steps to generate the library file:

**NOTE**

- Intel® recommends creating a new configuration in the same project properties. That way if you want to build the application, you can avoid changing the configuration type for your project.
- Creating a Windows library with the default Intel® oneAPI Base Toolkit and FPGA add-on for Intel® PAC with Intel® Arria® 10 GX FPGA and Intel® Stratix® 10 SX FPGA is supported only for FPGA emulation. For custom platforms, contact your board vendor for Windows support for FPGA hardware compiles.

1. In Microsoft Visual Studio\*, navigate to **Project > Properties**. The **Property Pages** dialog is displayed for your project.
2. Under the **Configuration Properties > General > Project Defaults > Configuration Type** option, select **Dynamic Library (.dll)** from the drop-down list.

**Project Properties Dialog**

3. Click **OK** to close the dialog.

The project automatically builds to create a dynamic library (.dll)

### Use the Shared Library

These steps may vary depending on the language or compiler you decide to use. Consult the specifications for your desired language for more details. See [Shared libraries with GCC on Linux](#) for an example.

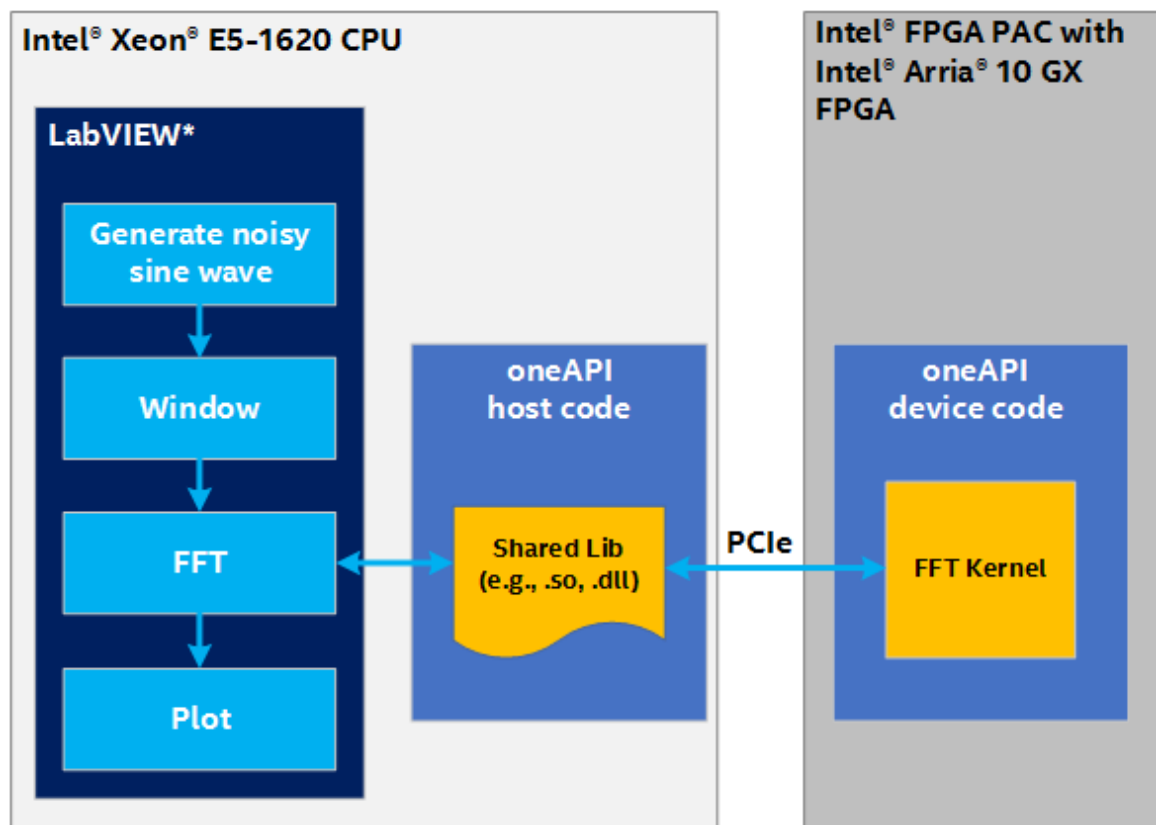
Generally, follow these steps to use the shared library:

1. Use the shared library function call in your third-party host code.
2. Link your host code with the shared library during the compilation.
3. Ensure that the library file is discoverable. For example:

```
export LD_LIBRARY_PATH=<lib file location>:$LD_LIBRARY_PATH
```

The following is an example illustration of using the shared library:

#### Example Use of the Shared Library



## FPGA Workflows in IDEs

The oneAPI tools integrate with third-party integrated development environments (IDEs) on Linux (Eclipse\*) and Windows (Visual Studio\*) to provide a seamless GUI experience for software development. See [Intel oneAPI DPC++ FPGA Workflows on Third-Party IDEs](#) for more details.

For FPGA development with Visual Studio Code on Linux\*, refer to [Intel® oneAPI DPC++ FPGA Development with Sample Browser Extension for Visual Studio Code on Linux](#).

# API-based Programming

Several libraries are available with oneAPI toolkits that can simplify the programming process by providing specialized APIs for use in optimized applications. This chapter provides basic details about the libraries, including code samples, to help guide the decision on which library is most useful in certain use cases. Detailed information about each library, including more about the available APIs, is available in the main documentation for that library.

Library	Usage
<a href="#">Intel oneAPI DPC++ Library</a>	Use this library for high performance parallel applications.
<a href="#">Intel oneAPI Math Kernel Library</a>	Use this library to include highly optimized and extensively parallelized math routines in an application.
<a href="#">Intel oneAPI Threading Building Blocks</a>	Use this library to combine TBB-based parallelism on multicore CPUs and DPC++ device-accelerated parallelism in an application.
<a href="#">Intel oneAPI Data Analytics Library</a>	Use this library to speed up big data analysis applications and distributed computation.
<a href="#">Intel oneAPI Collective Communications Library</a>	Use this library for applications that focus on Deep Learning and Machine Learning workloads.
<a href="#">Intel oneAPI Deep Neural Network Library</a>	Use this library for deep learning applications that use neural networks optimized for Intel Architecture Processors and Intel Processor Graphics.
<a href="#">Intel oneAPI Video Processing Library</a>	Use this library to accelerate video processing in an application.

## Intel oneAPI DPC++ Library (oneDPL)

The Intel® oneAPI DPC++ Library (oneDPL) aims to work with the Intel® oneAPI DPC++/C++ Compiler to provide high-productivity APIs to developers, which can minimize Data Parallel C++ (DPC++) programming efforts across devices for high performance parallel applications.

oneDPL consists of the following components:

- Parallel STL:
  - Parallel STL Usage Instructions
  - Macros
- An additional set of library classes and functions (referred to throughout this document as **Extension API**):
  - Parallel Algorithms
  - Iterators
  - Function Object Classes
  - Range-Based API
- Tested Standard C++ APIs
- Random Number Generator

### See Also

[Intel oneAPI DPC++ Library Guide](#)



## oneDPL Library Usage

Install the [Intel® oneAPI Base Toolkit](#) to use oneDPL.

To use Parallel STL or the Extension API, include the corresponding header files in your source code. All oneDPL header files are in the `oneapi/dpl` directory. Use `#include <oneapi/dpl/...>` to include them. oneDPL uses the namespace `oneapi::dpl` for the most of its classes and functions.

To use tested C++ standard APIs, you need to include the corresponding C++ standard header files and use the `std` namespace.

## oneDPL Code Sample

oneDPL sample code is available from the oneAPI GitHub repository <https://github.com/oneapi-src/oneAPI-samples/tree/master/Libraries/oneDPL>. Each sample includes a readme with build instructions.

## Intel oneAPI Math Kernel Library (oneMKL)

The Intel® oneAPI Math Kernel Library (oneMKL) is a computing math library of highly optimized and extensively parallelized routines for applications that require maximum performance. oneMKL contains the high-performance optimizations from the full Intel® Math Kernel Library for CPU architectures (with C/Fortran programming language interfaces) and adds to them a set of Data Parallel C++ (DPC++) programming language interfaces for achieving performance on various CPU architectures and Intel Graphics Technology for certain key functionalities.

You can use OpenMP\* offload to run standard oneMKL computations on Intel GPUs. Refer to [OpenMP\\* offload for C interfaces](#) and [OpenMP\\* offload for Fortran interfaces](#) for more information.

The new DPC++ interfaces with optimizations for CPU and GPU architectures have been added for key functionality in the following major areas of computation:

- BLAS and LAPACK dense linear algebra routines
- Sparse BLAS sparse linear algebra routines
- Random number generators (RNG)
- Vector Mathematics (VM) routines for optimized mathematical operations on vectors
- Fast Fourier Transforms (FFTs)

### See Also

[Get Started with Intel oneAPI Math Kernel Library for Data Parallel C++](#)

[Intel oneAPI Math Kernel Library - Data Parallel C++ Developer Reference](#)

[Developer Guide for Intel oneAPI Math Kernel Library for Linux\\* OS](#)

[Developer Guide for Intel oneAPI Math Kernel Library for Windows\\* OS](#)

## oneMKL Usage

When using the DPC++ programming language interfaces, there are a few changes to consider:

- oneMKL has a dependency on the Intel oneAPI DPC++/C++ Compiler and Intel oneAPI DPC++ Library. Applications must be built with the Intel oneAPI DPC++/C++ Compiler, the DPC++ headers made available, and the application linked with oneMKL using the DPC++ linker.
- DPC++ interfaces in oneMKL use device-accessible Unified Shared Memory (USM) pointers for input data (vectors, matrices, etc.).
- Many DPC++ interfaces in oneMKL also support the use of `sycl::buffer` objects in place of the device-accessible USM pointers for input data.
- DPC++ interfaces in oneMKL are overloaded based on the floating point types. For example, there are several general matrix multiply APIs, accepting single precision real arguments (`float`), double precision real arguments (`double`), half precision real arguments (`half`), and complex arguments of different precision using the standard library types `std::complex<float>`, `std::complex<double>`.
- A two-level namespace structure for oneMKL is added for DPC++ interfaces:

Namespace	Description
oneapi::mkl	Contains common elements between various domains in oneMKL
oneapi::mkl::blas	Contains dense vector-vector, matrix-vector, and matrix-matrix low level operations
oneapi::mkl::lapack	Contains higher-level dense matrix operations like matrix factorizations and eigensolvers
oneapi::mkl::rng	Contains random number generators for various probability density functions
oneapi::mkl::stats	Contains basic statistical estimates for single and double precision multi-dimensional datasets
oneapi::mkl::vm	Contains vector math routines
oneapi::mkl::dft	Contains fast fourier transform operations
oneapi::mkl::sparse	Contains sparse matrix operations like sparse matrix-vector multiplication and sparse triangular solver

## oneMKL Code Sample

To demonstrate a typical workflow for the oneMKL with DPC++ interfaces, the following example source code snippets perform a double precision matrix-matrix multiplication on a GPU device.

**NOTE** The following code example requires additional code to compile and run, as indicated by the inline comments.

```
// Standard SYCL header
#include <CL/sycl.hpp>
// STL classes
#include <exception>
#include <iostream>
// Declarations for Intel oneAPI Math Kernel Library DPC++ APIs
#include "oneapi/mkl.hpp"
int main(int argc, char *argv[]) {
    //
    // User obtains data here for A, B, C matrices, along with setting m, n, k, ldA, ldB, ldC.
    //
    // For this example, A, B and C should be initially stored in a std::vector,
    // or a similar container having data() and size() member functions.
    //

    // Create GPU device
    sycl::device my_device;
    try {
        my_device = sycl::device(sycl::gpu_selector());
    }
    catch (...) {
        std::cout << "Warning: GPU device not found! Using default device instead." << std::endl;
    }
    // Create asynchronous exceptions handler to be attached to queue.
    // Not required; can provide helpful information in case the system isn't correctly
    configured.
```

```

auto my_exception_handler = [](sycl::exception_list exceptions) {
    for (std::exception_ptr const& e : exceptions) {
        try {
            std::rethrow_exception(e);
        }
        catch (sycl::exception const& e) {
            std::cout << "Caught asynchronous SYCL exception:\n"
                << e.what() << std::endl;
        }
        catch (std::exception const& e) {
            std::cout << "Caught asynchronous STL exception:\n"
                << e.what() << std::endl;
        }
    }
};

// create execution queue on my gpu device with exception handler attached
sycl::queue my_queue(my_device, my_exception_handler);
// create sycl buffers of matrix data for offloading between device and host
sycl::buffer<double, 1> A_buffer(A.data(), A.size());
sycl::buffer<double, 1> B_buffer(B.data(), B.size());
sycl::buffer<double, 1> C_buffer(C.data(), C.size());
// add oneapi::mkl::blas::gemm to execution queue and catch any synchronous exceptions
try {
    using oneapi::mkl::blas::gemm;
    using oneapi::mkl::transpose;
    gemm(my_queue, transpose::nontrans, transpose::nontrans, m, n, k, alpha, A_buffer, ldA,
B_buffer,
        ldB, beta, C_buffer, ldC);
}
catch (sycl::exception const& e) {
    std::cout << "\t\tCaught synchronous SYCL exception during GEMM:\n"
        << e.what() << std::endl;
}
catch (std::exception const& e) {
    std::cout << "\t\tCaught synchronous STL exception during GEMM:\n"
        << e.what() << std::endl;
}
// ensure any asynchronous exceptions caught are handled before proceeding
my_queue.wait_and_throw();
//
// post process results
//
// Access data from C buffer and print out part of C matrix
auto C_accessor = C_buffer.template get_access<sycl::access::mode::read>();
std::cout << "\t" << C << " = [ " << C_accessor[0] << ", "
    << C_accessor[1] << ", ... ]\n";
std::cout << "\t    [ " << C_accessor[1 * ldC + 0] << ", "
    << C_accessor[1 * ldC + 1] << ", ... ]\n";
std::cout << "\t    [ " << "... ]\n";
std::cout << std::endl;

return 0;
}

```

Consider that (double precision valued) matrices A(of size m-by-k), B( of size k-by-n) and C(of size m-by-n) are stored in some arrays on the host machine with leading dimensions ldA, ldB, and ldC, respectively. Given scalars (double precision) alpha and beta, compute the matrix-matrix multiplication (mkl::blas::gemm):

$C = \alpha * A * B + \beta * C$

Include the standard SYCL headers and the oneMKL DPC++ specific header that declares the desired `mkl::blas::gemm` API:

```
// Standard SYCL header
#include <CL/sycl.hpp>
// STL classes
#include <exception>
#include <iostream>
// Declarations for Intel oneAPI Math Kernel Library DPC++ APIs
#include "oneapi/mkl.hpp"
```

Next, load or instantiate the matrix data on the host machine as usual and then create the GPU device, create an asynchronous exception handler, and finally create the queue on the device with that exception handler. Exceptions that occur on the host can be caught using standard C++ exception handling mechanisms; however, exceptions that occur on a device are considered asynchronous errors and stored in an exception list to be processed later by this user-provided exception handler.

```
// Create GPU device
sycl::device my_device;
try {
    my_device = sycl::device(sycl::gpu_selector());
}
catch (...) {
    std::cout << "Warning: GPU device not found! Using default device instead." << std::endl;
}
// Create asynchronous exceptions handler to be attached to queue.
// Not required; can provide helpful information in case the system isn't correctly
configured.
auto my_exception_handler = [](sycl::exception_list exceptions) {
    for (std::exception_ptr const& e : exceptions) {
        try {
            std::rethrow_exception(e);
        }
        catch (sycl::exception const& e) {
            std::cout << "Caught asynchronous SYCL exception:\n"
                << e.what() << std::endl;
        }
        catch (std::exception const& e) {
            std::cout << "Caught asynchronous STL exception:\n"
                << e.what() << std::endl;
        }
    }
};
```

The matrix data is now loaded into the DPC++ buffers, which enables offloading to desired devices and then back to host when complete. Finally, the `mkl::blas::gemm` API is called with all the buffers, sizes, and transpose operations, which will enqueue the matrix multiply kernel and data onto the desired queue.

```
// create execution queue on my gpu device with exception handler attached
sycl::queue my_queue(my_device, my_exception_handler);
// create sycl buffers of matrix data for offloading between device and host
sycl::buffer<double, 1> A_buffer(A.data(), A.size());
sycl::buffer<double, 1> B_buffer(B.data(), B.size());
sycl::buffer<double, 1> C_buffer(C.data(), C.size());
// add oneapi::mkl::blas::gemm to execution queue and catch any synchronous exceptions
try {
    using oneapi::mkl::blas::gemm;
    using oneapi::mkl::transpose;
    gemm(my_queue, transpose::nontrans, transpose::nontrans, m, n, k, alpha, A_buffer, ldA,
B_buffer,
        ldB, beta, C_buffer, ldC);
```

```

    }
    catch (sycl::exception const& e) {
        std::cout << "\t\tCaught synchronous SYCL exception during GEMM:\n"
                  << e.what() << std::endl;
    }
    catch (std::exception const& e) {
        std::cout << "\t\tCaught synchronous STL exception during GEMM:\n"
                  << e.what() << std::endl;
    }
}

```

At some time after the `gemm` kernel has been enqueued, it will be executed. The queue is asked to wait for all kernels to execute and then pass any caught asynchronous exceptions to the exception handler to be thrown. The runtime will handle transfer of the buffer's data between host and GPU device and back. By the time an accessor is created for the `C_buffer`, the buffer data will have been silently transferred back to the host machine if necessary. In this case, the accessor is used to print out a 2x2 submatrix of `C_buffer`.

```

// Access data from C buffer and print out part of C matrix
auto C_accessor = C_buffer.template get_access<sycl::access::mode::read>();
std::cout << "\t" << C << " = [ " << C_accessor[0] << ", "
          << C_accessor[1] << ", ... ]\n";
std::cout << "\t" << [ " << C_accessor[1 * ldC + 0] << ", "
          << C_accessor[1 * ldC + 1] << ", ... ]\n";
std::cout << "\t" << [ " << "... ]\n";
std::cout << std::endl;

return 0;

```

Note that the resulting data is still in the `C_buffer` object and, unless it is explicitly copied elsewhere (like back to the original `C` container), it will only remain available through accessors until the `C_buffer` is out of scope.

## Intel oneAPI Threading Building Blocks (oneTBB)

Intel® oneAPI Threading Building Blocks (oneTBB) is a widely used C++ library for task-based, shared memory parallel programming on the host. The library provides features for parallel programming on CPUs beyond those currently available in SYCL\* and ISO C++, including:

- Generic parallel algorithms
- Concurrent containers
- A scalable memory allocator
- Work-stealing task scheduler
- Low-level synchronization primitives

oneTBB is compiler-independent and is available on a variety of processors and operating systems. It is used by other oneAPI libraries (Intel oneAPI Math Kernel Library, Intel oneAPI Deep Neural Network Library, etc.) to express multithreading parallelism for CPUs.

### See Also

[Get Started with Intel oneAPI Threading Building Blocks](#)

[Intel oneAPI Threading Building Blocks Documentation](#)

### oneTBB Usage

oneTBB can be used with the Intel oneAPI DPC++/C++ Compiler in the same way as with any other C++ compiler. For more details, see the [oneTBB documentation](#).

Currently, oneTBB does not directly use any accelerators. However, it can be combined with the DPC++ language, OpenMP\* offload, and other oneAPI libraries to build a program that efficiently uses all available hardware resources.

## oneTBB Code Sample

Two basic oneTBB code samples are available within the oneAPI GitHub repository <https://github.com/oneapi-src/oneAPI-samples/tree/master/Libraries/oneTBB>. Both samples are prepared for CPU and GPU.

- `tbb-async-sycl`: illustrates how computational kernel can be split for execution between CPU and GPU using oneTBB Flow Graph asynchronous node and functional node. The Flow Graph asynchronous node uses SYCL\* to implement calculations on GPU while the functional node does CPU part of calculations.
- `tbb-task-sycl`: illustrates how two oneTBB tasks can execute similar computational kernels with one task executing SYCL code and another one the oneTBB code.
- `tbb-resumable-tasks-sycl`: illustrates how a computational kernel can be split for execution between a CPU and GPU using oneTBB resumable task and `parallel_for`. The resumable task uses SYCL to implement calculations on GPU while `parallel_for` does the CPU portion of calculations.

## Intel oneAPI Data Analytics Library (oneDAL)

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Intel oneAPI Data Analytics Library (oneDAL) is a library that helps speed up big data analysis by providing highly optimized algorithmic building blocks for all stages of data analytics (preprocessing, transformation, analysis, modeling, validation, and decision making) in batch, online, and distributed processing modes of computation.

The library optimizes data ingestion along with algorithmic computation to increase throughput and scalability. It includes C++ and Java\* APIs and connectors to popular data sources such as Spark\* and Hadoop\*. Python\* wrappers for oneDAL are part of [Intel Distribution for Python](#).

In addition to classic features, oneDAL provides DPC++ API extensions to the traditional C++ interface and enables GPU usage for some algorithms.

The library is particularly useful for distributed computation. It provides a full set of building blocks for distributed algorithms that are independent from any communication layer. This allows users to construct fast and scalable distributed applications using user-preferable communication means.

For general information, visit the [oneDAL GitHub\\* page](#). The complete list of features and documentation are available at the [official Intel oneAPI Data Analytics Library website](#). Free and open-source community-supported versions are available, as well as paid versions with premium support.

### See Also

[Get Started with the Intel oneAPI Data Analytics Library](#)

[Intel oneAPI Data Analytics Library Documentation](#)

## oneDAL Usage

Information about dependencies needed to build and link your application with oneDAL are available from the [oneDAL System Requirements](#).

A oneDAL-based application can seamlessly execute algorithms on CPU or GPU by picking the proper device selector. New capabilities also allow:

- extracting DPC++ buffers from numeric tables and pass them to a custom kernel
- creating numeric tables from DPC++ buffers

Algorithms are optimized to reuse DPC++ buffers to keep GPU data and remove overload from repeatedly copying data between GPU and CPU.

## oneDAL Code Sample

oneDAL code samples are available from the oneDAL GitHub. The following code sample is a recommended starting point: <https://github.com/oneapi-src/oneDAL/tree/master/examples/oneapi/dpc/source/svm>

## Intel oneAPI Collective Communications Library (oneCCL)

Intel oneAPI Collective Communications Library (oneCCL) is a scalable and high-performance communication library for Deep Learning (DL) and Machine Learning (ML) workloads. It develops the ideas that originated in Intel® Machine Learning Scaling Library and expands the design and API to encompass new features and use cases.

oneCCL features include:

- Built on top of lower-level communication middleware – MPI and libfabrics
- Optimized to drive scalability of communication patterns by enabling the productive trade-off of compute for communication performance
- Enables a set of DL-specific optimizations, such as prioritization, persistent operations, out of order execution, etc.
- DPC++-aware API to run across various hardware targets, such as CPUs and GPUs
- Works across various interconnects: Intel® Omni-Path Architecture (Intel® OPA), InfiniBand\*, and Ethernet

### See Also

[Get Started with Intel oneAPI Collective Communications Library](#)

[Intel oneAPI Collective Communications Library Documentation](#)

### oneCCL Usage

Refer to the [Intel oneAPI Collective Communications Library System Requirements](#) for a full list of hardware and software dependencies, such as MPI and Intel oneAPI DPC++/C++ Compiler.

SYCL-aware API is an optional feature of oneCCL. There is a choice between CPU and SYCL back ends when creating the oneCCL stream object.

- For CPU backend: Specify `ccl_stream_host` as the first argument.
- For SYCL backend: Specify `ccl_stream_cpu` or `ccl_stream_gpu` depending on the device type.
- For collective operations that operate on the SYCL stream:
  - For C API, oneCCL expects communication buffers to be `sycl::buffer` objects casted to `void*`.
  - For C++ API, oneCCL expects communication buffers to be passed by reference.

Additional usage details are available from <https://oneapi-src.github.io/oneCCL/>.

### oneCCL Code Sample

oneCCL code samples are available from the oneAPI GitHub repository <https://github.com/oneapi-src/oneAPI-samples/tree/master/Libraries/oneCCL>.

A Getting Started sample with instructions to build and run the code is available from within the same GitHub repository.

## Intel oneAPI Deep Neural Network Library (oneDNN)

Intel oneAPI Deep Neural Network Library (oneDNN) is an open-source performance library for deep learning applications. The library includes basic building blocks for neural networks optimized for Intel Architecture Processors and Intel Processor Graphics. oneDNN is intended for deep learning applications and framework developers interested in improving application performance on Intel Architecture Processors and Intel Processor Graphics. Deep learning practitioners should use one of the applications enabled with oneDNN.

oneDNN is distributed as part of Intel® oneAPI DL Framework Developer Toolkit, the Intel oneAPI Base Toolkit, and is available via apt and yum channels.

oneDNN continues to support features currently available with DNNL, including C and C++ interfaces, OpenMP\*, Intel oneAPI Threading Building Blocks, and OpenCL™ runtimes. oneDNN introduces DPC++ API and runtime support for the oneAPI programming model.

For more information, see <https://github.com/oneapi-src/oneDNN>.

## See Also

[Get Started with Intel oneAPI Deep Neural Network Library](#)  
[Intel oneAPI Deep Neural Network Library Documentation](#)

## oneDNN Usage

oneDNN supports systems based on Intel 64 architecture or compatible processors. A full list of supported CPU and graphics hardware is available from the Intel oneAPI Deep Neural Network Library System Requirements.

oneDNN detects the instruction set architecture (ISA) in the runtime and uses online generation to deploy the code optimized for the latest supported ISA.

Several packages are available for each operating system to ensure interoperability with CPU or GPU runtime libraries used by the application.

Configuration	Dependency
cpu_dpcpp_gpu_dpcpp	DPC++ runtime
cpu_iomp	Intel OpenMP* runtime
cpu_gomp	GNU* OpenMP runtime
cpu_vcomp	Microsoft* Visual C++ OpenMP runtime
cpu_tbb	Intel oneAPI Threading Building Blocks

The packages do not include library dependencies and these need to be resolved in the application at build time with oneAPI toolkits or third-party tools.

When used in the DPC++ environment, oneDNN relies on the DPC++ runtime to interact with CPU or GPU hardware. oneDNN may be used with other code that uses DPC++. To do this, oneDNN provides API extensions to interoperate with underlying SYCL objects.

One of the possible scenarios is executing a DPC++ kernel for a custom operation not provided by oneDNN. In this case, oneDNN provides all necessary APIs to seamlessly submit a kernel, sharing the execution context with oneDNN: using the same device and queue.

The interoperability API is provided for two scenarios:

- Construction of oneDNN objects based on existing DPC++ objects
- Accessing DPC++ objects for existing oneDNN objects

The mapping between oneDNN and DPC++ objects is summarized in the tables below.

oneDNN Objects	DPC++ Objects
Engine	cl::sycl::device and cl::sycl::context
Stream	cl::sycl::queue
Memory	cl::sycl::buffer<uint8_t, 1> or Unified Shared Memory (USM) pointer

**NOTE** Internally, library memory objects use 1D uint8\_t SYCL buffers, however SYCL buffers of a different type can be used to initialize and access memory. In this case, buffers will be reinterpreted to the underlying type `cl::sycl::buffer<uint8_t, 1>`.

oneDNN Object	Constructing from DPC++ Object
Engine	<code>dnnl::sycl_interop::make_engine(sycl_dev, sycl_ctx)</code>



oneDNN Object	Constructing from DPC++ Object
Stream	<code>dnnl::sycl_interop::make_stream(engine, sycl_queue)</code>
Memory	USM based: <code>dnnl::memory(memory_desc, engine, usm_ptr)</code> Buffer based: <code>dnnl::sycl_interop::make_memory(memory_desc, engine, sycl_buf)</code>
oneDNN Object	Extracting DPC++ Object
Engine	<code>dnnl::sycl_interop::get_device(engine)</code> <code>dnnl::sycl_interop::get_context(engine)</code>
Stream	<code>dnnl::sycl_interop::get_queue(stream)</code>
Memory	USM pointer: <code>dnnl::memory::get_data_handle()</code> Buffer: <code>dnnl::sycl_interop::get_buffer(memory)</code>

#### Notes

- Building applications with oneDNN requires a compiler. The Intel oneAPI DPC++/C++ Compiler is available as part of the Intel oneAPI Base Toolkit.
- You must include `dnnl_sycl.hpp` to enable the SYCL-interop API.
- Because OpenMP does not rely on the passing of runtime objects, it does not require an interoperability API to work with oneDNN.

## oneDNN Code Sample

oneDNN sample code is available from the Intel oneAPI Base Toolkit GitHub repository <https://github.com/oneapi-src/oneAPI-samples/tree/master/Libraries/oneDNN>. The Getting Started sample is targeted to new users and includes a readme file with example build and run commands.

## Intel oneAPI Video Processing Library (oneVPL)

Intel oneAPI Video Processing Library (oneVPL) is a programming interface for video decoding, encoding, and processing to build portable media pipelines on CPUs, GPUs, and other accelerators. The oneVPL API is used to develop quality, performant video applications that can leverage Intel® hardware accelerators. It provides device discovery and selection in media centric and video analytics workloads, and API primitives for zero-copy buffer sharing. oneVPL is backward compatible with Intel® Media SDK and cross-architecture compatible to ensure optimal execution on current and next generation hardware without source code changes.

oneVPL is an open specification API.

### See Also

[Get Started with oneVPL](#)

## oneVPL Usage

Applications can use oneVPL to program video decoding, encoding, and image processing components. oneVPL provides a default CPU implementation that can be used as a reference design before using other accelerators.

oneVPL applications follow a basic sequence in the programming model:

1. The oneVPL dispatcher automatically finds all available accelerators during runtime.

2. Dispatcher uses the selected accelerator context to initialize a session.
3. oneVPL configures the video component at the start of the session.
4. oneVPL processing loop is launched. The processing loop handles work asynchronously.
5. If the application chooses to let oneVPL manage working memory, then memory allocation will be implicitly managed by the video calls in the processing loop.
6. After work is done, oneVPL uses a clear call to clean up all resources.

The oneVPL API is defined using a classic C style interface and is compatible with C++ and DPC++.

## oneVPL Code Sample

oneVPL provides rich code samples to show how to use the oneVPL API. The code samples are included in the release package and are also available from the [oneAPI-samples](#) repository on GitHub\*.

For example, the [hello-decode sample](#) shows a simple decode operation of HEVC input streams and demonstrates the basic steps in the oneVPL programming model.

The sample can be broken down into the following key steps in the code:

### NOTE

The snippets below may not reflect the latest version of the sample. Refer to the release package or sample repository for the latest version of this example.

1. Initialize oneVPL session with dispatcher:

```
mfxLoader loader = NULL;
mfxConfig cfg = NULL;

loader = MFXLoad();

cfg = MFXCreateConfig(loader);
ImplValue.Type = MFX_VARIANT_TYPE_U32;
ImplValue.Data.U32 = MFX_CODEC_HEVC;
sts = MFXSetConfigFilterProperty(cfg,
(mfxU8*)"mfxImplDescription.mfxDecoderDescription.decoder.CodecID", ImplValue);

sts = MFXCreateSession(loader, 0, &session);
```

Here, `MFXCreateConfig()` creates the dispatcher internal configuration. Once the dispatcher is configured, the application uses `MFXSetConfigFilterProperty()` to set its requirements including codec ID and accelerator preference. After the application sets the desired requirements, the session is created.

2. Start the decoding loop:

```
while(is_stillgoing) {
    sts = MFXVideoDECODE_DecodeFrameAsync(session,
        (isdRAINING) ? NULL : &bitstream,
        NULL,
        &pmfxOutSurface,
        &syncp);
    .....
}
```

After preparing the input stream, the stream has the required context and the decoding loop is started immediately.

`MFXVideoDECODE_DecodeFrameAsync()` takes the bit stream as the second parameter. When the bit stream becomes NULL, oneVPL drains the remaining frames from the input and completes the operation. The third parameter is the working memory; the NULL input shown in the example means the application wants oneVPL to manage working memory.

**3. Evaluate results of a decoding call:**

```

while(is_stillgoing) {
    sts = MFXVideoDECODE_DecodeFrameAsync(...);

    switch(sts) {
        case MFX_ERR_MORE_DATA:
            .....
            ReadEncodedStream(bitstream, codec_id, source);
            .....
        }
        break;

        case MFX_ERR_NONE:
            do {
                sts = pmfxOutSurface->FrameInterface->Synchronize(pmfxOutSurface,
WAIT_100_MILLSECONDS);
                if( MFX_ERR_NONE == sts ) {
                    sts = pmfxOutSurface->FrameInterface->Map(pmfxOutSurface, MFX_MAP_READ);

                    WriteRawFrame(pmfxOutSurface, sink);

                    sts = pmfxOutSurface->FrameInterface->Unmap(pmfxOutSurface);

                    sts = pmfxOutSurface->FrameInterface->Release(pmfxOutSurface);

                    framenum++;
                }
            } while( sts == MFX_WRN_IN_EXECUTION );
            break;

        default:
            break;
    }
}

```

For each `MFXVideoDECODE_DecodeFrameAsync()` call, the application continues to read the input bit stream until oneVPL completes a new frame with `MFX_ERR_NONE`, indicating the function successfully completed its operation. For each new frame, the application waits until the output memory (surface) is ready and then outputs and releases the output frame.

The `Map()` call is used to map the memory from the discrete graphic memory space to the host memory space.

**4. Exit and do cleanup:**

```

MFXUnload(loader);
free(bitstream.Data);
fclose(sink);
fclose(source);

```

Finally, `MFXUnload()` is called to reclaim the resources from oneVPL. This is the only call that the application must execute to reclaim the oneVPL library resources.

**NOTE**

This example explains the key steps in the oneVPL programming model. It does not explain utility functions for input and output.

## Other Libraries

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Other libraries are included in various oneAPI toolkits. For more information about each of the libraries listed, consult the official documentation for that library.

- Intel® Integrated Performance Primitives (IPP)
- Intel® MPI Library
- Intel® Open Volume Kernel Library

## 6

# Software Development Process

The software development process using the oneAPI programming model is based upon standard development processes. Since the programming model pertains to employing an accelerator to improve performance, this chapter details steps specific to that activity. These include:

- The performance tuning cycle
- Debugging of code
- Migrating code that targets other accelerators
- Composability of code

## Migrating Code to DPC++

Code written in other programming languages, such as C++ or OpenCL™, can be migrated to DPC++ code for use on multiple devices. The steps used to complete the migration vary based on the original language.

### Migrating from C++ to SYCL/DPC++

SYCL is a single-source style programming model based on C++. It builds on features of C++11 and has additional support for C++14 and enables C++17 Parallel STL programs to be accelerated on OpenCL™ devices. Some of the supported C++ features include templates, classes, operator overloading, lambda, and static polymorphism.

When accelerating an existing C++ application on OpenCL devices, SYCL provides seamless integration as most of the C++ code remains intact. Refer to sections within [oneAPI Programming Model](#) for SYCL constructs to enable device side compilation.

### Migrating from CUDA\* to DPC++

The Intel DPC++ Compatibility Tool is part of the Intel oneAPI Base Toolkit. The goal of this tool is to assist in the migration of an existing program that is written in NVIDIA\* CUDA\* to a program written in DPC++. This tool generates DPC++ code as much as possible. However, it will not migrate all code and manual changes may be required. The tool provides help with IDE plug-ins, a [user guide](#), and embedded comments in the code to complete the migration to DPC++. After completing any manual changes, use a DPC++ compiler to create executables.



Additional details, including examples of migrated code and download instructions for the tool, are available from the [Intel® DPC++ Compatibility Tool website](#). Full usage information is available from the [Intel® DPC++ Compatibility Tool User Guide](#).

## Migrating from OpenCL Code to DPC++

In the current version of DPC++, the runtime employs OpenCL code to enact the parallelism. DPC++ typically requires fewer lines of code to implement kernels and also fewer calls to essential API functions and methods. It enables creation of OpenCL programs by embedding the device source code in line with the host source code.

Most of the OpenCL application developers are aware of the somewhat verbose setup code that goes with offloading kernels on devices. Using DPC++, it is possible to develop a clean, modern C++ based application without most of the setup associated with OpenCL C code. This reduces the learning effort and allows for focus on parallelization techniques.

However, OpenCL application features can continue to be used via the SYCL API. The updated code can use as much or as little of the SYCL interface as desired.

## Migrating Between CPU, GPU, and FPGA

In DPC++, a platform consists of a host device connected to zero or more devices, such as CPU, GPU, FPGA, or other kinds of accelerators and processors.

When a platform has multiple devices, design the application to offload some or most of the work to the devices. There are different ways to distribute work across devices in the oneAPI programming model:

1. Initialize device selector – SYCL provides a set of classes called selectors that allow manual selection of devices in the platform or let oneAPI runtime heuristics choose a default device based on the compute power available on the devices.
2. Splitting datasets – With a highly parallel application with no data dependency, explicitly divide the datasets to employ different devices. The following code sample is an example of dispatching workloads across multiple devices. Use `dpcpp snippet.cpp` to compile the code.

```
int main() {
    int data[1024];
    for (int i = 0; i < 1024; i++)
        data[i] = i;
    try {
        cpu_selector cpuSelector;
        queue cpuQueue(cpuSelector);
        gpu_selector gpuSelector;
        queue gpuQueue(gpuSelector);
        buffer<int, 1> buf(data, range<1>(1024));
        cpuQueue.submit([&](handler& cgh) {
            auto ptr =
                buf.get_access<access::mode::read_write>(cgh);
            cgh.parallel_for<class divide>(range<1>(512),
                [=](id<1> index) {
                    ptr[index] -= 1;
                });
        });
        gpuQueue.submit([&](handler& cgh1) {
            auto ptr =
                buf.get_access<access::mode::read_write>(cgh1);
            cgh1.parallel_for<class offset1>(range<1>(1024),
                id<1>(512), [=](id<1> index) {
                    ptr[index] += 1;
                });
        });
        cpuQueue.wait();
        gpuQueue.wait();
    }
    catch (exception const& e) {
```

```

        std::cout <<
        "SYCL exception caught: " << e.what() << '\n';
        return 2;
    }
    return 0;
}

```

- 3. Target multiple kernels across devices** – If the application has scope for parallelization on multiple independent kernels, employ different queues to target devices. The list of SYCL supported platforms can be obtained with the list of devices for each platform by calling `get_platforms()` and `platform.get_devices()` respectively. Once all the devices are identified, construct a queue per device and dispatch different kernels to different queues. The following code sample represents dispatching a kernel on multiple SYCL devices.

```

#include <stdio.h>
#include <vector>
#include <CL/sycl.hpp>
using namespace cl::sycl;
using namespace std;
int main()
{
    size_t N = 1024;
    vector<float> a(N, 10.0);
    vector<float> b(N, 10.0);
    vector<float> c_add(N, 0.0);
    vector<float> c_mul(N, 0.0);
    {
        buffer<float, 1> abuffer(a.data(), range<1>(N),
            { property::buffer::use_host_ptr() });
        buffer<float, 1> bbuffer(b.data(), range<1>(N),
            { property::buffer::use_host_ptr() });
        buffer<float, 1> c_addbuffer(c_add.data(), range<1>(N),
            { property::buffer::use_host_ptr() });
        buffer<float, 1> c_mulbuffer(c_mul.data(), range<1>(N),
            { property::buffer::use_host_ptr() });
    }
    try {
        gpu_selector gpuSelector;
        auto queue = cl::sycl::queue(gpuSelector);
        queue.submit([&](cl::sycl::handler& cgh) {
            auto a_acc = abuffer.template
                get_access<access::mode::read>(cgh);
            auto b_acc = bbuffer.template
                get_access<access::mode::read>(cgh);
            auto c_acc_add = c_addbuffer.template
                get_access<access::mode::write>(cgh);
            cgh.parallel_for<class VectorAdd>
                (range<1>(N), [=](id<1> it) {
                    //int i = it.get_global();
                    c_acc_add[it] = a_acc[it] + b_acc[it];
                });
        });
        cpu_selector cpuSelector;
        auto queue1 = cl::sycl::queue(cpuSelector);
        queue1.submit([&](cl::sycl::handler& cgh) {
            auto a_acc = abuffer.template
                get_access<access::mode::read>(cgh);
            auto b_acc = bbuffer.template
                get_access<access::mode::read>(cgh);
            auto c_acc_mul = c_mulbuffer.template
                get_access<access::mode::write>(cgh);
        });
    }
}

```

```

        cgh.parallel_for<class VectorMul>
        (range<1>(N), [=](id<1> it) {
            c_acc_mul[it] = a_acc[it] * b_acc[it];
        });
    }
    catch (cl::sycl::exception e) {
/* In the case of an exception being throw, print the
error message and
        * return 1. */
        std::cout << e.what();
        return 1;
    }
}
for (int i = 0; i < 8; i++) {
    std::cout << c_add[i] << std::endl;
    std::cout << c_mul[i] << std::endl;
}
return 0;
}

```

## Composability

The oneAPI programming model enables an ecosystem with support for the entire development toolchain. It includes compilers and libraries, debuggers, and analysis tools to support multiple accelerators like CPU, GPUs, FPGA, and more.

### C/C++ OpenMP\* and DPC++ Composability

The oneAPI programming model provides a unified compiler based on LLVM/Clang with support for OpenMP\* offload. This allows seamless integration that allows the use of OpenMP constructs to either parallelize host side applications or offload to a target device. Both the Intel® oneAPI DPC++/C++ Compiler, available with the Intel® oneAPI Base Toolkit, and Intel® C++ Compiler Classic, available with the Intel® oneAPI HPC Toolkit or the Intel® oneAPI IoT Toolkit, support OpenMP and DPC++ composability with a set of restrictions. A single application can offload execution to available devices using OpenMP target regions or DPC++/SYCL constructs in different parts of the code, such as different functions or code segments.

OpenMP and DPC++ offloading constructs may be used in separate files, in the same file, or in the same function with some restrictions. OpenMP and DPC++ offloading code can be bundled together in executable files, in static libraries, in dynamic libraries, or in various combinations.

#### NOTE

DPC++ is based on TBB runtime when executing device code on the CPU; hence, using both OpenMP and DPC++ on a CPU can lead to oversubscribing of threads. Performance analysis of workloads executing on the system could help determine if this is occurring.

### Restrictions

There are some restrictions to be considered when mixing OpenMP and DPC++/SYCL constructs in the same application.

- OpenMP directives cannot be used inside DPC++/SYCL kernels that run in the device. Similarly, DPC++/SYCL code cannot be used inside the OpenMP target regions. However, it is possible to use SYCL constructs within the OpenMP code that runs on the host CPU.



- OpenMP and DPC++/SYCL device parts of the program cannot have cross dependencies. For example, a function defined in the SYCL part of the device code cannot be called from the OpenMP code that runs on the device and vice versa. OpenMP and SYCL device parts are linked independently and they form separate binaries that become a part of the resulting fat binary that is generated by the compiler.
- The direct interaction between OpenMP and SYCL runtime libraries are not supported at this time. For example, a device memory object created by OpenMP API is not accessible by DPC++ code. That is, using the device memory object created by OpenMP in DPC++/SYCL code results unspecified execution behavior.

## Example

The following code snippet uses DPC++/SYCL and OpenMP offloading constructs in the same application.

```
#include <CL/sycl.hpp>
#include <array>
#include <iostream>

float computePi(unsigned N) {
    float Pi;
#pragma omp target map(from : Pi)
#pragma omp parallel for reduction(+ : Pi)
    for (unsigned I = 0; I < N; ++I) {
        float T = (I + 0.5f) / N;
        Pi += 4.0f / (1.0 + T * T);
    }
    return Pi / N;
}

void iota(float *A, unsigned N) {
    cl::sycl::range<1> R(N);
    cl::sycl::buffer<float, 1> AB(A, R);
    cl::sycl::queue().submit([&](cl::sycl::handler &cgh) {
        auto AA = AB.template get_access<cl::sycl::access::mode::write>(cgh);
        cgh.parallel_for<class Iota>(R, [=](cl::sycl::id<1> I) {
            AA[I] = I;
        });
    });
}

int main() {
    std::array<float, 1024u> Vec;
    float Pi;

#pragma omp parallel sections
    {
#pragma omp section
        iota(Vec.data(), Vec.size());
#pragma omp section
        Pi = computePi(8192u);
    }

    std::cout << "Vec[512] = " << Vec[512] << std::endl;
    std::cout << "Pi = " << Pi << std::endl;
    return 0;
}
```

The following command is used to compile the example code: `icpx -fsycl -fiopenmp -fopenmp-targets=spir64 offloadOmp_dpcpp.cpp`

where

- `-fsycl` option enables DPC++
- `-fiopenmp -fopenmp-targets=spir64` option enables OpenMP\* offload

The following shows the program output from the example code.

```
./a.out
Vec[512] = 512
Pi = 3.14159
```

---

#### NOTE

If the code does not contain OpenMP offload, but only normal OpenMP code, use the following command, which omits `-fopenmp-targets: icpx -fsycl -fiopenmp omp_dpcpp.cpp`

---

## OpenCL™ Code Interoperability

The oneAPI programming model enables developers to continue using all OpenCL code features via different parts of the SYCL API. The OpenCL code interoperability mode provided by SYCL helps reuse the existing OpenCL code while keeping the advantages of higher programming model interfaces provided by SYCL. There are 2 main parts in the interoperability mode:

1. To create SYCL objects from OpenCL code objects. For example, a SYCL buffer can be constructed from an OpenCL `cl_mem` or SYCL queue from a `cl_command_queue`.
2. To get OpenCL code objects from SYCL objects. For example, launching an OpenCL kernel that uses an implicit `cl_mem` associated to a SYCL accessor.

## Debugging the DPC++ and OpenMP\* Offload Process

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When writing, debugging, and optimizing code for a host platform, the process of improving your code is simple: deal with language errors when you build, catch and root-cause crashes/incorrect results during execution with a debugger, then identify and fix performance issues using a profiling tool.

Improving code can become considerably more complicated in applications where part of the execution is offloaded to another device using either DPC++ or OpenMP\* offload.

- Incorrect use of the DPC++ or OpenMP\* offload languages may not be exposed until just-in-time compilation occurs when you run your program with an attached offload device (these issues can be exposed earlier with ahead-of-time (AOT) compilation).
- Crashes due to logic errors may arise as unexpected behavior on the host, on the offload device, or in the software stack that ties the various computing devices together. To root cause these issues, you need to:
  - Debug what is happening in your code on the host using a standard debugger, such as Intel Distribution for GDB\*.
  - Debug problems on the offload device using a device-specific debugger. Note, however, that the device may have a different architecture, conventions for representing compute threads, or assembly than the host.
  - To debug problems that show up in the intermediate software stack only when kernels and data are being exchanged with the device, you need to monitor the communication between device and host and any errors that are reported during the process.
- Besides the usual performance issues that can occur on the host and offload devices, the patterns by which the host and offload device work together can have a profound impact on application performance. This is another case where you need to monitor the communications between the host and offload device.

This section discusses the various debugging and performance analysis tools and techniques available to you for the entire lifecycle of the offload program.

## oneAPI Debug Tools

The following tools are available to help with debugging the DPC++ and OpenMP\* offload process.

Tool	When to Use
Environment variables	Environment variables allow you to gather diagnostic information from the OpenMP and DPC++ runtimes at program execution with no modifications to your program.
ze_tracer tool from Profiling Tools Interfaces for GPU (PTI for GPU)	When using the oneAPI Level Zero backend for DPC++ and OpenMP Offload, this tool can be used to debug backend errors and for performance profiling on both the host and device.  Learn more: <ul style="list-style-type: none"> <li>• <a href="#">ze_tracer tool GitHub</a></li> <li>• <a href="#">PTI for GPU GitHub</a></li> </ul>
Intercept Layer for OpenCL™ Applications	When using the OpenCL backend for DPC++ and OpenMP Offload, this library can be used to debug backend errors and for performance profiling on both the host and device.
Intel® Distribution for GDB*	Used for source-level debugging of the application, typically to inspect logical bugs, on the host and any devices you are using (CPU, GPU, FPGA emulation).
Intel® Inspector	This tool helps to locate and debug memory and threading problems, including those that can cause offloading to fail.  <b>NOTE</b> Intel Inspector is included in the Intel oneAPI HPC Toolkit or the Intel oneAPI IoT Toolkit.
In-application debugging	In addition to these tools and runtime based approaches, the developer can locate problems using other approaches. For example: <ul style="list-style-type: none"> <li>• Comparing kernel output to expected output</li> <li>• Sending intermediate results back by variables they create for debugging purposes</li> <li>• Printing results from within kernels</li> </ul> <b>NOTE</b> Both DPC++ and OpenMP allow printing to <code>stdout</code> from within an offload region - be sure to note which SIMD lane or thread is providing the output.

## Debug Environment Variables

Both the OpenMP\* and DPC++ offload runtimes provide environment variables that let you understand the communication between the host and offload device. The variables also allow you to discover or control the runtime chosen for offload computations.

### OpenMP\* Offload Environment Variables

There are several environment variables that you can use to understand how OpenMP Offload works and control which backend it uses.

---

#### NOTE

OpenMP is not supported for FPGA devices.

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Environment Variable	Description
LIBOMPTARGET_DEBUG	<p>This environment variable enables debug output from the OpenMP Offload runtime. It reports:</p> <ul style="list-style-type: none"> <li>• The available runtimes detected and used (1,2)</li> <li>• When the chosen runtime is started and stopped (1,2)</li> <li>• Details on the offload device used (1,2)</li> <li>• Support libraries loaded (1,2)</li> <li>• Size and address of all memory allocations and deallocations (1,2)</li> <li>• Information on every data copy to and from the device, or device mapping in the case of unified shared memory (1,2)</li> <li>• When each kernel is launched and details on the launch (arguments, SIMD width, group information, etc.) (1,2)</li> <li>• Which Level Zero/OpenCL API functions are invoked (function name, arguments/parameters) (2)</li> </ul> <p>Values: (0, 1, 2)</p> <p>Default: 0</p>
LIBOMPTARGET_PLUGIN_PROFILE	<p>This variable enables the display of performance data for offloaded OpenMP code. It displays:</p> <ul style="list-style-type: none"> <li>• Total data transfer times (read and write)</li> <li>• Data allocation times</li> <li>• Module build times (just-in-time compile)</li> <li>• The execution time of each kernel.</li> </ul> <p>Values:</p> <ul style="list-style-type: none"> <li>• F - disabled</li> <li>• T - enabled with timings in milliseconds</li> <li>• T,usec - enabled with timings in microseconds</li> </ul> <p>Default: F</p> <p>Example: <code>export LIBOMPTARGET_PLUGIN_PROFILE=T,usec</code></p>
LIBOMPTARGET_PLUGIN	<p>This environment variable allows you to choose the backend used for OpenMP offload execution.</p>

Environment Variable	Description
	<p><b>NOTE</b></p> <p>The Level Zero backend is only supported for GPU devices.</p> <p>Values:</p> <ul style="list-style-type: none"> <li>• <code>LEVEL0</code> - uses the Level Zero backend</li> <li>• <code>OPENCL</code> - uses the OpenCL™ backend</li> </ul> <p>Default:</p> <ul style="list-style-type: none"> <li>• For GPU offload devices: <code>LEVEL0</code></li> <li>• For CPU or FPGA offload devices: <code>OPENCL</code></li> </ul>

### SYCL\* and DPC++ Environment Variables

DPC++ programs support all standard SYCL environment variables. The full list is available from [GitHub](#). Of interest for debugging are the following SYCL environment variables, plus an additional Level Zero environment variable.

Environment Variable	Description
<code>SYCL_DEVICE_FILTER</code>	<p>This complex environment variable allows you to limit the runtimes, compute device types, and compute device IDs used by the DPC++ runtime to a subset of all available combinations.</p> <p>The compute device IDs correspond to those returned by the SYCL API, <code>clinfo</code>, or <code>sycl-ls</code> (with the numbering starting at 0) and have no relation to whether the device with that ID is of a certain type or supports a specific runtime. Using a programmatic special selector (like <code>gpu_selector</code>) to request a device filtered out by <code>SYCL_DEVICE_FILTER</code> will cause an exception to be thrown.</p> <p>Refer to the Environment Variables descriptions in GitHub for additional details: <a href="https://github.com/intel/llvm/blob/sycl/sycl/doc/EnvironmentVariables.md">https://github.com/intel/llvm/blob/sycl/sycl/doc/EnvironmentVariables.md</a></p> <p>Example values include:</p> <ul style="list-style-type: none"> <li>• <code>opencl:cpu</code> - use only the OpenCL™ runtime on all available CPU devices</li> <li>• <code>opencl:gpu</code> - use only the OpenCL runtime on all available GPU devices</li> <li>• <code>opencl:gpu:2</code> - use only the OpenCL runtime on only the third device, which also has to be a GPU</li> <li>• <code>level_zero:gpu:1</code> - use only the Level Zero runtime on only the second device, which also has to be a GPU</li> <li>• <code>opencl:cpu,level_zero</code> - use only the OpenCL runtime on the CPU device, or the Level Zero runtime on any supported compute device</li> </ul> <p>Default: use all available runtimes and devices</p>
<code>SYCL_PI_TRACE</code>	<p>This environment variable enables debug output from the DPC++ runtime.</p>

Environment Variable	Description
	<p>Values:</p> <ul style="list-style-type: none"> <li>• 1 - report SYCL plugins and devices discovered and used</li> <li>• 2 - report SYCL API calls made, including arguments and result values</li> <li>• -1 - provides all available tracing</li> </ul> <p>Default: disabled</p>
ZE_DEBUG	<p>This environment variable enables debug output from the Level Zero backend when used with the DPC++ runtime. It reports:</p> <ul style="list-style-type: none"> <li>• Level Zero APIs called</li> <li>• Level Zero event information</li> </ul> <p>Value: variable defined with any value - enabled</p> <p>Default: disabled</p>

### Environment Variables that Produce Diagnostic Information for Support

The Level Zero backend provides a few environment variables that can be used to control behavior and aid in diagnosis.

- Level Zero Specification, core programming guide: <https://spec.oneapi.com/level-zero/latest/core/PROG.html#environment-variables>
- Level Zero Specification, tool programming guide: <https://spec.oneapi.com/level-zero/latest/tools/PROG.html#environment-variables>

An additional source of debug information comes from the Intel® Graphics Compiler, which is called by the Level Zero or OpenCL backends (used by both the OpenMP Offload and DPC++ Runtimes) at runtime or during Ahead-of-Time (AOT) compilation. Intel Graphics Compiler creates the appropriate executable code for the target offload device. The full list of these environment variables can be found at [https://github.com/intel/intel-graphics-compiler/blob/master/documentation/configuration\\_flags.md](https://github.com/intel/intel-graphics-compiler/blob/master/documentation/configuration_flags.md). The two that are most often needed to debug performance issues are:

- `IGC_ShaderDumpEnable=1` (default=0) causes all LLVM, assembly, and ISA code generated by the Intel® Graphics Compiler to be written to `/tmp/IntelIGC/<application_name>`
- `IGC_DumpToCurrentDir=1` (default=0) writes all the files created by `IGC_ShaderDumpEnable` to your current directory instead of `/tmp/IntelIGC/<application_name>`. Since this is potentially a lot of files, it is recommended to create a temporary directory just for the purpose of holding these files.

If you have a performance issue with your OpenMP offload or DPC++ offload application that arises between different versions of Intel® oneAPI, when using different compiler options, when using the debugger, and so on, then you may be asked to enable `IGC_ShaderDumpEnable` and provide the resulting files. For more information on compatibility, see [oneAPI Library Compatibility](#).

### Offload Intercept Tools

In addition to debuggers and diagnostics built into the offload software itself, it can be quite useful to monitor the API calls and data sent through the offload pipeline. For OpenCL™, you can add a library to `LD_LIBRARY_PATH` that will intercept and report on all OpenCL calls, and then use environment variables to control what diagnostic information to report to a file. For Level Zero, your application is run as an argument to the `ze_tracer` tool, which intercepts and reports on various aspects of Level Zero API calls based on how `ze_tracer` is called.

### Intercept Layer for OpenCL™ Applications

This library collects debugging and performance data when OpenCL is used as the backend to your DPC++ or OpenMP offload program. When OpenCL is used as the backend to your DPC++ or OpenMP offload program, this tool can help you detect buffer overwrites, memory leaks, mismatched pointers, and can provide more detailed information about runtime error messages (allowing you to diagnose these issues when either CPU, FPGA, or GPU devices are used for computation). Note that you will get nothing useful if you use `ze_tracer` on a program that uses the OpenCL backend, or the Intercept Layer for OpenCL Applications library on a program that uses the Level Zero backend.

Additional resources:

- Extensive information on building and using the Intercept Layer for OpenCL Applications is available from <https://github.com/intel/opencl-intercept-layer>.

---

**NOTE**

For best results, run `cmake` with the following flags: `-DENABLE_CLIPROF=TRUE -DENABLE_CLILOADER=TRUE`

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- Information about a similar tool (CLIntercept) is available from <https://github.com/gmeeker/clintercept> and <https://sourceforge.net/p/clintercept/wiki/Home/>.
- Information on the controls for the Intercept Layer for OpenCL Applications can be found at <https://github.com/intel/opencl-intercept-layer/blob/master/docs/controls.md>.
- Information about optimizing for GPUs is available from the [Intel oneAPI GPU Optimization Guide](#).

**ze\_tracer**

Like the Intercept Layer for OpenCL™ Applications, this tool collects debugging and performance data when then Level Zero is the backend for DPC++ or OpenMP\*, rather than OpenCL. Note that Level Zero can only be used as the backend for computations that happen on the GPU (there is no Level Zero backend for the CPU or FPGA at this time). The `ze_tracer` tool is part of the Profiling Tools Interfaces for GPU (PTI for GPU) project, found at <https://github.com/intel/pti-gpu>. Note that you will get nothing useful if you use `ze_tracer` on a program that uses the OpenCL backend, or the Intercept Layer for OpenCL™ Applications library on a program that uses the Level Zero backend.

The `ze_tracer` tool is distributed as source. Instructions for how to build the tool are available from [https://github.com/intel/pti-gpu/tree/master/tools/ze\\_tracer](https://github.com/intel/pti-gpu/tree/master/tools/ze_tracer). The tool provides the following features:

- Call logging: This mode allows you to trace all standard Level Zero (L0) API calls along with their arguments and return values annotated with time stamps. Among other things, this can give you supplemental information on any failures that occur when a host program tries to make use of an attached compute device.
- Host and device timing: These provide the duration of all API calls, the duration of each kernel, and application runtime for the entire application.
- Device Timeline mode: Gives time stamps for each device activity. All the time stamps are in the same (CPU) time scale.
- Browser visualization: It is possible to dump results of Call Tracing and Device Timeline modes into a trace (JSON) file to visualize it in browser.

These data can help debug offload failures or performance issues.

Additional resources:

- [Profiling Tools Interfaces for GPU \(PTI for GPU\) GitHub project](#)
- [ze\\_tracer GitHub page](#)

## Intel® Distribution for GDB\*

The Intel Distribution for GDB\* is an application debugger that allows you to inspect and modify the program state. With the debugger, both the host part of your application and kernels that are offloaded to a device can be debugged seamlessly in the same debug session. The debugger supports the CPU, GPU, and FPGA-emulation devices. Major features of the tool include:

- Automatically attaching to the GPU device to listen to debug events
- Automatically detecting JIT-compiled, or dynamically loaded, kernel code for debugging
- Defining breakpoints (both inside and outside of a kernel) to halt the execution of the program
- Listing the threads; switching the current thread context
- Listing active SIMD lanes; switching the current SIMD lane context per thread
- Evaluating and printing the values of expressions in multiple thread and SIMD lane contexts
- Inspecting and changing register values
- Disassembling the machine instructions
- Displaying and navigating the function call-stack
- Source- and instruction-level stepping
- Non-stop and all-stop debug mode
- Recording the execution using Intel Processor Trace (CPU only)

For more information and links to full documentation for Intel Distribution for GDB, see *Get Started with Intel Distribution for GDB on [Linux\\* Host](#) | [Windows\\* Host](#)*.

## Intel® Inspector for Offload

Intel® Inspector is a dynamic memory and threading error checking tool for users developing serial and multithreaded applications. It can be used to verify correctness of the native part of the application as well as dynamically generated offload code.

Unlike the tools and techniques above, Intel Inspector cannot be used to catch errors in offload code that is communicating with a GPU or an FPGA. Instead, Intel Inspector requires that the DPC++ or OpenMP runtime needs to be configured to execute kernels on CPU target. In general, it requires definition of the following environment variables prior to an analysis run.

- To configure a DPC++ application to run kernels on a CPU device

```
export SYCL_DEVICE_FILTER=opencl:cpu
```

- To configure an OpenMP application to run kernels on a CPU device

```
export OMP_TARGET_OFFLOAD=MANDATORY
export LIBOMPTARGET_DEVICETYPE=cpu
```

- To enable code analysis and tracing in JIT compilers or runtimes

```
export CL_CONFIG_USE_VTUNE=True
export CL_CONFIG_USE_VECTORIZER=false
```

Use one of the following commands to start analysis from the command line. You can also start from the Intel Inspector graphical user interface.

- Memory: `inspxe-cl -c mi3 -- <app> [app_args]`
- Threading: `inspxe-cl -c ti3 -- <app> [app_args]`

View the analysis result using the following command: `inspxe-cl -report=problems -report-all`

If your DPC++ or OpenMP Offload program passes bad pointers to the OpenCL™ backend, or passes the wrong pointer to the backend from the wrong thread, Intel Inspector should flag the issue. This may make the problem easier to find than trying to locate it using the intercept layers or the debugger.

Additional details are available from the *Intel Inspector User Guide for [Linux\\* OS](#) | [Windows\\* OS](#)*.



## Trace the Offload Process

When a program that offloads computation to a GPU is started, there are a lot of moving parts involved in program execution. Machine-independent code needs to be compiled to machine-dependent code, data and binaries need to be copied to the device, results returned, etc. This section will discuss how to trace all this activity using the tools described in [oneAPI Debug Tools](#).

### Kernel Setup Time

Before offload code can run on the device, the machine-independent version of the kernel needs to be compiled for the target device, and the resulting code needs to be copied to the device. This can complicate/skew benchmarking if this kernel setup time is not considered. Just-in-time compilation can also introduce a noticeable delay when debugging an offload application.

If you have an OpenMP\* offload program, setting `LIBOMPTARGET_PLUGIN_PROFILE=T[,usec]` explicitly reports the amount of time required to build the offload code "ModuleBuild", which you can compare to the overall execution time of your program.

Kernel setup time is more difficult to determine if you have a DPC++ offload program.

- If Level Zero is your backend, you can derive kernel setup time from the Device Timing and Device Timeline returned by `ze_tracer`.
- If OpenCL™ is your backend, you may be able to derive the information by setting the `BuildLogging`, `KernelInfoLogging`, `CallLogging`, `CallLoggingElapsedTime`, `KernelInfoLogging`, `HostPerformanceTiming`, `HostPerformanceTimeLogging`, `ChromeCallLogging`, or `CallLoggingElapsedTime` flags when using the Intercept Layer for OpenCL Applications to get similar information.

You can also use this technique to supplement the information returned by `LIBOMPTARGET_PLUGIN_PROFILE=T`.

### Monitoring Buffer Creation, Sizes, and Copies

Understanding when buffers are created, how many buffers are created, and whether they are reused or constantly created and destroyed can be key to optimizing the performance of your offload application. This may not always be obvious when using a high-level programming language like OpenMP or DPC++, which can hide a lot of the buffer management from the user.

At a high level, you can track buffer-related activities using the `LIBOMPTARGET_DEBUG` and `SYCL_PI_TRACE` environment variables when running your program. `LIBOMPTARGET_DEBUG` gives you more information than `SYCL_PI_TRACE` - it reports the addresses and sizes of the buffers created. By contrast, `SYCL_PI_TRACE` just reports the API calls, with no information you can easily tie to the location or size of individual buffers.

At a lower level, if you are using Level Zero as your backend, the Call Logging mode of `ze_tracer` will give you information on all Level Zero API calls, including their arguments. This can be useful because, for example, a call for buffer creation (such as `zeMemAllocDevice`) will give you the size of the resulting buffer being passed to and from the device. `ze_tracer` also allows you to dump all the Level Zero device-side activities (including memory transfers) in Device Timeline mode. For each activity one can get append (to command list), submit (to queue), start and end times.

If you are using OpenCL as your backend, setting the `CallLogging`, `CallLoggingElapsedTime`, and `ChromeCallLogging` flags when using the Intercept Layer for OpenCL Applications should give you similar information.

### Total Transfer Time

Comparing total data transfer time to kernel execution time can be important for determining whether it is profitable to offload a computation to a connected device.

If you have an OpenMP offload program, setting `LIBOMPTARGET_PLUGIN_PROFILE=T[,usec]` explicitly reports the amount of time required to build ("DataAlloc"), read ("DataRead"), and write data ("DataWrite") to the offload device (although only in aggregate).

Data transfer times can be more difficult to determine if you have a DPC++ program.

- If Level Zero is your backend, you can derive total data transfer time from the Device Timing and Device Timeline returned by `ze_tracer`.
- If OpenCL is your backend, you may be able to derive the information by setting the `BuildLogging`, `KernelInfoLogging`, `CallLogging`, `CallLoggingElapsedTime`, `KernelInfoLogging`, `HostPerformanceTiming`, `HostPerformanceTimeLogging`, `ChromeCallLogging`, or `CallLoggingElapsedTime` flags when using the Intercept Layer for OpenCL Applications.

## Kernel Execution Time

If you have an OpenMP offload program, setting `LIBOMPTARGET_PLUGIN_PROFILE=T[,usec]` explicitly reports the total execution time of every offloaded kernel ("Kernel#...").

For DPC++ offload programs:

- If Level Zero is your backend, the Device Timing mode of `ze_tracer` will give you the device-side execution time for every kernel.
- If OpenCL is your backend, you may be able to derive the information by setting the `CallLoggingElapsedTime`, `DevicePerformanceTiming`, `DevicePerformanceTimeKernelInfoTracking`, `DevicePerformanceTimeLWSTracking`, `DevicePerformanceTimeGWSTracking`, `ChromePerformanceTiming`, `ChromePerformanceTimingInStages` flags when using the Intercept Layer for OpenCL Applications.

## When Device Kernels are Called and Threads are Created

On occasion, offload kernels are created and transferred to the device a long time before they actually start executing (usually only after all data required by the kernel has also been transferred, along with control).

You can set a breakpoint in a device kernel using the Intel® Distribution for GDB\*. From there, you can query kernel arguments, monitor thread creation and destruction, list the current threads and their current positions in the code (using "info thread"), and so on.

## Debug the Offload Process

### Run with Different Runtimes or Compute Devices

When an offload program fails to run correctly or produces incorrect results, a relatively quick sanity check is to run the application on a different runtime (OpenCL™ vs. Level Zero) or compute device (CPU vs. GPU) using `LIBOMPTARGET_PLUGIN` and `OMP_TARGET_OFFLOAD` for OpenMP\* applications, and `SYCL_DEVICE_FILTER` for DPC++ applications. Errors that reproduce across runtimes mostly eliminate the runtime as being a problem. Errors that reproduce on all available devices mostly eliminates bad hardware as the problem.

### Debug CPU Execution

Offload code has two options for CPU execution: either the "host" implementation, or the CPU version of OpenCL. The "host" implementation is a truly native implementation of the offloaded code, meaning it can be debugged like any of the non-offloaded code. The CPU version of OpenCL, while it goes through the OpenCL runtime and code generation process, eventually ends up as normal parallel code running under a TBB runtime. Again, this provides a familiar debugging environment with familiar assembly and parallelism mechanisms. Pointers have meaning through the entire stack, and data can be directly inspected. There are also no memory limits beyond the usual limits for any operating system process.

Finding and fixing errors in CPU offload execution often solves errors seen in GPU offload execution with much less pain, and without requiring use of a system with an attached GPU or other accelerator.

For OpenMP applications, to get the "host" implementation, remove the "target" or "device" constructs, replacing them with normal host OpenMP code. If `LIBOMPTARGET_PLUGIN=OPENCL` and offload to the GPU is disabled, then the offloaded code runs under the OpenMP runtime with TBB providing parallelism.

For DPC++ applications, with `SYCL_DEVICE_FILTER=host` the "host" device is actually single-threaded, which may help you determine if threading issues, such as data races and deadlocks, are the source of execution errors. Setting `SYCL_DEVICE_FILTER=opencl:cpu` uses the CPU OpenCL runtime, which also uses TBB for parallelism.

## Debug GPU Execution Using Intel® Distribution for GDB\*

Intel® Distribution for GDB\* is extensively documented in *Get Started with Intel Distribution for GDB on Linux\* Host | Windows\* Host*. However, since debugging applications with GDB\* on a GPU differs slightly from the process on the host (some commands are used differently and you might see some unfamiliar output), some of those differences are summarized here.

The [Debugging with Intel Distribution for GDB on Linux OS Host Tutorial](#) shows a sample debug session where we start a debug session of a DPC++ program, define a breakpoint inside the kernel, run the program to offload to the GPU, print the value of a local variable, switch to the SIMD lane 5 of the current thread, and print the variable again.

As in normal GDB\*, for a command `<CMD>`, use the `help <CMD>` command of GDB to read the information text for `<CMD>`. For example:

```
(gdb) help info threads
Display currently known threads.
Usage: info threads [OPTION]... [ID]...
If ID is given, it is a space-separated list of IDs of threads to display.
Otherwise, all threads are displayed.

Options:
  -gid
    Show global thread IDs.
```

## Inferiors, Threads, and SIMD Lanes Referencing in GDB\*

The threads of the application can be listed using the debugger. The printed information includes the thread ids and the locations that the threads are currently stopped at. For the GPU threads, the debugger also prints the active SIMD lanes.

In the example referenced above, you may see some unfamiliar formatting used when threads are displayed via the GDB "info threads" command:

Id	Target Id	Frame
1.1	Thread <id omitted>	<frame omitted>
1.2	Thread <id omitted>	<frame omitted>
2.1	Thread 1610612736	(inactive)
* 2.2:1	Thread 1073741824	<frame> at array-transform.cpp:61
2.2:[3 5 7]	Thread 1073741824	<frame> at array-transform.cpp:61
2.3:[1 3 5 7]	Thread 1073741888	<frame> at array-transform.cpp:61
2.4:[1 3 5 7]	Thread 1073742080	<frame> at array-transform.cpp:61

Here, GDB is displaying the threads with the following format:

```
<inferior_number>.<thread_number>:<SIMD Lane/s>
```

So, for example, the thread id "2.3:[1 3 5 7]" refers to SIMD lanes 1, 3, 5, and 7 of thread 3 running on inferior 2.

An "inferior" in the GDB terminology is the process that is being debugged. In the debug session of a program that offloads to the GPU, there will typically be two inferiors; one "native" inferior representing the host part of the program (inferior 1 above), and another "remote" inferior representing the GPU device (inferior 2 above). Intel Distribution for GDB automatically creates the GPU inferior - no extra steps are required.

When you print the value of an expression, the expression is evaluated in the context of the current thread's current SIMD lane. You can switch the thread as well as the SIMD lane to change the context using the "thread" command such as "thread 3:4", "thread :6", or "thread 7". The first command makes a switch to the thread 3 and SIMD lane 4. The second command switches to SIMD lane 6 within the current thread. The third command switches to thread 7. The default lane selected will either be the previously selected lane, if it is active, or the first active lane within the thread.

The "thread apply command" may be similarly broad or focused (which can make it easier to limit the output from, for example, a command to inspect a variable). For more details and examples about debugging with SIMD lanes, see the [Debugging with Intel Distribution for GDB on Linux OS Host Tutorial](https://sourceware.org/gdb/current/onlinedocs/gdb/Threads.html).

More information about threads and inferiors in GDB can be found from <https://sourceware.org/gdb/current/onlinedocs/gdb/Threads.html> and <https://sourceware.org/gdb/current/onlinedocs/gdb/Inferiors-Connections-and-Programs.html#Inferiors-Connections-and-Programs>.

### Controlling the Scheduler

By default, when a thread hits a breakpoint, the debugger stops all the threads before displaying the breakpoint hit event to the user. This is the all-stop mode of GDB. In the non-stop mode, the stop event of a thread is displayed while the other threads run freely.

In all-stop mode, when a thread is resumed (for example, to resume normally with the `continue` command, or for stepping with the `next` command), all the other threads are also resumed. If you have some breakpoints set in threaded applications, this can quickly get confusing, as the next thread that hits the breakpoint may not be the thread you are following.

You can control this behavior using the `set scheduler-locking` command to prevent resuming other threads when the current thread is resumed. This is useful to avoid intervention of other threads while only the current thread executes instructions. Type `help set scheduler-locking` for the available options, and see <https://sourceware.org/gdb/current/onlinedocs/gdb/Thread-Stops.html> for more information. Note that SIMD lanes cannot be resumed individually; they are resumed together with their underlying thread.

In non-stop mode, by default, only the current thread is resumed. To resume all threads, pass the "-a" flag to the `continue` command.

### Dumping Information on One or More Threads/Lanes (Thread Apply)

Commands for inspecting the program state are typically executed in the context of the current thread's current SIMD lane. Sometimes it is desired to inspect a value in multiple contexts. For such needs, the `thread apply` command can be used. For instance, the following executes the `print element` command for the SIMD lanes 3-5 of Thread 2.5:

```
(gdb) thread apply 2.5:3-5 print element
```

Similarly, the following runs the same command in the context of SIMD lane 3, 5, and 6 of the current thread:

```
(gdb) thread apply :3 :5 :6 print element
```

### Stepping GPU Code After a Breakpoint

To stop inside the kernel that is offloaded to the GPU, simply define a breakpoint at a source line inside the kernel. When a GPU thread hits that source line, the debugger stops the execution and shows the breakpoint hit. To single-step a thread over a source-line, use the `step` or `next` commands. The `step` commands steps into functions while `next` steps over calls. Before stepping, we recommend to `set scheduler-locking step` to prevent intervention of other threads.

## Building a DPC++ Executable for Use with Intel® Distribution for GDB\*

Much like when you want to debug a host application, you need to set some additional flags to create a binary that can be debugged on the GPU. See [Get Started with Intel Distribution for GDB on Linux\\* Host](#) for details.

For a smooth debug experience when using the just-in-time (JIT) compilation flow, enable debug information emission from the compiler via the `-g` flag, and disable optimizations via the `-O0` flag for both the host and JIT-compiled kernel of the application. The flags for the kernel are taken during link time. For example:

- Compile your program using: `dpcpp -g -O0 -c myprogram.cpp`
- Link your program using: `dpcpp -g -O0 myprogram.o`

If you are using CMake to configure the build of your program, use the `Debug` type for the `CMAKE_BUILD_TYPE`, and append `-O0` to the `CMAKE_CXX_FLAGS_DEBUG` variable. For example: `set (CMAKE_CXX_FLAGS_DEBUG "${CMAKE_CXX_FLAGS_DEBUG} -O0")`

Applications that are built for debugging may take a little longer to start up than when built with the usual "release" level of optimization. Thus, your program may appear to run a little more slowly when started in the debugger. If this causes problems, developers of larger applications may want to use ahead-of-time (AOT) compilation to JIT the offload code when their program is built, rather than when it is run (warning, this may also take longer to build when using `-g -O0`). For more information, see [Compilation Flow Overview](#).

When doing ahead-of-time compilation for GPU, you must use a device type that fits your target device. Run the following command to see the available GPU device options on your current machine: `ocloc compile --help`

Additionally, the debug mode for the kernel must be enabled. The following example AoT compilation command targets the KBL device:

```
dpcpp -g -O0 -fsycl-targets=spir64_gen-unknown-unknown-sycldevice \
-Xs "-device kbl -internal_options -cl-kernel-debug-enable -options -cl-opt-disable"
myprogram.cpp
```

## Building an OpenMP\* Executable for use with Intel® Distribution for GDB\*

Compile and link your program using the `-g -O0` flags. For example:

```
icpx -fopenmp -O0 -fopenmp-targets=spir64 -c -g myprogram.cpp
icpx -fopenmp -O0 -fopenmp-targets=spir64 -g myprogram.o
```

Set the following environment variables to disable optimizations and enable debug info for the kernel:

```
export LIBOMPTARGET_OPENCL_COMPILATION_OPTIONS="-g -cl-opt-disable"
export LIBOMPTARGET_LEVEL0_COMPILATION_OPTIONS="-g -cl-opt-disable"
```

Ahead-of-time (AOT) compilation is currently not supported for OpenMP.

## Debugging GPU Execution Using Offload Intercept Tools

A common issue with offload programs is that they may fail to run at all, instead giving a generic OpenCL™ error with little additional information. Both the Intercept Layer for OpenCL Applications and `ze_tracer` can be used to get more information about these errors, often helping the developer identify the source of the problem.

### Intercept Layer for OpenCL Applications

Using this library, in particular the `BuildLogging`, `ErrorLogging`, and `USMChecking=1` options, you can often find the source of the error.

1. Create a `clintercept.conf` file in the home directory with the following content:

```
SimpleDumpProgramSource=1
CallLogging=1
LogToFile=1
//KernelNameHashTracking=1
BuildLogging=1
ErrorLogging=1
USMChecking=1
//ContextCallbackLogging=1
// Profiling knobs
KernelInfoLogging=1
DevicePerformanceTiming=1
DevicePerformanceTimeLWSTracking=1
DevicePerformanceTimeGWSTracking=1
```

2. Run the application with `cliloader` as follows:

```
<OCL_Intercept_Install_Dir>/bin/cliloader/cliloader -d ./<app_name> <app_args>
```

3. Review the following results in the `~CLIntercept_Dump/<app_name>` directory:

- `clintercept_report.txt`: Profiling results
- `clintercept_log.txt`: Log of OpenCL™ calls used to debug OpenCL issues

The following snippet is from an example log file generated by a program that returned the runtime error:

`CL_INVALID_ARG_VALUE (-50)`

```
...
<<<< clSetKernelArgMemPointerINTEL -> CL_SUCCESS
>>>>
clGetKernelInfo( _ZTSZZ10outer_coreiP5mesh_i16dpct_type_1c0e3516dpct_type_60257cS2_S2_S2_S2_S2_S2_S2_S2_S2_iENKU1RN2c14sycl7handlerEE197->45c1ES6_EU1NS4_7nd_itemILi3EEEE225->13 ):
param_name = CL_KERNEL_CONTEXT (1193)
<<<< clGetKernelInfo -> CL_SUCCESS
>>>>
clSetKernelArgMemPointerINTEL( _ZTSZZ10outer_coreiP5mesh_i16dpct_type_1c0e3516dpct_type_60257cS2_S2_S2_S2_S2_S2_S2_S2_S2_iENKU1RN2c14sycl7handlerEE197->45c1ES6_EU1NS4_7nd_itemILi3EEEE225->13 ): kernel = 0xa2d51a0, index = 3, value = 0x41995e0
mem pointer 0x41995e0 is an UNKNOWN pointer and no device support shared system pointers!
ERROR! clSetKernelArgMemPointerINTEL returned CL_INVALID_ARG_VALUE (-50)
<<<< clSetKernelArgMemPointerINTEL -> CL_INVALID_ARG_VALUE
```

In this example, the following values help with debugging the error:

- `ZTSZZ10outer_coreiP5mesh`
- `index = 3, value = 0x41995e0`

Using this data, you can identify which kernel had the problems, what argument was problematic, and why.

## ze\_tracer

Similar to Intercept Layer for OpenCL Applications, the `ze_tracer` tool can help find the source of errors for a Level Zero runtime.

To use the `ze_tracer` tool:

1. Use Call Logging mode to run the application. Redirecting the tool output to a file is optional, but recommended.

```
./ze_tracer -c ./<app_name> <app_args> [2> log.txt]
```

## 2. Review the call trace to figure out the error (log.txt). For example:

```
>>>> [102032049] zeKernelCreate: hModule = 0x55a68c762690 desc = 0x7fff865b5570 {29 0 0 GEMM}
phKernel = 0x7fff865b5438 (hKernel = 0)
<<<< [102060428] zeKernelCreate [28379 ns] hKernel = 0x55a68c790280 -> ZE_RESULT_SUCCESS (0)
...
>>>> [102249951] zeKernelSetGroupSize: hKernel = 0x55a68c790280 groupSizeX = 256 groupSizeY = 1
groupSizeZ = 1
<<<< [102264632] zeKernelSetGroupSize [14681 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [102278558] zeKernelSetArgumentValue: hKernel = 0x55a68c790280 argIndex = 0 argSize = 8
pArgValue = 0x7fff865b5440
<<<< [102294960] zeKernelSetArgumentValue [16402 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [102308273] zeKernelSetArgumentValue: hKernel = 0x55a68c790280 argIndex = 1 argSize = 8
pArgValue = 0x7fff865b5458
<<<< [102321981] zeKernelSetArgumentValue [13708 ns] -> ZE_RESULT_ERROR_INVALID_ARGUMENT
(2013265924)
>>>> [104428764] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 2 argSize = 8
pArgValue = 0x7ffe289c7e60
<<<< [104442529] zeKernelSetArgumentValue [13765 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [104455176] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 3 argSize = 4
pArgValue = 0x7ffe289c7e2c
<<<< [104468472] zeKernelSetArgumentValue [13296 ns] -> ZE_RESULT_SUCCESS (0)
...
```

The example log data shows:

- A level zero API call that causes the problem (zeKernelSetArgumentValue)
- The problem reason (ZE\_RESULT\_ERROR\_INVALID\_ARGUMENT)
- The argument index (argIndex = 1)
- An invalid value location (pArgValue = 0x7fff865b5458)
- A kernel handle (hKernel = 0x55a68c790280), which provides the name of the kernel for which this issue is observed (GEMM)

More information could be obtained by omitting the "redirection to file" option and dumping all the output (application output + tool output) into one stream. Dumping to one stream may help determine the source of the error in respect to application output (for example, you can find that the error happens between application initialization and the first phase of computations):

```
Level Zero Matrix Multiplication (matrix size: 1024 x 1024, repeats 4 times)
Target device: Intel(R) Graphics [0x3ea5]
...
>>>> [104131109] zeKernelCreate: hModule = 0x55af5f39ca10 desc = 0x7ffe289c7f80 {29 0 0 GEMM}
phKernel = 0x7ffe289c7e48 (hKernel = 0)
<<<< [104158819] zeKernelCreate [27710 ns] hKernel = 0x55af5f3ca600 -> ZE_RESULT_SUCCESS (0)
...
>>>> [104345820] zeKernelSetGroupSize: hKernel = 0x55af5f3ca600 groupSizeX = 256 groupSizeY = 1
groupSizeZ = 1
<<<< [104360082] zeKernelSetGroupSize [14262 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [104373679] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 0 argSize = 8
pArgValue = 0x7ffe289c7e50
<<<< [104389443] zeKernelSetArgumentValue [15764 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [104402448] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 1 argSize = 8
pArgValue = 0x7ffe289c7e68
<<<< [104415871] zeKernelSetArgumentValue [13423 ns] -> ZE_RESULT_ERROR_INVALID_ARGUMENT
(2013265924)
>>>> [104428764] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 2 argSize = 8
pArgValue = 0x7ffe289c7e60
<<<< [104442529] zeKernelSetArgumentValue [13765 ns] -> ZE_RESULT_SUCCESS (0)
>>>> [104455176] zeKernelSetArgumentValue: hKernel = 0x55af5f3ca600 argIndex = 3 argSize = 4
```

```

pArgValue = 0x7ffe289c7e2c
<<<< [104468472] zeKernelSetArgumentValue [13296 ns] -> ZE_RESULT_SUCCESS (0)
...
Matrix multiplication time: 0.0427564 sec
Results are INCORRECT with accuracy: 1
...
Matrix multiplication time: 0.0430995 sec
Results are INCORRECT with accuracy: 1
...
Total execution time: 0.381558 sec

```

## Correctness

Offload code is often used for kernels that can efficiently process large amounts of information on the attached compute device, or to generate large amounts of information from some input parameters. If these kernels are running without crashing, this can often mean that you learn that they are not producing the correct results much later in program execution.

In these cases, it can be difficult to identify which kernel is producing incorrect results. One technique for finding the kernel producing incorrect data is to run the program twice, once using a purely host-based implementation, and once using an offload implementation, capturing the inputs and outputs from every kernel (often to individual files). Now compare the results and see which kernel call is producing unexpected results (within a certain epsilon - the offload hardware may have a different order of operation or native precision that causes the results to differ from the host code in the last digit or two).

Once you know which kernel is producing incorrect results, use Intel Distribution for GDB to determine the reason. See the [Debugging with Intel Distribution for GDB on Linux OS Host Tutorial](#) for basic information and links to more detailed documentation.

Both DPC++ and OpenMP\* also allow for the use of standard language print mechanisms (`printf` for DPC++ and C++ OpenMP offload, `print *`, ... for Fortran OpenMP offload) within offloaded kernels, which you can use to verify correct operation while they run. Print the thread and SIMD lane the output is coming from and consider adding synchronization mechanisms to ensure printed information is in a consistent state when printed. Examples for how to do this in DPC++ using the stream class can be found in the [Intel oneAPI GPU Optimization Guide](#). You could use a similar approach to the one described for DPC++ for OpenMP offload.

### Tip

Using `printf` can be verbose in DPC++ kernels. To simplify, add the following macro:

```

#ifdef __SYCL_DEVICE_ONLY__
    #define CL_CONSTANT __attribute__((opencl_constant))
#else
    #define CL_CONSTANT
#endif
#define PRINTF(format, ...) { \
    static const CL_CONSTANT char _format[] = format; \
    sycl::ONEAPI::experimental::printf(_format, ## __VA_ARGS__) }

```

Usage example: `PRINTF("My integer variable:%d\n", (int) x);`

## Failures

Just-in-time (JIT) compilation failures that occur at runtime due to incorrect use of the DPC++ or OpenMP\* offload languages will cause your program to exit with an error.



In the case of DPC++, if you cannot find these using ahead-of-time compilation of your DPC++ code, selecting the OpenCL backend, setting SimpleDumpProgramSource and BuildLogging, and using the Intercept Layer for OpenCL Applications may help identify the kernel with the syntax error.

Logic errors can also result in crashes or error messages during execution. Such issues can include:

- Passing a buffer that belongs to the wrong context to a kernel
- Passing the "this" pointer to a kernel rather than a class element
- Passing a host buffer rather than a device buffer
- Passing an uninitialized pointer, even if it is not used in the kernel

Using the Intel® Distribution for GDB\* (or even the native GDB), if you watch carefully, you can record the addresses of all contexts created and verify that the address being passed to an offload kernel belongs to the correct context. Likewise, you can verify that the address of a variable passed matches that of the variable itself, and not its containing class.

It may be easier to track buffers and addresses using the Intercept Layer for OpenCL™ allocation or ze\_tracer and choosing the appropriate backend. When using the OpenCL backend, setting CallLogging, BuildLogging, ErrorLogging, and USMChecking and running your program should produce output that explains what error in your code caused the generic OpenCL error to be produced. Using ze\_tracer's Call Logging or Device Timeline should give additional enhanced error information to help you better understand the source of generic errors from the Level Zero backend. This can help locate many of the logic errors mentioned above.

If the code is giving an error when offloading to a device using the Level Zero backend, try using the OpenCL backend. If the program works, report an error against the Level Zero backend. If the error reproduces in the OpenCL backend to the device, try using the OpenCL CPU backend. In OpenMP offload, this can be specified by setting OMP\_TARGET\_OFFLOAD to CPU. For DPC++, this can be done by setting SYCL\_DEVICE\_FILTER=opencl:cpu. Debugging with everything on the CPU can be easier, and removes complications caused by data copies and translation of the program to a non-CPU device.

As an example of a logic issue that can get you in trouble, consider what is captured by the lambda function used to implement the parallel\_for in this DPC++ snippet.

```
class MyClass {
private:
    int *data;
    int factor;
    :
void run() {
    :
    auto data2 = data;
    auto factor2 = factor;
    {
        dpct::get_default_queue_wait().submit([&](cl::sycl::handler &cgh)
        {
            auto dpct_global_range = grid * block;
            auto dpct_local_range = block;
            cgh.parallel_for<dpct_kernel_name<class kernel_855a44>>>(
                cl::sycl::nd_range<1>(
                    cl::sycl::range<1> dpct_global_range.get(0)),
                    cl::sycl::range<1>( dpct_local_range.get(0))),
                    [=](cl::sycl::nd_item<3> item_ct1)
                {
                    {
                        kernel(data, b, factor, LEN, item_ct1);    // This blows up
                    };
                });
            });
        }
    } // run
} // MyClass
```

In the above code snippet, the program crashes because [=] will copy by value all variables used inside the lambda. In the example it may not be obvious that "factor" is really "this->factor" and "data" is really "this->data," so "this" is the variable that is captured for the use of "data" and "factor" above. OpenCL or Level Zero will crash with an illegal arguments error in the "kernel(data, b, factor, LEN, item\_ctl)" call.

The fix is the use of local variables `auto data2` and `auto factor2`. "auto factor2 = factor" becomes "int factor2 = this->factor" so using factor2 inside the lambda with [=] would capture an "int". We would rewrite the inner section as "kernel(data2, b, factor2, LEN, item\_ctl);".

---

#### NOTE

This issue is commonly seen when migrating CUDA\* kernels. You can also resolve the issue by keeping the same CUDA kernel launch signature and placing the command group and lambda inside the kernel itself.

---

Using the Intercept Layer for OpenCL™ allocation or `ze_tracer`, you would see that the kernel was called with two identical addresses, and the extended error information would tell you that you are trying to copy a non-trivial data structure to the offload device.

Note that if you are using unified shared memory (USM), and "MyClass" is allocated in USM, the above code will work. However, if only "data" is allocated in USM, then the program will crash for the above reason.

In this example, note that you can also re-declare the variables in local scope with the same name so that you don't need to change everything in the kernel call.

Intel® Inspector can also help diagnose these sorts of failures. If you set the following environment variables and then run Memory Error Analysis on offload code using the CPU device, Intel Inspector will flag many of the above issues:

- OpenMP\*
  - `export OMP_TARGET_OFFLOAD=CPU`
  - `export OMP_TARGET_OFFLOAD=MANDATORY`
  - `export LIBOMPTARGET_PLUGIN=OPENCL`
- DPC++
  - `export SYCL_DEVICE_FILTER=opencl:cpu`
  - Or initialize your queue with a CPU selector to force use of the OpenCL CPU device: `cl::sycl::queue Queue(cl::sycl::cpu_selector{});`
- Both
  - `export CL_CONFIG_USE_VTUNE=True`
  - `export CL_CONFIG_USE_VECTORIZER=false`

---

#### NOTE

A crash can occur when optimizations are turned on during the compilation process. If turning off optimizations causes your crash to disappear, use `-g -[optimization level]` for debugging. For more information, see the [Intel oneAPI DPC++/C++ Compiler Developer Guide and Reference](#).

---

## Optimize Offload Performance

Offload performance optimization basically boils down to three tasks:

1. Minimize the number and size of data transfers to and from the device while maximizing execution time of the kernel on the device.

2. When possible, overlap data transfers to/from the device with computation on the device.
3. Maximize the performance of the kernel on the device.

While it is possible to take explicit control of data transfers in both OpenMP\* offload and DPC++, you also can allow this to happen automatically. In addition, because the host and offload device operate mostly asynchronously, even if you try to take control over data transfers, the transfers may not happen in the expected order, and may take longer than anticipated. When data used by both the device and the host is stored in unified shared memory (USM), there is another transparent layer of data transfers happening that also can affect performance.

Resources:

- [Intel oneAPI GPU Optimization Guide](#)
- [Intel oneAPI FPGA Optimization Guide](#)

## Buffer Transfer Time vs Execution Time

Transferring any data to or from an offload device is relatively expensive, requiring memory allocations in user space, system calls, and interfacing with hardware controllers. Unified shared memory (USM) adds to these costs by requiring that some background process keeps memory being modified on either the host or offload device in sync. Furthermore, kernels on the offload device must wait to run until all the input or output buffers they need to run are set up and ready to use.

All this overhead is roughly the same no matter how much information you need to transfer to or from the offload device in a single data transfer. Thus, it is much more efficient to transfer 10 numbers in bulk rather than one at a time. Still, every data transfer is expensive, so minimizing the total number of transfers is also very important. If, for example, you have some constants that are needed by multiple kernels, or during multiple invocations of the same kernel, transfer them to the offload device once and reuse them, rather than sending them with every kernel invocation. Finally, as might be expected, single large data transfers take more time than single small data transfers.

The number and size of buffers sent is only part of the equation. Once the data is at the offload device, consider how long the resulting kernel executes. If it runs for less time than it takes to transfer the data to the offload device, it may not be worthwhile to offload the data in the first place unless the time to do the same operation on the host is longer than the combined kernel execution and data transfer time.

Finally, consider how long the offload device is idle between the execution of one kernel and the next. A long wait could be due data transfer or just the nature of the algorithm on the host. If the former, it may be worthwhile to overlap data transfer and kernel execution, if possible.

In short, execution of code on the host, execution of code on the offload device, and data transfer is quite complex. The order and time of such operations isn't something you can gain through intuition, even in the simplest code. You need to make use of tools like those listed below to get a visual representation of these activities and use that information to optimize your offload code.

## Intel® VTune™ Profiler

In addition to giving you detailed performance information on the host, VTune can also provide detailed information about performance on a connected GPU. Setup information for GPUs is available from the [Intel VTune Profiler User Guide](#).

Intel VTune Profiler's GPU Offload view gives you an overview of the hotspots on the GPU, including the amount of time spent for data transfer to and from each kernel. The GPU Compute/Media Hotspots view allows you to dive more deeply into what is happening to your kernels on the GPU, such as by using the **Dynamic Instruction Count** to view a micro analysis of the GPU kernel performance. With these profiling modes, you can observe how data transfer and compute occur over time, determine if there is enough work for a kernel to run effectively, learn how your kernels use the GPU memory hierarchy, and so on.

Additional details about these analysis types is available from the [Intel VTune Profiler User Guide](#). A detailed look at optimizing for GPU using VTune Profiler is available from the [Optimize Applications for Intel GPUs with Intel VTune Profiler](#) page.

You can also use Intel VTune Profiler to capture kernel execution time. The following commands provide light-weight profiling results:

- **Collect**
  - **Level zero backend:** `vtune -collect-with runss -knob enable-gpu-level-zero=true -finalization-mode=none -app-working-dir <app_working_dir> - <app>`
  - **OpenCL™ backend:** `vtune -collect-with runss -knob collect-programming-api=true -finalization-mode=none -app-working-dir <app_working_dir> - <app>`
- **Report:** `vtune --report hotspots --group-by=source-computing-task --sort-desc="Total Time" -r vtune-test`

## Intel® Advisor

Intel® Advisor provides two features that can help you get the improved performance when offloading computation to GPU:

- **Offload Modeling** can watch your host OpenMP\* program and recommend parts of it that would be profitably offloaded to the GPU. It also allows you to model a variety of different target GPUs, so that you can learn if offload will be profitable on some but not others. Offload Advisor gives detailed information on what factors may bound offload performance.
- **GPU Roofline analysis** can watch your application when it runs on the GPU, and graphically show how well each kernel is making use of the memory subsystem and compute units on the GPU. This can let you know how well your kernel is optimized for the GPU.

To run these modes on an application that already does some offload, you need to set up your environment to use the OpenCL™ device on the CPU for analysis. Instructions are available from the [Intel Advisor User Guide](#).

Offload modeling does not require that you have already modified your application to use a GPU - it can work entirely on host code.

Resources:

- [Intel Advisor Cookbook: GPU Offload](#)
- [Get Started with Offload Modeling](#)
- [Get Started with GPU Roofline](#)

## ze\_tracer and Intercept Layer for OpenCL™ Applications Timelines

If you do not want to use Intel® VTune™ Profiler to understand when data is being copied to the GPU, and when kernels run, both `ze_tracer` and the Intercept Layer for OpenCL™ Applications give you a way to observe this information (although, if you want a graphical timeline, you'll need to write a script to visualize the output). For more information, see [Trace the Offload Process](#).

## Performance Tuning Cycle

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The goal of the performance tuning cycle is to improve the time to solution whether that be interactive response time or elapsed time of a batch job. In the case of a heterogeneous platform, there are compute cycles available on the devices that execute independently from the host. Taking advantage of these resources offers a performance boost.

The performance tuning cycle includes the following steps detailed in the next sections:

1. Establish a baseline
2. Identify kernels to offload
3. Offload the kernels
4. Optimize
5. Repeat until objectives are met

## Establish Baseline

Establish a baseline that includes a metric such as elapsed time, time in a compute kernel, or floating-point operations per second that can be used to measure the performance improvement and that provides a means to verify the correctness of the results.

A simple method is to employ the chrono library routines in C++, placing timer calls before and after the workload executes.

## Identify Kernels to Offload

To best utilize the compute cycles available on the devices of a heterogeneous platform, it is important to identify the tasks that are compute intensive and that can benefit from parallel execution. Consider an application that executes solely on a CPU, but there may be some tasks suitable to execute on a GPU. This can be determined using the Offload Modeling perspective of the [Intel® Advisor](#).

Intel Advisor estimates performance characterizations of the workload as it may execute on an accelerator. It consumes the information from profiling the workload and provides performance estimates, speedup, bottleneck characterization, and offload data transfer estimates and recommendations.

Typically, kernels with high compute, a large dataset, and limited memory transfers are best suited for offload to a device.

See [Get Started: Identify High-impact Opportunities to Offload to GPU](#) for quick steps to ramp up with the Offload Modeling perspective. For more resources about modeling performance of your application on GPU platforms, see [Offload Modeling Resources for Intel® Advisor Users](#).

## Offload Kernels

After identifying kernels that are suitable for offload, employ DPC++ to offload the kernel onto the device. Consult the previous chapters as an information resource.

## Optimize

oneAPI enables functional code that can execute on multiple accelerators; however, the code may not be the most optimal across the accelerators. A three-step optimization strategy is recommended to meet performance needs:

1. Pursue general optimizations that apply across accelerators.
2. Optimize aggressively for the prioritized accelerators.
3. Optimize the host code in conjunction with step 1 and 2.

Optimization is a process of eliminating bottlenecks, i.e. the sections of code that are taking more execution time relative to other sections of the code. These sections could be executing on the devices or the host. During optimization, employ a profiling tool such as Intel® VTune™ Profiler to find these bottlenecks in the code.

This section discusses the first step of the strategy - Pursue general optimizations that apply across accelerators. Device specific optimizations and best practices for specific devices (step 2) and optimizations between the host and devices (step 3) are detailed in device-specific optimization guides, such as the [Intel oneAPI DPC++ FPGA Optimization Guide](#). This section assumes that the kernel to offload to the accelerator is already determined. It also assumes that work will be accomplished on one accelerator. This guide does not speak to division of work between host and accelerator or between host and potentially multiple and/or different accelerators.

General optimizations that apply across accelerators can be classified into four categories:

1. High-level optimizations
2. Loop-related optimizations
3. Memory-related optimizations
4. DPC++-specific optimizations

The following sections summarize these optimizations only; specific details on how to code most of these optimizations can be found online or in commonly available code optimization literature. More detail is provided for the DPC++ specific optimizations.

### High-level Optimization Tips

- Increase the amount of parallel work. More work than the number of processing elements is desired to help keep the processing elements more fully utilized.
- Minimize the code size of kernels. This helps keep the kernels in the instruction cache of the accelerator, if the accelerator contains one.
- Load balance kernels. Avoid significantly different execution times between kernels as the long-running kernels may become bottlenecks and affect the throughput of the other kernels.
- Avoid expensive functions. Avoid calling functions that have high execution times as they may become bottlenecks.

### Loop-related Optimizations

- Prefer well-structured, well-formed, and simple exit condition loops – these are loops that have a single exit and a single condition when comparing against an integer bound.
- Prefer loops with linear indexes and constant bounds – these are loops that employ an integer index into an array, for example, and have bounds that are known at compile-time.
- Declare variables in deepest scope possible. Doing so can help reduce memory or stack usage.
- Minimize or relax loop-carried data dependencies. Loop-carried dependencies can limit parallelization. Remove dependencies if possible. If not, pursue techniques to maximize the distance between the dependency and/or keep the dependency in local memory.
- Unroll loops with `pragma unroll`.

### Memory-related Optimizations

- When possible, favor greater computation over greater memory use. The latency and bandwidth of memory compared to computation can become a bottleneck.
- When possible, favor greater local and private memory use over global memory use.
- Avoid pointer aliasing.
- Coalesce memory accesses. Grouping memory accesses helps limit the number of individual memory requests and increases utilization of individual cache lines.
- When possible, store variables and arrays in private memory for high-execution areas of code.
- Beware of loop unrolling effects on concurrent memory accesses.
- Avoid a write to a global that another kernel reads. Use a pipe instead.
- Consider employing the `[[intel::kernel_args_restrict]]` attribute to a kernel. The attribute allows the compiler to ignore dependencies between accessor arguments in the DPC++ kernel. In turn, ignoring accessor argument dependencies allows the compiler to perform more aggressive optimizations and potentially improve the performance of the kernel.

### DPC++-specific Optimizations

- When possible, specify a work-group size. The attribute, `[[cl::reqd_work_group_size(X, Y, Z)]]`, where X, Y, and Z are integer dimension in the ND-range, can be employed to set the work-group size. The compiler can take advantage of this information to optimize more aggressively.
- Consider use of the `-Xsfp-relaxed` option when possible. This option relaxes the order of arithmetic floating-point operations.
- Consider use of the `-Xsfpc` option when possible. This option removes intermediary floating-point rounding operations and conversions whenever possible and carries additional bits to maintain precision.
- Consider use of the `-Xsno-accessor-aliasing` option. This option ignores dependencies between accessor arguments in a SYCL\* kernel.

## Recompile, Run, Profile, and Repeat

Once the code is optimized, it is important to measure the performance. The questions to be answered include:

- Did the metric improve?
- Is the performance goal met?
- Are there any more compute cycles left that can be used?

Confirm the results are correct. If you are comparing numerical results, the numbers may vary depending on how the compiler optimized the code or the modifications made to the code. Are any differences acceptable? If not, go back to optimization step.

## oneAPI Library Compatibility

oneAPI applications may include dynamic libraries at runtime that require compatibility across release versions of Intel tools. Intel oneAPI Toolkits and component products use [semantic versioning](#) to support compatibility.

The following policies apply to APIs and ABIs delivered with Intel oneAPI Toolkits.

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### NOTE

oneAPI applications are supported on 64-bit target devices.

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- New Intel oneAPI device drivers, oneAPI dynamic libraries, and oneAPI compilers will not break previously deployed applications built with oneAPI tools. Current APIs will not be removed or modified without notice and an iteration of the major version.
- Developers of oneAPI applications should ensure that the header files and libraries have the same release version. For example, an application should not use 2021.2 Intel® oneAPI Math Kernel Library header files with 2021.1 Intel oneAPI Math Kernel Library.
- New dynamic libraries provided with the Intel compilers will work with applications built by older versions of the compilers (this is commonly referred to as *backward compatibility*). However, the converse is not true: newer versions of the oneAPI dynamic libraries may contain routines that are not available in earlier versions of the library.
- Older dynamic libraries provided with the oneAPI Intel compilers will not work with newer versions of the oneAPI compilers.

Developers of oneAPI applications should ensure that thorough application testing is conducted to ensure that a oneAPI application is deployed with a compatible oneAPI library.

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# Glossary

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## Accelerator

Specialized component containing compute resources that can quickly execute a subset of operations. Examples include CPU, FPGA, GPU.

See also: Device

## Accessor

Communicates the desired location (host, device) and mode (read, write) of access.

## Application Scope

Code that executes on the host.

## Buffers

Memory object that communicates the type and number of items of that type to be communicated to the device for computation.

## Command Group Scope

Code that acts as the interface between the host and device.

## Command Queue

Issues command groups concurrently.

## Compute Unit

A grouping of processing elements into a 'core' that contains shared elements for use between the processing elements and with faster access than memory residing on other compute units on the device.

## Device

An accelerator or specialized component containing compute resources that can quickly execute a subset of operations. A CPU can be employed as a device, but when it is, it is being employed as an accelerator. Examples include CPU, FPGA, GPU.

See also: Accelerator

## Device Code

Code that executes on the device rather than the host. Device code is specified via lambda expression, functor, or kernel class.

## Fat Binary

Application binary that contains device code for multiple devices. The binary includes both the generic code (SPIR-V representation) and target specific executable code.

## Fat Library

Archive or library of object code that contains object code for multiple devices. The fat library includes both the generic object (SPIR-V representation) and target specific object code.



**Fat Object**

File that contains object code for multiple devices. The fat object includes both the generic object (SPIR-V representation) and target specific object code.

**Host**

A CPU-based system (computer) that executes the primary portion of a program, specifically the application scope and command group scope.

**Host Code**

Code that is compiled by the host compiler and executes on the host rather than the device.

**Images**

Formatted opaque memory object that is accessed via built-in function. Typically pertains to pictures comprised of pixels stored in format like RGB.

**Kernel Scope**

Code that executes on the device.

**ND-range**

Short for N-Dimensional Range, a group of kernel instances, or work item, across one, two, or three dimensions.

**Processing Element**

Individual engine for computation that makes up a compute unit.

**Single Source**

Code in the same file that can execute on a host and accelerator(s).

**SPIR-V**

Binary intermediate language for representing graphical-shader stages and compute kernels.

**Sub-groups**

Sub-groups are an Intel extension.

**Work-groups**

Collection of work-items that execute on a compute unit.

**Work-item**

Basic unit of computation in the oneAPI programming model. It is associated with a kernel which executes on the processing element.